

Analysis of Simulation Results

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Simulations: Outline

- ◆ Simulation Basics
 - Terminology
 - Types of simulations
 - Implementing a simulator
- ◆ Analysis of Simulation Results
 - Model Verification
 - Model Validation
 - Transient Analysis
 - Terminating Simulations
 - Stopping Criteria
- ◆ Random Number Generation

Analysis of Simulation Results

- ◆ Issues to be resolved before simulation results can be used:
 - **Model verification:**
 - ❖ Is the model implemented correctly?
 - **Model validation:**
 - ❖ Is the model representative of the real system?
 - **Transient removal:**
 - ❖ How many initial observations to discard to ensure model has reached steady-state?
 - **Stopping criteria:**
 - ❖ How long to run the simulation?

Model Verification Techniques

- ◆ Techniques for debugging large programs
 - **Code design:**
 - ❖ Modularity
 - ❖ Top-down design
 - ❖ Anti-bugging
 - ❖ Structured walk-through
 - **Test design:**
 - ❖ Deterministic models/inputs
 - ❖ Simplified cases
 - ❖ Degeneracy tests (corner cases)
 - ❖ Consistency tests
 - ❖ Seed independence
 - **Output design:**
 - ❖ Traces (graphic form)
 - ❖ Continuity test

Model Validation Techniques

- ◆ Need to ensure that assumptions used in developing model are valid
- ◆ Validation techniques depend on the assumptions and the system
 - Not generally applicable across all systems
- ◆ Consist of validating three key aspects of the model
 - Assumptions
 - Input parameter values and distributions
 - Output values and conclusions
- ◆ Three possible sources of valid information (for comparison):
 - Expert intuition
 - Real system measurements
 - Theoretical results

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 - Stopping criteria:
 - ❖ How long to run the simulation?

Transient Removal

- ◆ In most simulations, only steady-state performance is of interest
 - Initial transient state of simulation should not be included in metric computations
- ◆ Main challenge:
 - Not possible to define exactly what constitutes the transient state
- ◆ Hence, all methods of transient removal are heuristic:
 - Long runs
 - Proper initialization
 - Truncation
 - Initial data deletion
 - Moving average of independent replications
 - Batch means

Long Runs

- ◆ Use long simulation runs:
 - Ensure that the presence of initial transients will not affect the result significantly
- ◆ ☹️:
 - Wastes computation, storage, and processing resources
 - Difficult to ensure that the length of run chosen is long enough

Proper Initialization

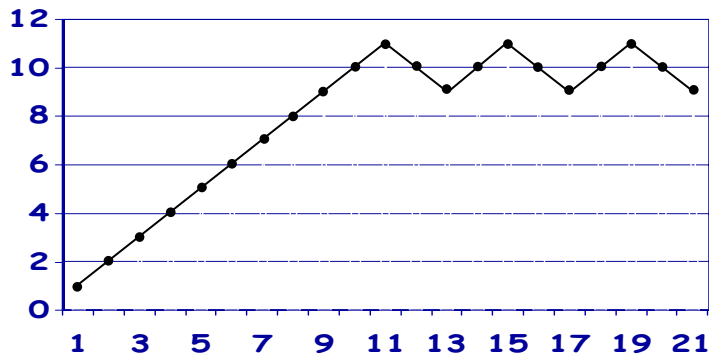
- ◆ Start the simulation in a state close to the expected steady state
 - Results in a reduction of length of transient period
- ◆ Example:
 - Start a CPU simulation with some jobs in the queue (not empty queue)
 - The number of initial jobs may be determined from previous simulations or by simple analysis

Truncation

- ◆ Assumption:
 - Variability during steady-state is less than during the transient state
- ◆ One measure of variability: range of observations
 - In a trajectory plotting successive observations, range of observations can often be seen to stabilize as simulation enters steady-state
- ◆ Method:
 - Given a sample $\{x_1, x_2, \dots, x_n\}$
 - Ignore the first L observations and calculate the minimum and maximum of remaining $(n-L)$ observations
 - Repeat above step for $L=1, 2, \dots, n-1$
 - ❖ Until $(L+1)$ -th observation is neither the minimum nor maximum of the remaining observations.
 - Final value of L gives the length of transient state

Truncation Example

- ◆ Observations: 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 10, 9, 10, 11, 10, 9, 10, 11, 10, 9



- ◆ At $L=9$, range of remaining sequence is: (9,11)
 - $(L+1)$ -th observation is: 10
- ◆ Length of transient interval is, therefore, 9

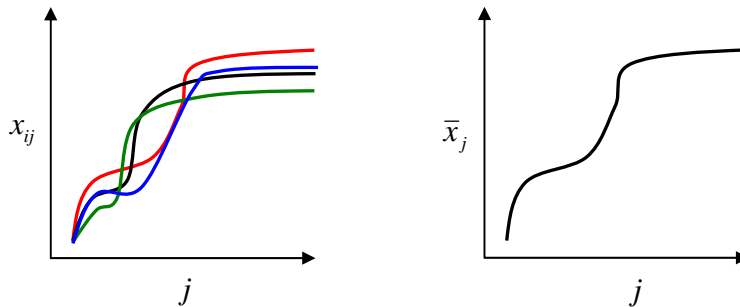
Initial Data Deletion

- ◆ Study change in overall average as some of the initial observations are deleted from the sample
- ◆ Assumption:
 - During steady-state, the average does not change much as some observations are deleted
- ◆ However, randomness does cause average to change slightly even in steady-state
 - First average across several repetitions
 - Watch for knee in the average-vs-observation plot

Initial Data Deletion: Methodology

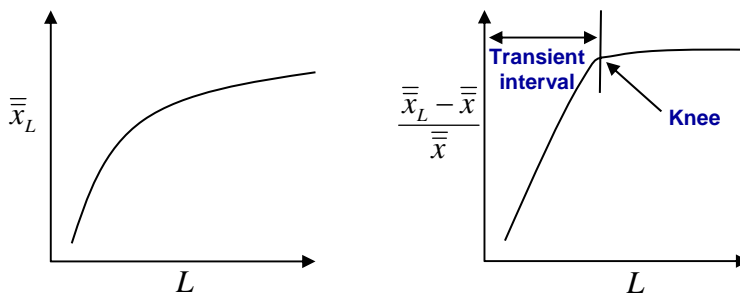
- Suppose m replications of size n each
 - Let x_{ij} denote the j -th observation in the i -th replication
- Get a mean trajectory by averaging, for each j , across replications

$$\bar{x}_j = \frac{1}{m} \sum_{i=1}^m x_{ij}$$



Initial Data Deletion: Methodology

- Get the overall mean of the **mean trajectory**: $\bar{\bar{x}} = \frac{1}{n} \sum_{j=1}^n \bar{x}_j$
- Get an overall mean of last $(n-L)$ values of the **mean trajectory**: $\bar{\bar{x}}_L = \frac{1}{n-L} \sum_{j=L+1}^n \bar{x}_j$
- Compute the relative change in the overall mean: $\frac{\bar{\bar{x}}_L - \bar{\bar{x}}}{\bar{\bar{x}}}$
- Repeat for $L = 1$ to $n-1$
 - Knee of plot of (relative-change vs. L) gives length of the transient interval



Moving Average of Independent Replications

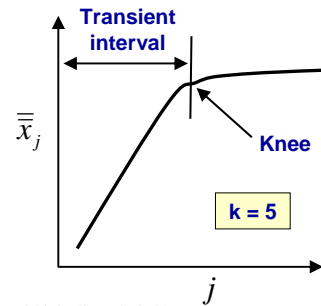
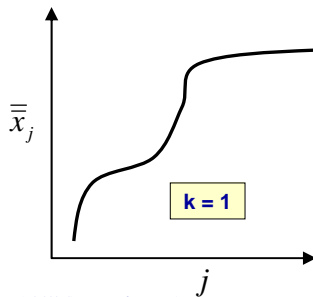
- ◆ Get a mean trajectory by averaging across replications:

$$\bar{x}_j = \frac{1}{m} \sum_{i=1}^m x_{ij}, \quad j = 1, 2, \dots, n$$

- ◆ Plot trajectory of the moving average of successive $(2k+1)$ values

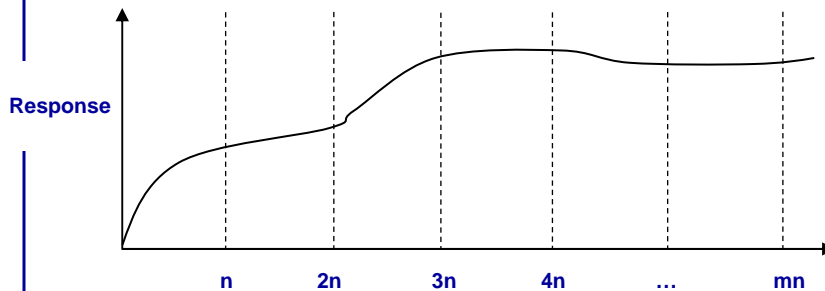
$$\bar{\bar{x}}_j = \frac{1}{2k+1} \sum_{l=-k}^k \bar{x}_{j+l}, \quad j = k+1, k+2, \dots, n-k$$

- ◆ Repeat with $k = 1, 2, 3, \dots$ until the plot is sufficiently smooth
 - Knee of plot gives the length of transient phase



Batch Means

- ◆ Setup:
 - Run a very long simulation
 - Divide it up into several parts (**batches**) of equal duration



- ◆ Approach:
 - Study variance of batch means as a function of batch size

Batch Means: Methodology

- ◆ N observations can be divided into m batches of size n each

- Let x_{ij} be the j-th observation in the i-th batch

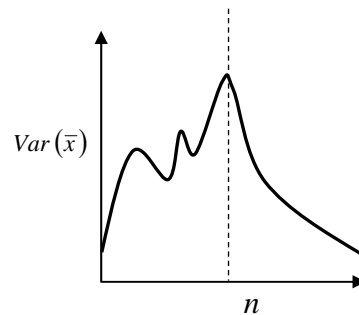
- ◆ For each batch, compute a batch mean: $\bar{x}_i = \frac{1}{n} \sum_{j=1}^n x_{ij}, \quad i = 1, 2, \dots, m$

- ◆ Compute the overall mean: $\bar{\bar{x}} = \frac{1}{m} \sum_{i=1}^m \bar{x}_i$

- ◆ Compute the variance of the batch means: $Var(\bar{x}) = \frac{1}{m-1} \sum_{i=1}^m (\bar{x}_i - \bar{\bar{x}})^2$

- ◆ Repeat for $n=2, 3, 4, \dots$

- ◆ Plot the variance as a function of n
 - Length of transient interval is the value of n at which the variance definitely starts decreasing



Batch Means: Rationale

- ◆ Rationale:

- Suppose length of transient period is T

- If n is much less than T

- ❖ Initial batches bring the overall mean toward the initial batch means and the variance is small

- As batch size increases, variance increases

- At $n > T$, only first batch mean is different; others are roughly equal

- ❖ Results in the decrease of variance

Other Issues Related to Steady-state

- ◆ Final conditions:
 - System state at the end of simulation may not be typical of the steady state
 - Exclude final portion of response from the steady-state computations
 - Methods similar to determining initial transient period
- ◆ Handling entities left at the end of the simulation:
 - Mean service time
 - ❖ Include only those jobs that have completed service
 - Mean waiting time:
 - ❖ Include only those jobs that have started execution
 - Mean queue length
 - ❖ Use time averages, instead of event averages
- ◆ Terminating simulations
 - Study system in transient state

Analysis of Simulation Results

- ◆ Issues to be resolved before simulation results can be used:
 - Model verification:
 - ❖ Is the model implemented correctly?
 - Model validation:
 - ❖ Is the model representative of the real system?
 - Transient removal:
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 - Stopping criteria:
 - ❖ How long to run the simulation?

Stopping Criteria

- Important to set length of simulation correctly
 - If too short, results may be highly variable
 - If too long, computing resources and manpower may be unnecessarily wasted
- Goal:
 - Run simulation until confidence interval for the mean response metric narrows to a desired width
- Confidence interval for the sample mean: $\bar{x} \pm z_{1-\alpha/2} \sqrt{\text{Var}(\bar{x})}$
 - $z_{1-\alpha/2}$: derived from the unit normal variate
 - ❖ Values are well-known and tabulated
 - How to compute: $\text{Var}(\bar{x})$

Variance of the Mean Response Metric

- Variance of the sample mean of n independent observations can be easily obtained from the variance of the observations as:

$$\text{Var}(\bar{x}) = \text{Var}(x) / n$$

- Formula valid only if the observations are independent
- However, observations in most simulations are not independent
 - eg, successive waiting times are highly correlated
 - Formula can not be used to estimate variance of mean waiting time
- For correlated observations
 - Variance of the mean may be several times larger than that obtained from above formula !

Ignoring correlation may lead to narrower confidence intervals and premature termination of simulation

Computing Variance of Mean (Correlated Values)

- ◆ Several methods available:
 - Independent replications
 - Batch means
 - Regeneration
- ◆ Basic Idea:
 - Find regions of independence within the sample, to generate a set of independent means

Independent Replications

- ◆ Basic idea:
 - Mean of independent replications are independent
 - ✦ Even if observations within a replication are correlated
- ◆ Method uses m replications of size $(n + n_0)$ each
 - n_0 : length of initial transient phase
 - First n_0 observations of each replication are discarded
- ◆ Suppose m replications of size n each
 - Let x_{ij} denote the j -th observation in the i -th replication

Independent Replications: Methodology

- For each replication, compute a mean: $\bar{x}_i = \frac{1}{n} \sum_{j=n_0+1}^{n_0+n} x_{ij}, \quad i = 1, 2, \dots, m$
- Compute the overall mean: $\bar{\bar{x}} = \frac{1}{m} \sum_{i=1}^m \bar{x}_i$
- Compute the variance of replicate means: $Var(\bar{x}) = \frac{1}{m-1} \sum_{i=1}^m (\bar{x}_i - \bar{\bar{x}})^2$
- Confidence interval for the mean response is: $\bar{\bar{x}} \pm z_{1-\alpha/2} \sqrt{Var(\bar{x})}$

Selecting m and n

- Method of independent replications requires discarding $m \cdot n_0$ initial observations
 - Larger the m, larger is the wastage of data
- Confidence interval width is inversely proportional to: \sqrt{mn}
 - Narrower confidence interval can be obtained by increasing m or n
- Hence, it is recommended that:
 - Number of replications, m, should be kept fairly small (~10)
 - Length of replications, n, should be increased to obtain the desired confidence

Batch Means

- ◆ Setup:
 - Run a long simulation
 - Discard the initial transient interval
 - Divide the remaining observations into several batches
- ◆ Basic Idea:
 - If batch sizes are larger, means of batches are independent
- ◆ Given a long run of $N + n_0$ observations,
 - Where n_0 belong to initial transient phase and are discarded
 - N observations are divided into m batches of n observations each

Batch Means: Methodology

- ◆ For each batch, compute a mean:
$$\bar{x}_i = \frac{1}{n} \sum_{j=1}^n x_{ij}, \quad i = 1, 2, \dots, m$$
- ◆ Compute the overall mean:
$$\bar{\bar{x}} = \frac{1}{m} \sum_{i=1}^m \bar{x}_i$$
- ◆ Compute the variance of batch means:
$$Var(\bar{x}) = \frac{1}{m-1} \sum_{i=1}^m (\bar{x}_i - \bar{\bar{x}})^2$$
- ◆ Confidence interval for the mean response is:
$$\bar{x} \pm z_{1-\alpha/2} \sqrt{Var(\bar{x})}$$

Selecting m and n

- Only n_0 initial observations are discarded
 - Independent of m or n
 - Wastage smaller than method of independent replications
- Confidence interval width is inversely proportional to: \sqrt{mn}
 - Narrower confidence interval can be obtained by increasing m or n
- Selecting n:
 - Batch size, n, must be large so that the batch means have little correlation
 - One idea: compute the auto-covariance of successive batch means:

$$Cov(\bar{x}_i, \bar{x}_{i+1}) = \frac{1}{m-2} \sum_{i=1}^{m-1} (\bar{x}_i - \bar{\bar{x}})(\bar{x}_{i+1} - \bar{\bar{x}})$$

- Increase n till auto-covariance is small relative to variance of means

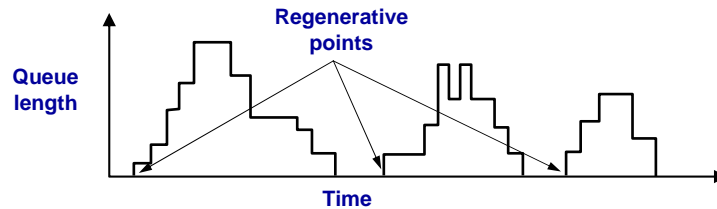
Example: Selecting Batch Size

| Batch Size | Auto-covariance | Variance |
|------------|-----------------|----------|
| 1 | -0.18792 | 1.79989 |
| 2 | 0.02643 | 0.81173 |
| 4 | 0.11024 | 0.42003 |
| 8 | 0.08979 | 0.26437 |
| 16 | 0.04001 | 0.17650 |
| 32 | 0.01108 | 0.10833 |
| 64 | 0.00010 | 0.06066 |
| 128 | -0.00378 | 0.02992 |
| 256 | 0.00027 | 0.01133 |
| 512 | 0.00069 | 0.00503 |
| 1024 | 0.00078 | 0.00202 |

- At n=64, auto-covariance is less than 1% of original sample variance

Method of Regeneration

- Consider a single CPU scheduling simulation
 - Starts with an empty job queue



- System often returns to the initial state of empty job queue
 - On returning to this state, trajectory does not depend on past history
 - Regeneration Point
- Regeneration cycle:
 - Duration between two successive regeneration points

Regenerative Systems

- Mean metrics in different cycles are not correlated
 - Samples collected in different regenerative cycles are independent
- Variance computation is more complex than previous methods
 - Regeneration cycles are of different lengths
 - Overall mean response is not the average of the mean responses of individual cycles
 - If a regenerative simulation has m cycles of sizes: n_1, n_2, \dots, n_m ,

$$\bar{x}_i = \frac{1}{n_i} \sum_{j=1}^{n_i} x_{ij}, \quad \bar{\bar{x}} \neq \frac{1}{m} \sum_{i=1}^m \bar{x}_i$$

Regenerative Systems: Confidence Intervals

- Compute cycle sums: $y_i = \sum_{j=1}^{n_i} x_{ij}, \quad i = 1, 2, \dots, m$
- Compute the overall mean: $\bar{\bar{x}} = \sum_{i=1}^m y_i / \sum_{i=1}^m n_i$
- Calculate difference between expected and observed cycle sums:
 $w_i = y_i - n_i \bar{\bar{x}}, \quad i = 1, 2, \dots, m$
- Calculate the variance of the difference: $Var(w) = s_w^2 = \frac{1}{m-1} \sum_{i=1}^m (w_i)^2$
- Compute the mean cycle length: $\bar{n} = \frac{1}{m} \sum_{i=1}^m n_i$
- Confidence interval for the mean response is: $\bar{x} \pm z_{1-\alpha/2} \frac{s_w}{\bar{n} \sqrt{m}}$

Regenerative Systems Methodology

- ☺:
 - Does not require removing transient observations (no wastage of data)
- ☹:
 - Not all systems are regenerative
 - ❖ A system with two queues will need both queues to be empty
 - Cycle lengths are unpredictable
 - ❖ Not possible to plan the simulation time beforehand
 - Finding the regeneration point is not trivial
 - ❖ Requires checking after every event
 - Mean and variance estimators are biased
 - ❖ Expected values from a random sampling are not equal to the quantity being estimated

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