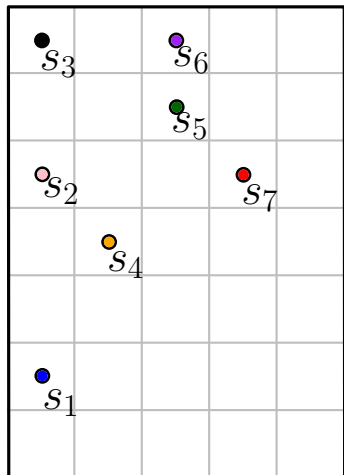


Computing the Nearest Neighbor Transform Exactly with only Double Precision

DAVID L. MILLMAN Steven Love
Timothy M. Chan Jack Snoeyink

28 June 2012

The Problem



Given n sites on a pixel grid,
what is the closest site to each pixel?

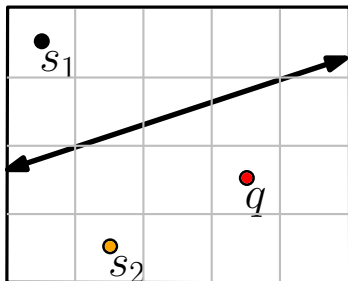
How much precision is need to
determine this?

Techniques for implementing geometric algorithms with finite precision computer arithmetic:

- Rely on machine precision (+epsilon)
- Topological Consistency [S99, S01, SI90, SI92, SII*00]
- Exact Geometric Computation [Y97]
 - Software based arithmetic [CORE, LEDA, MPFR]
 - Predicate eval. schemes [C92, FW93, ABO*97, S97,GRR00]
 - Degree-driven algorithm design [LPT99]

Analyzing Precision[LPT99]

Is q closer to s_1 ?



$$\mathbb{U} = \{1, 2, \dots, U\}$$

$$s_1, s_2, q \in \mathbb{U}^2$$

$$s_1 = (x_1, y_1)$$

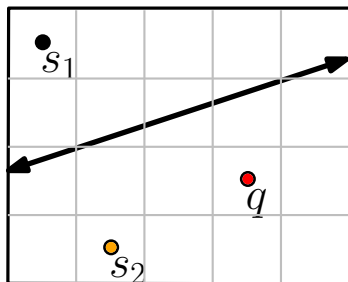
$$s_2 = (x_2, y_2)$$

$$q = (x_q, y_q)$$

$$\|q - s_1\|^2 \geq \|q - s_2\|^2$$

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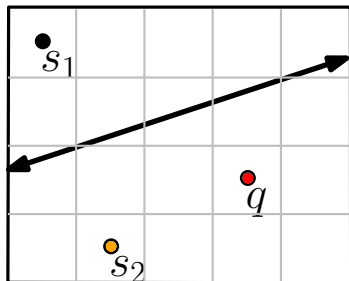
$$q = (x_q, y_q)$$

$$\|q - s_1\|^2 \geq \|q - s_2\|^2$$

$$f(s_1, s_2, q) = \text{sign}((x_q - x_1)^2 + (y_q - y_1)^2 - (x_q - x_2)^2 - (y_q - y_2)^2)$$

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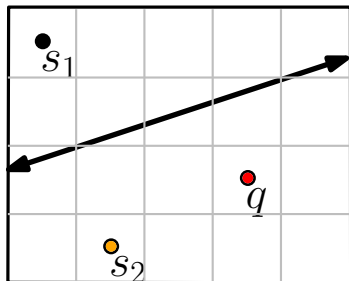
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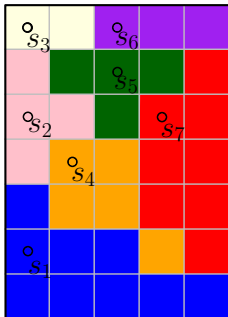
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Nearest Neighbor Transform



Given

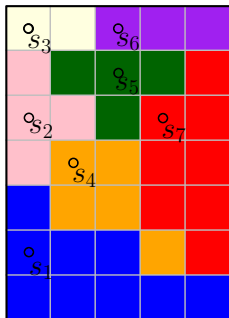
A grid of size U and

Sites $S = \{s_1, \dots, s_n\} \subset \mathbb{U}^2$

Label

Each grid point of \mathbb{U}^2 with the closest site of S

Nearest Neighbor Transform



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	Alg	Time
Brute Force	deg 2	$O(nU^2)$
Nearest Neighbor Trans. [B90]	deg 5	$O(U^2)$
Discrete Voronoi diagram [C06, MQR03]	deg 3	$O(U^2)$
GPU Hardware [H99]	-	$\Theta(nU^2)$

Problem (NNTrans-min)

*For each pixel $q \in U^2$, find the site $s_i \in S$ such that,
for all $j < i$, the distance $\|q - s_i\| < \|q - s_j\|$, and
for all $j > i$, the distance $\|q - s_i\| \leq \|q - s_j\|$.*

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$$\begin{aligned}\|q - s_i\|^2 &< \|q - s_j\|^2 \\ q \cdot q - 2q \cdot s_i + s_i \cdot s_i &< q \cdot q - 2q \cdot s_j + s_j \cdot s_j \\ 2x_i x_q + 2y_i y_q - x_i^2 - y_i^2 &> 2x_j x_q + 2y_j y_q - x_j^2 - y_j^2.\end{aligned}$$

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For each pixel q , find the site with lowest index $s_i \in S$ that achieves the maximum of $2x_i x_q + 2y_i y_q - x_i^2 - y_i^2$.

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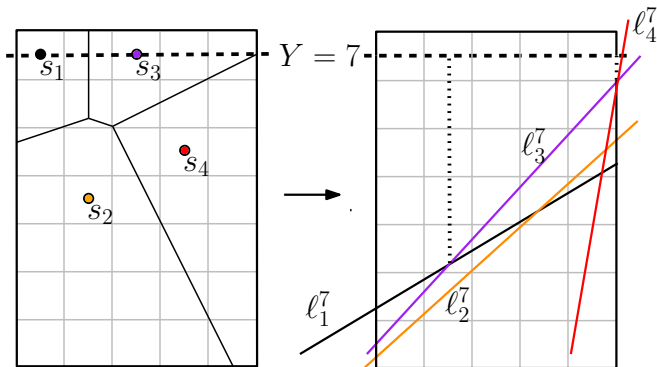
Problem (DUE-Y)

For a fixed $1 \leq Y \leq U$, and for each $1 \leq X \leq U$, find the smallest index of a line of L_Y with maximum y coordinate at $x = X$.

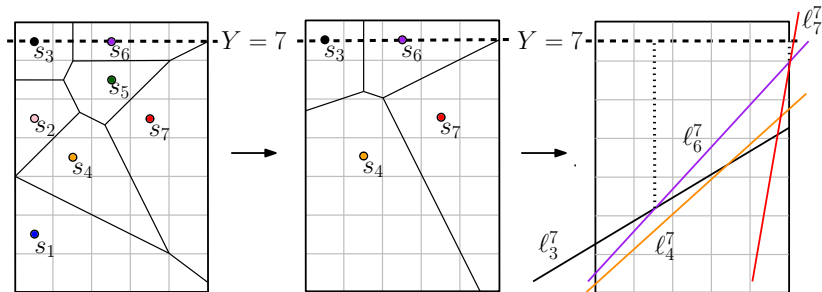
Problem Transformations–Part 2

Problem (DUE-Y)

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Sketch of NNTransform Algorithm



Three Algorithms for Computing the DUE

Discrete Upper Envelope Lemma

Given a set of n lines L of each of the form $y = \textcircled{1}x + \textcircled{2}$ we can compute the DUE of L in:

- $O(n + U)$ and degree 3, (DUE-DEG3)
- $O(n + U \log U)$ and degree 2, (DUE-ULgU)
- $O(n + U)$ expected time and degree 2. (DUE-U)

For each item:

- 1 Reduce L to at most U lines.
- 2 Compute DUE of at most U lines.

Three Algorithms for Computing the DUE

Discrete Upper Envelope Lemma

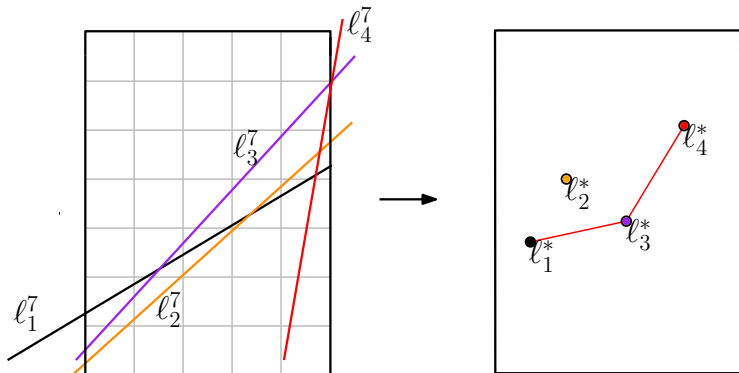
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Discrete Upper Envelope Lemma (DUE-DEG3)

Two steps:

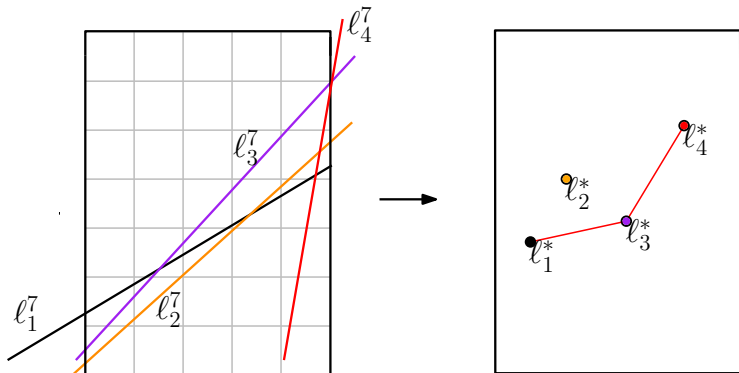
- 1 Compute upper env. via the lower hull of dual points
line $y = mx + b$ maps to dual point $(m, -b)$.
- 2 Discretize upper env to DUE.



Discrete Upper Envelope Lemma (DUE-DEG3)

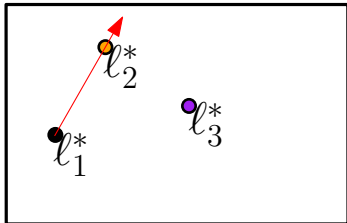
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line form is $y = \textcircled{1}x + \textcircled{2} \implies$ dual point form is $(\textcircled{1}, \textcircled{2})$

Orientation test



l_1^* , l_2^* and l_3^* have form (①, ②)

$$\text{orient}(l_1^*, l_2^*, l_3^*) = \text{sign} \left(\begin{vmatrix} \textcircled{0} & \textcircled{1} & \textcircled{2} \\ \textcircled{0} & \textcircled{1} & \textcircled{2} \\ \textcircled{0} & \textcircled{1} & \textcircled{2} \end{vmatrix} \right) = \text{sign}(\textcircled{3})$$

Three Algorithms for Computing the DUE

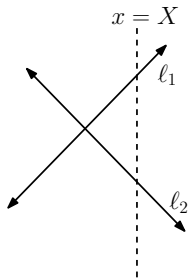
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Main predicate OrderOnALine

Order on a Line



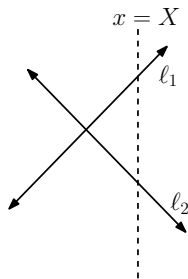
$$X = \textcircled{1}$$

$$l_1, l_2 \text{ have form } y = \textcircled{1}x + \textcircled{2}$$

$$\text{orderOnLine}(l_1, l_2, X) = \text{sign}(\textcircled{1}X + \textcircled{2} - \textcircled{1}X + \textcircled{2}) = \text{sign}(\textcircled{2})$$

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Lemma IntersectCol

Given two lines l_1 and l_2 of the form $y = \textcircled{1}x + \textcircled{2}$, the construction $\text{IntersectCol}(l_1, l_2)$ returns the column containing the intersection of the two lines in $O(\log U)$ time and degree 2.

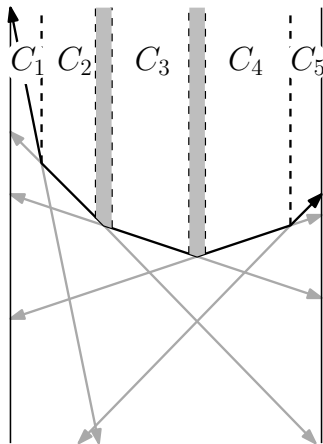
Three Algorithms for Computing the DUE

Discrete Upper Envelope Lemma

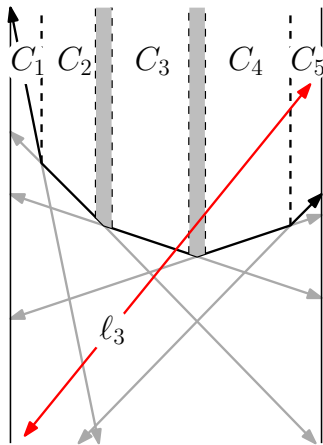
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Discrete Upper Envelope Lemma (DUE-ULgU)



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Three Algorithms for Computing the DUE

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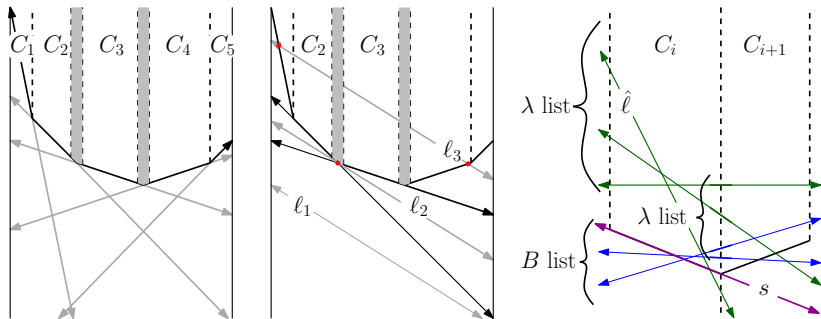
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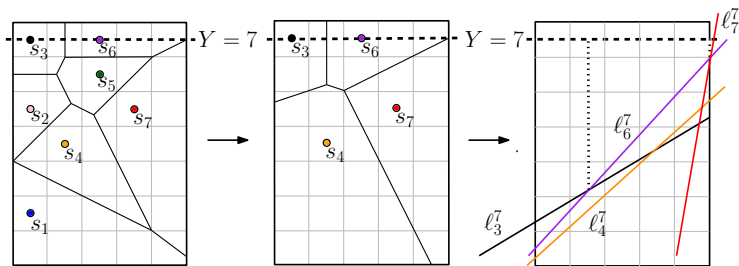
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Three Algorithms for Computing the NNTransform

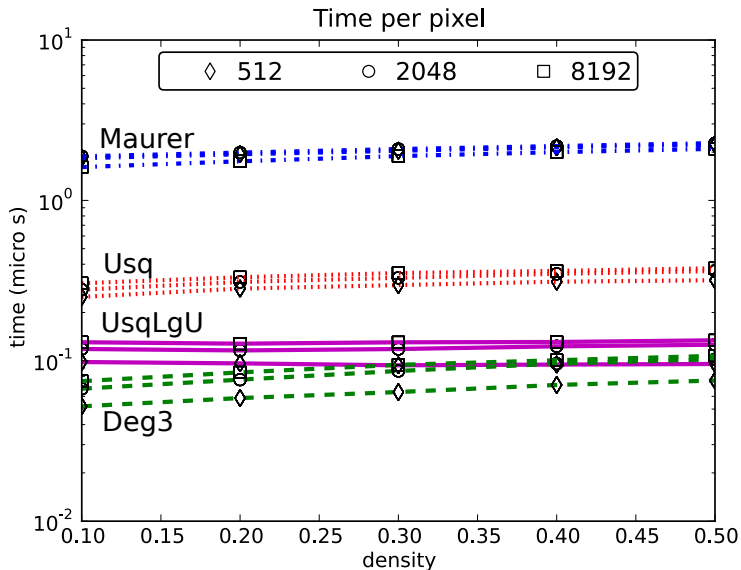
NNTransform Theorem

Given a set of n sites with degree 1 coordinates on a $U \times U$ grid, we can compute the nearest neighbor transform in:

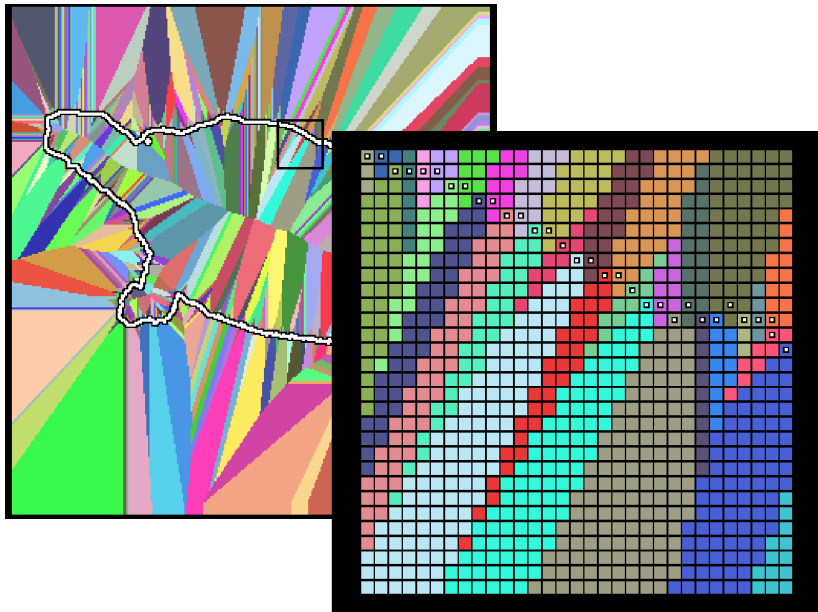
- $O(U^2)$ and degree 3, (Deg3)
- $O(U^2 \log U)$ and degree 2, (UsqLgU)
- $O(U^2)$ expected time and degree 2. (Usq)



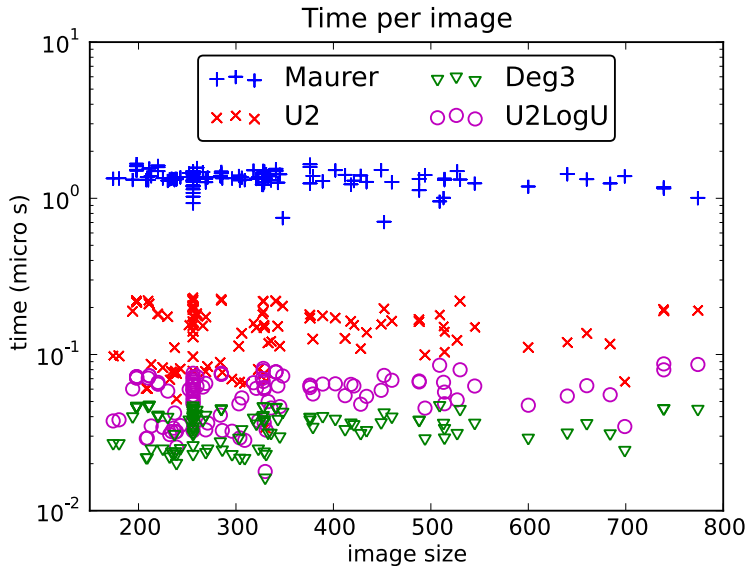
Experiments Part 1



Experiments Part 2



Experiments Part 2



Described and implemented three algorithms for computing the DUE of lines of the form $y = \textcircled{1}x + \textcircled{2}$:

- DUE-DEG3: $O(n + U)$ and degree 3
- DUE-ULgU: $O(n + U \log U)$ and degree 2
- DUE-U: $O(n + U)$ expected time and degree 2

Which gave us three algorithms for computing the NNTransform:

- Deg3: $O(U^2)$ and degree 3
- UsqLgU: $O(U^2 \log U)$ and degree 2
- Usq: $O(U^2)$ expected time and degree 2.

Can we compute the NNTransform with degree 2 without randomization?

What about L_1 or L_∞ ?

What other geometric problems can be considered using degree-driven algorithm design?

Summary

Described and implemented three algorithms for computing the DUE of lines of the form $y = \textcircled{1}x + \text{deg}(2)$:

- DUE-DEG3: $O(n + U)$ and degree 3
- DUE-ULgU: $O(n + U \log U)$ and degree 2
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Contact

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