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## **Error Detection**

What Causes Errors?

- Bit errors occur due to electrical interference or thermal noise
  - » Detect whether errors have occurred in the data frames received
    - Notify sender (for retransmission)
    - $\boldsymbol{\textbf{\diamond}}$  Or correct errors (based on error-correcting codes)
    - Or simply drop packet (to avoid wasting processing resources)
- Basic idea of error detection:
  - » Use k redundant bits to enable receiver to detect errors in a packet of size n
- ♦ Goals:
  - » Strong error detection properties (detect different types of errors)
  - » **Small overhead** (*k* vs. *n*)
  - » Efficient to implement

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# Naïve Approach Packet Duplication Just append a duplicate copy of the frame 0 1 0 1 0 0 1 1 0 1 0 1 0 0 1 1 Error detection: Errors that corrupt same positions in both frames will go undetected Overhead: 100 % overhead (k = n) Efficiency?

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# **One-dimensional Parity**

## **Smarter Scheme**

 Insert an extra bit to every set of 7 bits to balance the number of "1"s

0 1 0 1 0 0 1 | 1

### ◆ Error detection:

- » Catches all 1-bit errors
- » Can it detect 2-bit errors?

#### • Overhead:

» 14 % (k = 1, n = 7)

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# **Two-dimensional Parity**

**Improving Efficiency** 

- Compute parity also for each bit position across each of the bytes in a frame:
   0 1 0 1 0 0 1 | 1
- » Add parity bit for the parity byte also 1 1 0 1 0 0 1 0 1011110 1 0 0 0 1 1 1 0 1 0110100 1 • Error detection: 1011111 0 » Catches all 1/2-bit errors 0 1 0 1 1 0 0 1 » Can it detect 3-bit errors? 1010111 | 1
- » Can it detect 4-bit errors?
- » Can 2-D parity be used to correct all 1-bit errors?
- » Can it be used to correct 2-bit errors?

#### • Overhead:

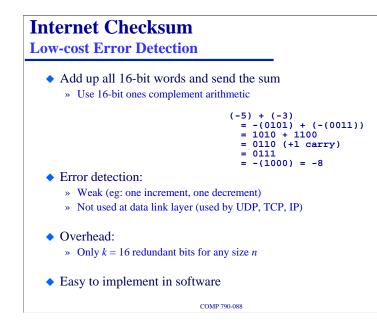
» 30 % (*k* = 15, *n* = 49)

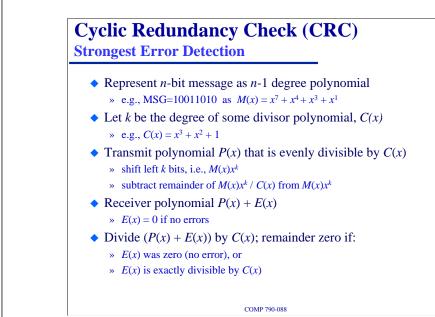
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## Cyclic Redundancy Check (CRC) Selecting C(x)

- Can catch:
  - » All single-bit errors, as long as the  $x^k$  and  $x^0$  terms have non-zero coefficients.
  - » All double-bit errors, as long as C(x) contains a factor with at least 3 terms
  - » Any odd number of errors, as long as C(x) contains the factor (x + 1)
  - » Any 'burst' error (i.e., sequence of consecutive error bits) for which the length of the burst is less than *k* bits.
  - » Most burst errors of larger than k bits can also be detected

#### • CRC algorithm is easily implemented in hardware

- » CRC-32 commonly used by link layer protocols (k = 32)
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## **Error Detection**

## Summary

- ♦ Goals:
  - » Strong error detection properties (detect different types of errors)
  - » Small overhead (k vs. n)
  - » Efficient to implement
- ◆ Ideas used:

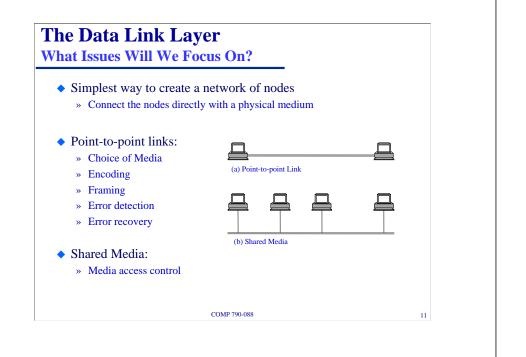
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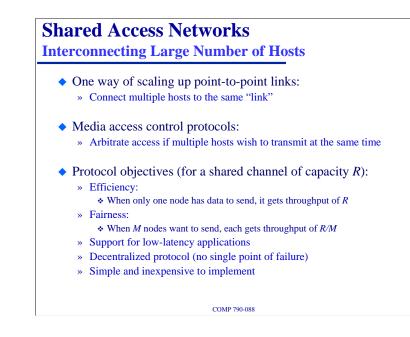
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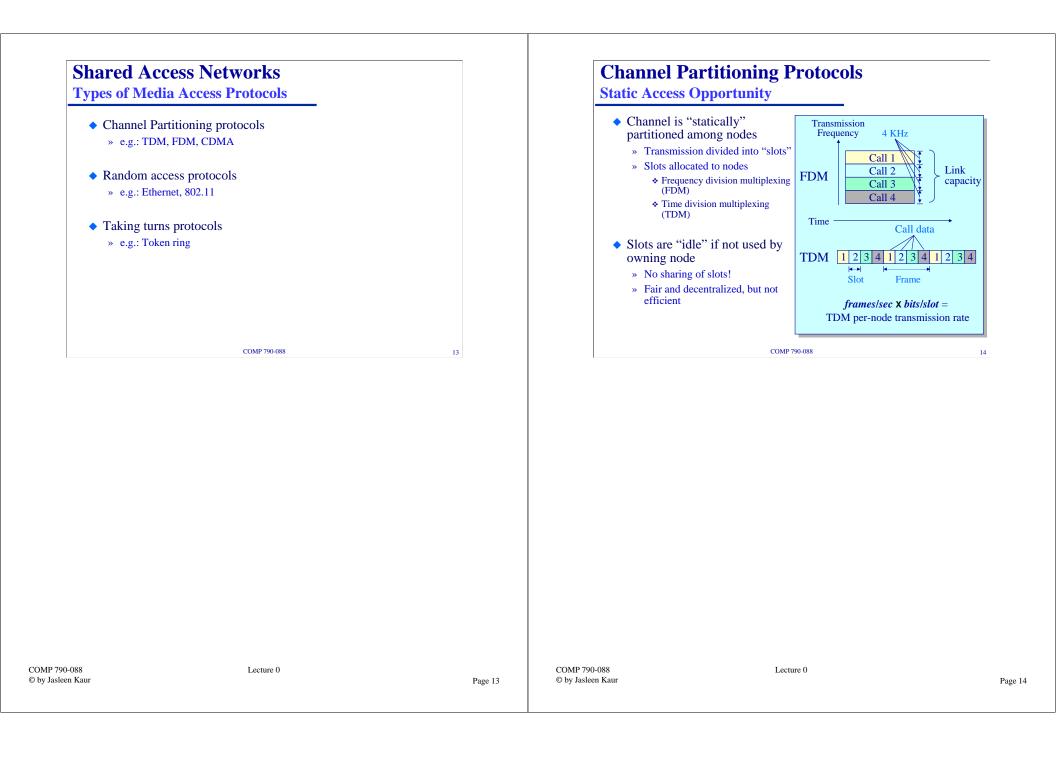




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## **Random Access Protocols**

**Non-static Channel Assignment** 

- No fixed pre-determined schedule of transmission
  - » Transmit, if data available
  - » Detect if "collision" occurs
- Typically, CSMA/CD
  - » Carrier Sense (CS): listen before transmitting
  - » Collision Detection (CD): listen while transmitting and stop on detecting collision
  - » Multiple Access (MA): Multiple nodes plugged into common "bus" medium

### • Example protocols:

- » Slotted Aloha
- » Ethernet (multiple-access bus version)
- » 802.11 (wireless)

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#### **Ethernet : Media Access Protocol Shared Bus Version** Α В ◆ If line is idle A в » Send immediately (efficiency) » Upper bound message size: 1500 B (latency) Α В ♦ If line is busy + » Wait until idle and transmit immediately (efficiency) » Is this really efficient when multiple nodes waiting? \* Aloha: wait until idle and transmit with probability p• How to guarantee that collision is detected (before frame is completely transmitted)?

- » Impose max propagation delay (51.2  $\mu$ s), minimum frame size (64 B)
- » If collision, then what?

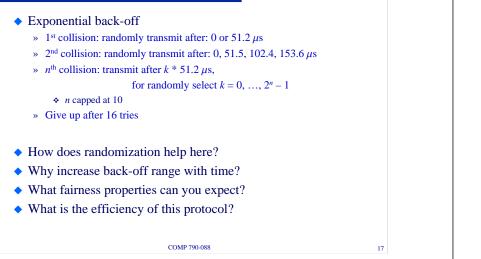
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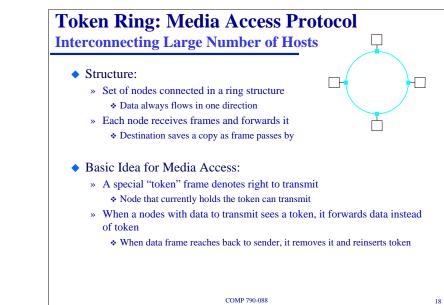
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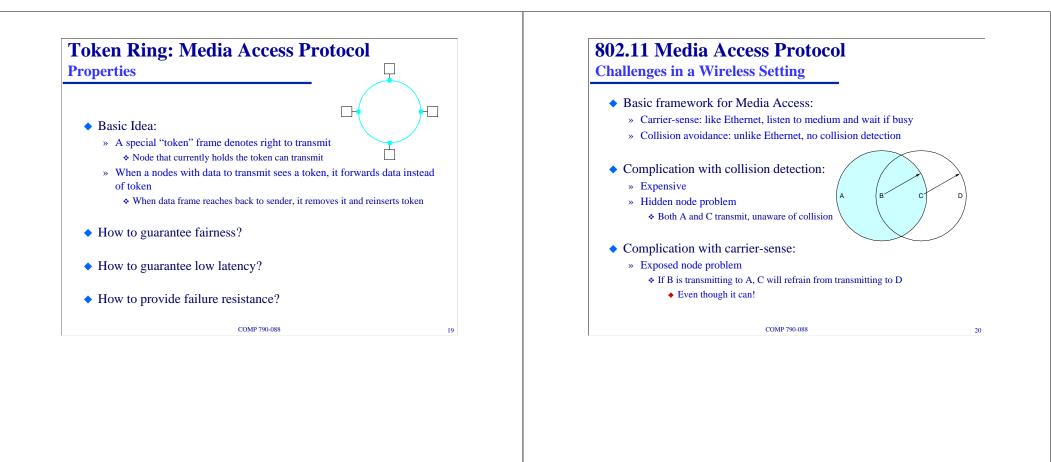
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## 802.11 Media Access Protocol MACAW

#### MACAW Protocol:

- » Multiple Access With Collision Avoidance for Wireless LANs
- » Basic philosophy: don't do collision detection, but *collision avoidance*
- Sender, receiver exchange control frames before a data frame
  - » Sender sends RTS (Request to Send), with length of data frame
  - » Receiver replies CTS (Clear to Send), with echo of frame length
  - » If sender gets CTS frame, it sends data frame
  - If not, does exponential back-off before trying again
  - » Receiver sends ACK after receiving data frame
- What should other nodes do?
  - » If they see a CTS frame?
  - » If they see RTS, but not CTS?
- A B C
- Properties: Fairness? Efficiency? Latency?
   » Zig-zag decoding: using collisions

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# Media Access Control

## Summary

- Protocol objectives (for a shared channel of capacity *R*):
  - » Efficiency: when only one node has data to send, it gets throughput of R
  - » Fairness: when M nodes want to send, each gets throughput of R/M
  - » Support for low latency applications
  - » Decentralized protocol (no single point of failure)
  - » Simple and inexpensive to implement

#### • Ideas used:

- Virtualization: helps guarantee fairness
   Partitioning (TDM/FDM), round-robin access opportunity (Token Ring)
- Fine-grained multiplexing: helps achieve low latency
   Fixed slot size (TDM/FDM), Limited frame size (Ethernet, 802.11, Token Ring)
- Randomization: helps achieve fairness in many cases
   Exponential back-off on collision (Ethernet, 802.11)
- Signaling: helps achieve efficiency in multi-node settings
   Channel-grabbing protocol (MACAW)

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