



### VRPN: A Device-Independent, Network-Transparent VR Peripheral System

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## Brought to You By



- The U.S. National Institutes of Health
  - -National Center for Research Resources
    - » UNC Resource on Computer Graphics for Molecular Studies and Microscopy
- Commercial support provided by 3rdTech
  - -Walt Disney VR Studios
  - -Schumberger Cambridge Research
  - -Paid-for improvements are in the public domain

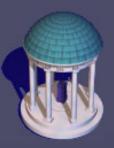


# "The great thing about standards...



... is that there are so many to choose from"

- Commercial:
  - vrco's CAVELib, Division's dVS, Sense8's WorldToolKit, Disney's Panda3D, ...
- Research:
  - MR toolkit, GIVEN++, DIVE, BrickNet, Alice/DIVER, AVIARY, Maverik/DEVA, VR Juggler, Bamboo, Dragon, DIVERSE, Vlib, ...
- Why on Earth publish another one?!?

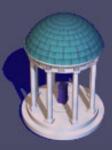


### VRPN is *not* a complete VR API



"You can only standardize what nobody cares about"

- Does not provide user interaction techniques
- Does not provide a scene graph (or transform tree)
- Does not provide graphics techniques
- Does:
  - handle the device control layer
  - provide communication between hosts
  - hook to higher levels of a VR system

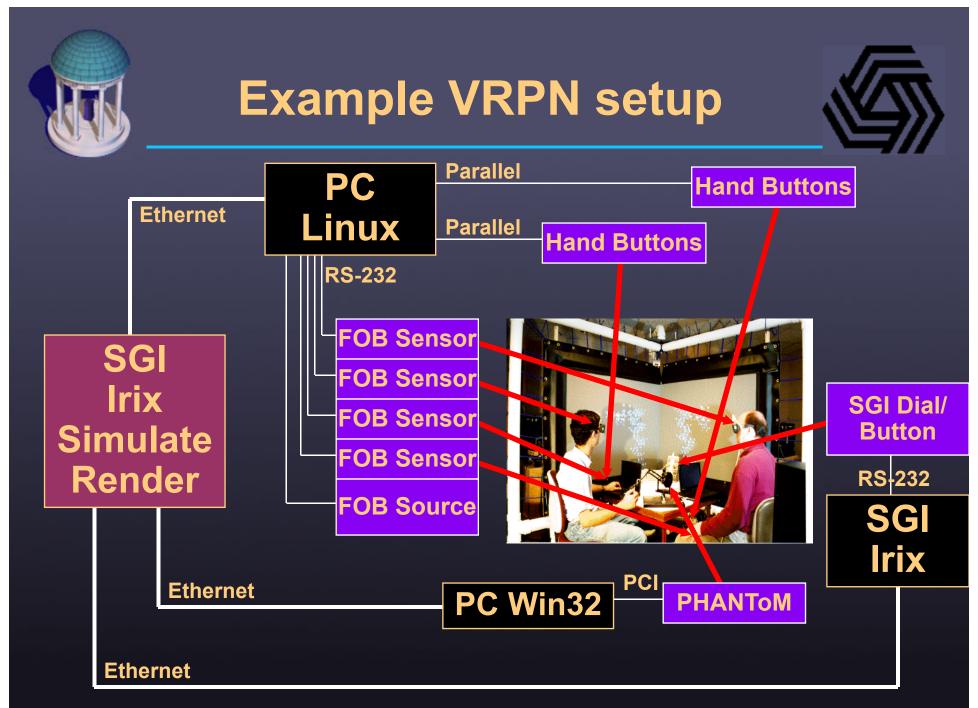


## **VRPN System Vision**



"A chicken for every pot and a PC for every VR device"

- Provide Easy Access
  - » Common Interface to different devices
  - » Access to VR peripherals from any graphics engine
  - » Multiple simultaneous connections to a server
  - » Storage and replay of interactive sessions
- Increase Robustness
  - » Keep the (sometimes fragile) trackers working
  - » Client application survives failure/restart of device server
- Be Efficient
  - » Timing: Low latency plus time stamps on common clock
  - » Communications Efficiency





### Demonstration



- Didn't bring the PIT with me
- Did bring a stored file of tracker values



### **VRPN** Guideline



### "Make difficult things easier..."

- -Writing client applications for arbitrary devices
- -Running servers for multiple devices
- "...without making easy things more difficult..."
  - -Warning/error messages from device driver
  - -Writing a driver for a new device
- "...or making desirable things impossible"
  - -Special commands for specific device drivers



### "Making difficult things easier..."



• Opening a (possibly networked) connection to an arbitrary type of tracking device and getting locally-time-stamped reports from it, restoring the connection if the server is shut down and restarted

#include "vrpn\_Tracker.h"

```
void handle_pos(void *, const vrpn_TRACKERCB t) {
    printf("Position of sensor %d is %f, %f, %f\n",
        t.sensor, t.pos[0], t.pos[1], t.pos[2]);
```

```
main() {
```

```
vrpn_Tracker_Remote *tkr = new vrpn_Tracker_Remote("Tracker0@myhost");
tkr->register_change_handler(NULL, handle_pos);
while (1) { tkr->mainloop(); }
```



### "Making difficult things easier..."



• Starting multiple tracker, button, and analog servers sharing a common network link to each of multiple applications, logging their sessions on a per-connection basis as requested by the clients

### cat > vrpn.cfg

vrpn_Tracker_Flock	Tracker0		4	/dev/ttyC1			115200
vrpn_Tracker_Fastrak Fastrak0				/dev/ttyC2			19200
vrpn_Tracker_Fastrak Isense900				/dev/ttyC3			115200 /
Wand	Wand0	0	-1.0 0.0	0.0 1.0	-1.0	0.0	0.0 1.0 /
Stylus	Stylus0	2					
vrpn_Magellan	Magella	n0		/dev/ttyC4			9600

```
^Z
```

vrpn\_server -f vrpn.cfg

# "....without making easy things more difficult..."

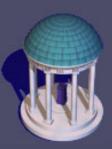


- Dealing with remote devices
  - -This was not included at first, and it really hurt
  - -Determining if device open was successful
  - -Error and warning messages from device
- Local client and server
- Writing a driver for a new device
  - -vrpn\_BaseClass
  - -Root classes for functions, and subclasses
    - » Serial tracker class
    - » Analog server class

# "...or making desirable things impossible"



- A very real danger in implementing libraries
  - -One ditch: Don't want the "lowest common denominator" device
  - The other ditch: Don't want a combinatorial explosion of special-case code to deal with different devices
  - Ditch avoidance described next...



## **Key Idea: Device Factoring**



"Don't think of writing drivers for a set of devices – think of designing interfaces for a set of functions

- Each device is factored into one or more interfaces
  - Client connects to the different interfaces separately
  - VRPN maps multiple data streams through the same connection when appropriate, based on run-time bindings
- Factoring and extensibility are supported by:
  - Devices silently ignoring unrecognized message types
  - Layered devices
  - Multiple-behavior devices
  - Application-level access to all messages

## Factoring: Common Types



- "Input" devices
  - -Tracker: 1 or more sensors, pos/quat for each
  - -Button: 1 or more buttons, press/release for each
  - -Analog: 1 or more floating-point values
  - -Dial: 1 or more floating-point incremental angles
- "Output" devices
  - -Sound: Audio clips with volume, location, etc
  - -ForceDevice: Surfaces and forces in 3D

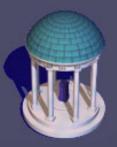
## **Factoring Complex Devices**



- SGI Dial/Button Box is 32-in Button, 8-in Analog
- Phantom consists of a single-sensor Tracker, a single Button, and a ForceDevice
- Intersense consists of multiplesensor Trackers, each wand is also a 2-in Analog and 5-in Button, each stylus is also a 5-in Button
- UNC Joystick consists of 7-in Analog and 2-in Button



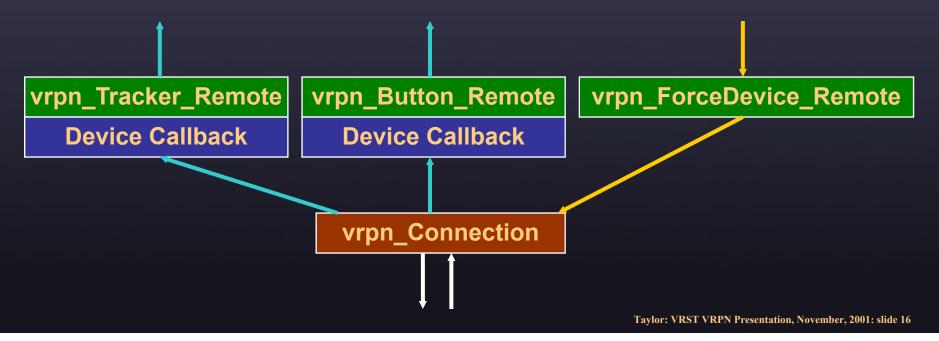


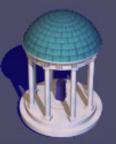


### **Client-side VRPN**



- App connects to *Remote* objects for each device
- VRPN consolidates devices on connections
- Raw message callbacks marshaled by "input" objects into proper callback types for each device
- Methods on "output" devices pack messages to server object



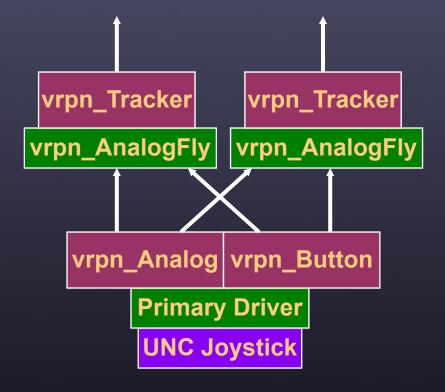


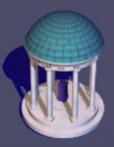
### User's view of VRPN: Phantom Example

```
#include "vrpn Tracker.h"
#include "vrpn_Button.h"
#include "vrpn_ForceDevice.h"
... callback functions here
main() {
  vrpn Tracker Remote *tkr =
       new vrpn_Tracker_Remote("Phantom@myhost");
  vrpn_Button_Remote *btn =
       new vrpn_Button_Remote("Phantom@myhost");
  vrpn ForceDevice Remote *frc =
       new vrpn ForceDevice Remote("Phantom@myhost");
  ... register callback handlers here
  while (1)
     {tkr->mainloop(); btn->mainloop(); frc->mainloop();}
```

### Exporting Multiple Interfaces: The UNC Joystick Box

- Layered Device
  - -Exports Analog/Button and Tracker
- Multiple-behavior Device
  - Exports two Trackers with different behaviors
- Client connects to one or more devices of interest
- Links can be within the same server process, or network links from client to server





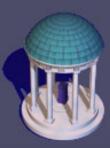
### **Other VRPN Features**



- Reliable vs. low-latency class of service
- Synchronized clocks between endpoints
- Logging of sessions (client and/or server)
- Multiple connections to a server
- Client and server reconnect
- Connection accept/close messages

-Local messages from the vrpn\_Connection

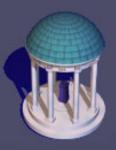
• Can run client and server on different machines, as different processes on the same machine, or within the same process



### Separate Client and Server When...



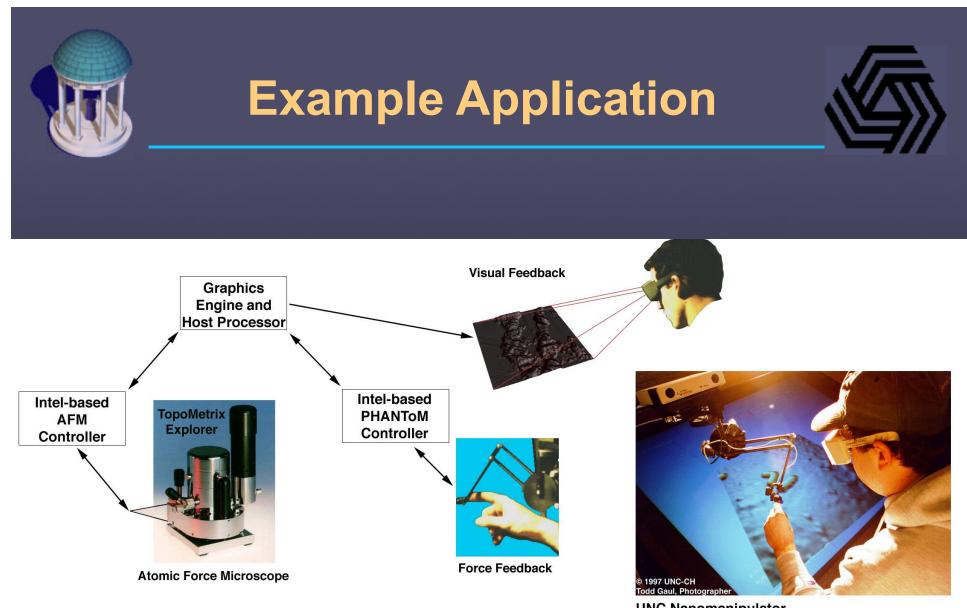
- Server initialization takes a long time
- Knowing the time of an event is critical
- Server requires frequent access to its device



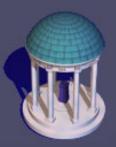
### Performance



- Overhead due to network
  - 0.5ms network, 1.7-3.3ms app-to-app 1-way average
- Reductions compared to "out-of-the-box" drivers
  - Serial port accelerations (buffer, jiffies, Cyclades) together reduce average latency by about 11ms
  - Optimized, time-aware drivers (first-character timestamp, no pessimistic polling)
  - Much faster initialization when connecting to a remote server
- Can get a net gain (*reduction* in latency) using VRPN
  - even over a network connection
- Can get more accurate timestamps



**UNC Nanomanipulator** 



### Where do I Learn More?



- Web page at www.cs.unc.edu/research/vrpn
- Can download source code
  - Clients run on PC/Win32, SGI/Irix, PC/Linux, Sparc/Solaris, HP700/Hpux, and PowerPC/AIX
  - *Trackers:* Ascension Flock of birds (single or multiple serial lines), Polhemus Fastrak, Intersense IS-600 and IS-900 (including wands and styli), Origin Systems DynaSight, Phantom<sup>™</sup>, 3rdTech HiBall 3000, Logitech Magellan, and Radamec SPI (video/movie camera tracker).
  - Other devices: Logitech Magellan (analog values and buttons), B&G systems CerealBox (buttons, dials, sliders), NRL ImmersionBox serial driver (buttons), Wanda (analog, buttons), National Instruments A/D cards, Win32 sound server based on the Miles SDK, SGI button and dial boxes, the "Totally Neat Gadget" (TNG3) from Mindtel, and the UNC hand-held Python controller (buttons).
- VRPN is in the public domain use it however you like