

Course goals

- exposure to another language
 - C++
 - Object-oriented principles
- knowledge of specific data structures
 - lists, stacks & queues, priority queues, dynamic dictionaries, graphs
- impact of DS design & implementation on program performance
 - asymptotic complexity of algorithms

Course outline

Features of C++, object-oriented programming principles, and features of the Unix programming environment will be introduced concurrently with the study of these topics, as appropriate

Review of C++

Introduction to Unix

Review of program performance

- time and space complexity
- asymptotic notation
- *searching* (linear vs binary) & *sorting* (insertion sort vs mergesort)

Data representation and lists

Stacks and Queues

Hash tables

Binary trees

- representation
- traversal

Priority queues

- Linear lists
- Heaps

Search trees

- Binary search trees
- balanced binary search trees - AVL trees

Graphs

- representation
- traversal

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- objects
- classes -- .h and .cpp files
- templates
- access control
 - public/ private/ protected methods
 - friend classes
- inheritance
 - public/ private/ protected inheritance
 - multiple inheritance
- the strings package

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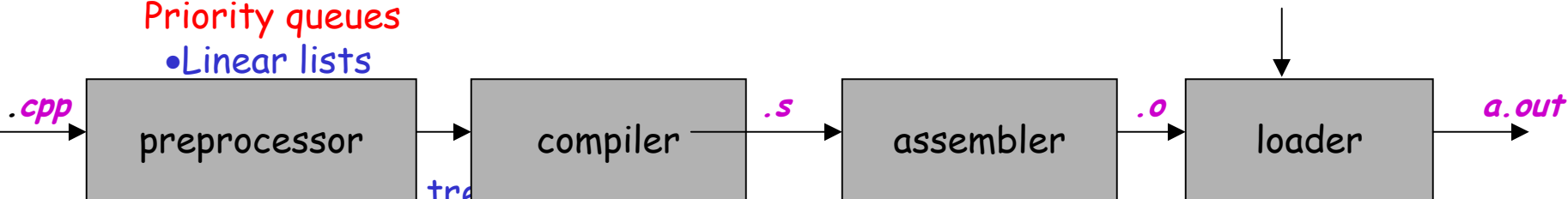
Binary trees

- representation
- traversal

Priority queues

- Linear lists

- man pages
- the g++ compiler
 - stages in compilation
- makefiles
- environment variables
- the gdb debugger
- emacs? pico



- balanced binary search trees - AVL trees

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- bigOh/ bigTheta notation
- asymptotic worst-case complexity of algorithms
- common complexities:
 - log n
 - n
 - n log n
 - n^2 , n^3 , ...
- determining complexities of algorithms
- example complexities -- sort/ search

Example: merge sort

```
mergeSort(A, i, j) // sort A[i,...j]
{
    if (i==j) return A[];
    mergeSort(A, i, (i+j)/2);
    mergeSort(A, (i+j)/2 + 1, j);
    merge(A, i, (i+j)/2, j)
}
```

```
merge(A, i, k, j)
//PreCond: A[i,...,k] and A[k,...,j] are sorted
//PostCond: A[i,...,j] is sorted
```

Recurrence : $T(n) \leq 2 \cdot T(n/2) + c_1 \cdot n + c_2$
 $T(1) = c_3$

$T(n) = O(n \log n)$

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- data representation:

- array-based

- linked/ pointer-based

- simulated pointer (cursors)

- lists

- ADT specification

- representation using arrays

- representation using linked lists

- compare and contrast

```
class list{
public:
    list();
    ~list();
    bool isEmpty();
    bool isFull();
    int length();
    bool Find(x,k);
    int Search(x);
    void delete(k,x);
    void insert(k,x);
private:
};
```

```
adt linearList{
    create()
    destroy()
    isEmpty()
    isFull()
    length()
    Find(x,k)
    Search(x)
    delete(k,x)
    insert(k,x)
}
```

NVL

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• ADT specification

- stack - LIFO
- queue - FIFO
- (dequeue)

• implementation

- representation using arrays
 - "circular" for queues
- representation using linked lists
- $\Theta(1)$ time operations
- min and nextMin operations

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- representation
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• a recursive definition

- root
- left [sub]tree
- right [sub]tree

• implementation

- representation using arrays
 - inefficient, except for complete trees
- representation using linked structures
- $O(h)$ time operations (h: height of the tree)

• tree traversals -- recursively defined

- preorder/ inorder/ postorder
- each takes $O(n)$ time (n: # elements)

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• ADT specification

- create/ destroy/ isEmpty
- insert
- min
- deleteMin

• implementation

- linear list -- one of the operations is $O(n)$
- binary tree -- a complete tree
 - represented using array
 - $O(\log n)$ operations
 - fast implementations (bit-manipulation)

• other operations --

- max
- decrease/ increase
- delete

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- representation
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• dynamic dictionaries -- ADT

- create/ destroy
- insert
- delete
- find

• implementation using binary trees

- bst's -- operations are $O(h)$
 - inorder traversal sorts the elements
- balanced bst's -- the AVL tree
 - height is always $O(\log n)$
 - insert/ delete may involve rotations
 - RR/ LL/ RL/ LR

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• implementation: representation using arrays as tables

- a hash function maps keys to buckets
- collisions may result in overflow
- handling overflows:
 - open addressing
 - linear probing
 - quadratic probing
 - chaining
- performance: worst-case $O(n)$, average-case $O(1)$

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- definition: $G=(V,E)$, $|V| = n$; $|E|=m$;
 - lots of terminology
- representation
 - adjacency matrices
 - adjacency lists
 - compare and contrast
- example operations
 - traversals
 - depth first (DFS)
 - breadth-first (BFS)
 - topological sort of DAG's
 - cycle detection
 - directed and undirected graphs
 - shortest paths
 - the Warshall-Floyd algorithm