

Measurement Techniques

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Events and Metrics

- ◆ Event-count metrics
 - Simple counts of number of times an event occurs
 - eg, number of page faults, number of disk I/Os
- ◆ Secondary-event metrics
 - Record the value of secondary parameters when events occur
 - eg, average number of messages queued in a send buffer
 - ❖ Triggering events: message-enqueue and message-dequeue
 - ❖ Measure: queue size, total number of queue operations
- ◆ Measurement Strategies:
 - Event-driven measurements
 - Sampling

Event-driven Measurements

- ◆ Record information whenever pre-selected events occur
 - Eg, modify page-fault handling routine to count number of page faults
- ◆ Tracing:
 - Record a subset of system state that uniquely identifies the event
 - Requires large amount of storage
- ◆ ☺:
 - Overhead of recording information incurred only when events occur
- ◆ ☹:
 - Time between measurements is unpredictable

Appropriate for low-frequency events

Sampling

- ◆ Records subset of system state at fixed time intervals
- ◆ Produces only a statistical summary of overall system behavior
- ◆ ☺:
 - Overhead independent of number of times an event occurs
 - ❖ Tradeoff between sampling frequency and desired resolution
- ◆ ☹:
 - Not every event occurrence gets recorded
 - Each run likely to produce different results
 - ❖ Samples taken asynchronously to program execution

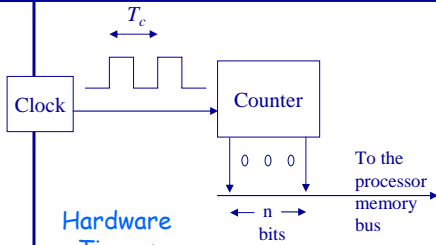
Fundamental Measurement Techniques: Issues

- ◆ Interval Timers
- ◆ Program Profiling
- ◆ Tracing

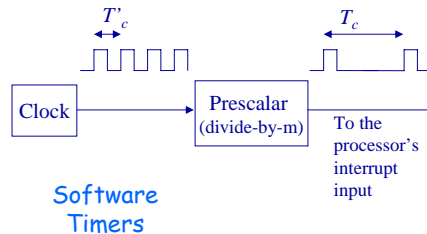
Interval Timers

- ◆ Count the number of clock pulses that occur between two predefined events
- ◆ Uses:
 - Measure the execution time of a code section
 - Provide the time basis for sampling tools
- ◆ $T_e = T_c * (x_2 - x_1)$
 - T_e : measured time
 - T_c : clock period
- ◆ Can be implemented in hardware or software

Hardware and Software Timers



- Count the number of pulses it receives at its clock input
- Programs read memory location mapped to the counter by system manufacturer
- Timer is typically reset to 0 when system is powered up



- Program-readable counter not directly implemented by a clock
- Hardware clock used to generate an interrupt at regular intervals
 - Clock source divided by m through a pre-scaling counter to derive interrupt
 - Counter incremented by interrupt-service routine
- Some systems allow application to reset to 0

Timer Roll-over

- Longest measurable interval: $(2^n - 1) * T_c$
- If count exceeds this value, $(x_2 - x_1)$ is incorrect measure
 - Use $2^n + (x_2 - x_1)$ instead

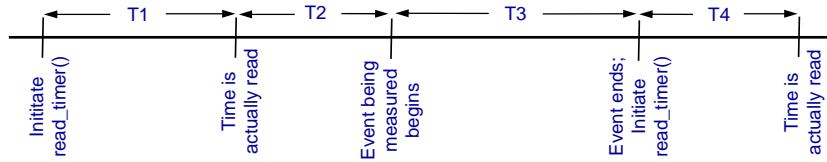
T_c	Counter width, n				
	16	24	32	48	64
10 ns	655 us	168 ms	42.9 s	32.6 days	58.5 centuries
100 ns	6.55 ms	1.68 s	7.16 min	326 days	585 centuries
1 us	65.5 ms	16.8 s	1.19 h	9.15 years	5,850 centuries
10 us	655 ms	2.8 min	11.9 h	89.3 years	58,500 centuries
100 us	6.55 s	28 min	4.97 days	893 years	585,000 centuries
1 ms	1.09 min	4.66 h	49.7 days	89.3 centuries	5,850,000 centuries

A few bits can help a lot!

Timer Overhead

```

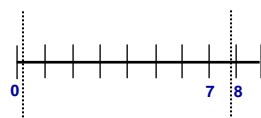
t_start = read_timer()
<event being timed>
t_end = read_timer()
elapsed_time = (t_end - t_start)*t_cycle
    
```



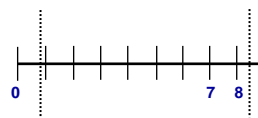
- ◆ Timer overhead: T_{ovhd}
 - Event time = $T_e = T_3$
 - Measured time = $T_2 + T_3 + T_1 = T_e + T_{ovhd}$
 - If $T_{ovhd} \ll T_e$, it can be ignored, else should be measured and subtracted
- ◆ ☹:
 - Variations in T_{ovhd} can be comparable to those in T_e
 - $T_e/T_{ovhd} > 100$

Quantization Errors

- ◆ Resolution: smallest change that can be detected and displayed by an interval timer
 - Typically, equal to a single clock tick, T_c
- ◆ Introduces a random quantization error into all measurements
 - Unpredictable and random



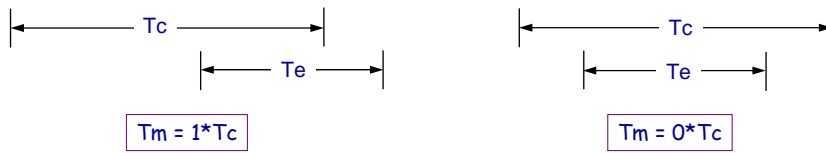
Timer reports: $T_m = 7 \cdot T_c$



Timer reports: $T_m = 8 \cdot T_c$

- ◆ Actual event time is within $n \cdot T_c < T_e < (n+1) \cdot T_c$
 - If T_e is smaller than T_c , impossible to directly measure T_e
- ◆ Tradeoff between resolution and roll-over frequency

Statistical Measures of Short Intervals



- ◆ Measurement is a Bernoulli experiment
 - Outcome is $1 * T_c$ with probability p
 - Outcome is $0 * T_c$ with probability $1-p$
- ◆ Repeating experiment n times yield a binomial distribution
 - As long as the n measurements are **independent**
- ◆ If number of "1" outcomes is m , then $m/n \sim T_e/T_c$
 - $T_e = m * T_c / n$

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Program Profiling

- ◆ Profile:
 - Measurement of the time spent by system in certain states
- ◆ Useful in identifying bottlenecks
 - In program code
 - In accessing system resources
- ◆ Examples of profiling techniques
 - PC Sampling
 - Basic-block Counting

PC Sampling

- ◆ Executing program is sampled at fixed points in time
 - External periodic signal interrupts program at fixed intervals
 - State information recorded by interrupt-servicing routine
 - ❖ Check return-address stack to find address of instruction
 - ❖ Use compiler's symbol-table information to map instruction address to a subroutine identifier
 - ❖ Increment counter for that subroutine
- ◆ Accuracy of statistical inference can be improved by:
 - Collecting more samples
 - ❖ Sampling for longer durations
 - ❖ Increasing the sampling rate
 - Ensuring interrupts occur asynchronously with sampled events
 - ❖ Ensures independence of random samples

Basic-block Counting

- ◆ Basic block:
 - Sequence of instructions with no branches into or out of the sequence
 - ❖ If first instruction is executed, all of the rest are as well
- ◆ Program can be profiled by inserting additional instructions at the beginning of every basic block
 - Profiling resolution is in terms of basic-blocks (not subroutines)
- ◆ ☺:
 - Yields an **exact** execution frequency histogram
 - Repeatable
- ◆ ☹:
 - Can incur significant run-time overhead
 - ❖ Access array of counters for current block's counter
 - ❖ Basic blocks typically have 3-20 instructions: 100% overhead!
 - Additional memory required to store counter array
 - Both of the above may alter program behavior

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Event Tracing

- ◆ Profiling ignores the time-ordering of events
 - Use program trace instead
- ◆ Trace:
 - A dynamic list of events generated by the executing program
 - ❖ Instructions executed
 - ❖ Memory addresses accessed
 - ❖ Disk blocks referenced
 - Can be analyzed to characterize overall program behavior
 - Typically, used as input to drive a simulator

Trace Generation

- ◆ Source-code modification
 - Add tracing statements to the source code
 - ☹: can reduce trace volume by tracing only desired events
 - ☹: time-consuming, error-prone
- ◆ Software Exceptions
 - Processor mode that forces a software exception just before each instruction execution
 - ❖ T-bit in DEC's VAX, Motorola 68000
 - ☹: slowed down programs by up to 1000 times
- ◆ Emulation
 - Emulation of a system on a completely different system
 - ❖ Eg, Java Virtual Machine
 - Modify emulator to output trace of instructions
 - ☹: emulation is slower than direct execution
- ◆ Compiler modification
 - Compiler adds extra instructions at entry point of each basic block

```
sum_x = 0.0
trace(1);
for (i=1; i <=n; i++)
  trace(2);
  {
    sum_x += x[i];
    trace(3);
  }
mean = sum_x / n;
trace(4);
```

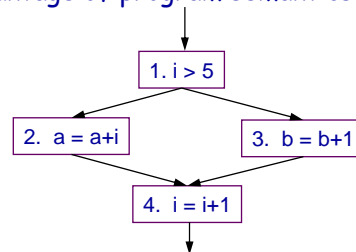
Trace Compression

- ◆ Tracing overheads:
 - Execution time slow down
 - Tremendous volume of data produced in a short time (~GB/min)
 - ❖ Large disk space needed
 - ❖ Disk I/O interferes with program execution
- ◆ Remedies for reducing amount of data:
 - Online trace consumption
 - ❖ Lack of repeatability
 - Data compression
 - ❖ Additional time needed to compress and decompress
 - Trace sampling
 - ❖ Not clear what is the right sampling technique, frequency, ...
 - Abstract execution

Abstract Execution

- ◆ Trace compression that takes advantage of program semantics

```
1. if ( i < 5 )
2.   then a = a + i;
3.   else b = b + 1;
4.   i = i + 1;
```



- ◆ Two-step tracing process:
 - Trace-generation:
 - ❖ Program analysis to identify a subset of trace that can reproduce the full trace
 - Trace-consumption:
 - ❖ Execution of trace-generation routines to retrieve full trace
- ◆ ☺:
 - Reduces trace size by 10 to 100 times
 - Slows down program being traced by 2-10 times
 - ❖ Comparable to other tracing techniques

Measuring System Load Using an Idle Loop

- Estimate:
 - Number of processes running on the system
- Use:
 - A program that counts up from zero
- Idea:
 - Run for a fixed amount of time on unloaded system
 - ❖ Let value of count be n
 - Run on loaded system
 - ❖ If one other process, count should be $n/2$
 - ❖ If m other processes, count should be $n/(m+1)$

Perturbations Due to Measurements

- Measurements impact system performance
 - Code can alter the spatial and temporal patterns of memory access
 - ❖ Cache may be flushed more often
 - ❖ Trace instructions could increase cache-hit rate
 - ❖ Cache performance impacted in an **unpredictable** manner
 - Increase in code size can result in larger overall context-switches
 - ❖ Can significantly alter program's paging behavior
- Trends:
 - Higher is the granularity of measurement, more is the perturbation
 - Perturbations are non-linear and non-additive
 - ❖ Doubling the amount of instrumentation need not double the impact on performance

Impact of perturbations on conclusions should be analyzed

Course Outline

- ◆ Selection of metrics
- ◆ Performance Evaluation Methodologies
- ◆ Workload selection
- ◆ Measurements tools
- ◆ **Analysis and visualization of measured data**
- ◆ System Modeling
- ◆ Simulations
- ◆ Case studies
- ◆ Distributed monitoring infrastructures
- ◆ PA in the Research and Industrial communities