



A Theory of Rate-Based Execution

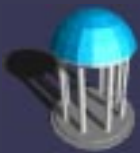
Kevin Jeffay

Department of Computer Science
University of North Carolina
at Chapel Hill
jeffay@cs.unc.edu

Steve Goddard

Computer Science & Engineering
University of Nebraska – Lincoln
goddard@cse.unl.edu

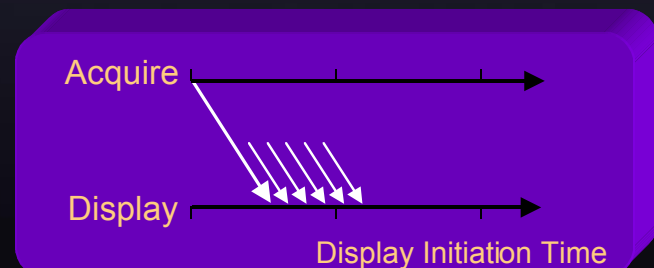
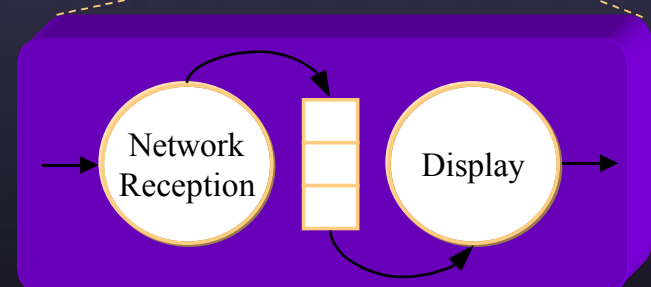
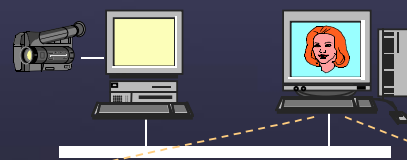
<http://www.cs.unc.edu/Research/Dirt/>



A Theory of Rate-Based Execution

What's wrong with the Liu & Layland model?

- Loosely speaking, nothing is periodic or sporadic in a distributed system
- The essential problem seems to be the requirement that the arrival process be somehow constrained





A Theory of Rate-Based Execution

Goals

- Extend the Liu and Layland theory of real-time processor scheduling to:
 - Support notions of execution rate that are more general than periodic or sporadic execution
 - Support integrated real-time device and application processing
 - Support responsive non-real-time computing

3



Rate-Based Execution

Concept

- Schedule tasks at the *average rate* at which they are expected to be invoked
 - Make buffering a first-class concept in the model
 - Understand the fundamental relationships between feasibility, response time, and processing rate
- Develop a model of tasks wherein:
 - Tasks complete execution before a well-defined deadline
 - Tasks make progress at application-specified rates
 - No constraints are placed on the external environment

4



Rate-Based Execution

Formal model

- Process make progress at the rate of processing x events every y time units, each event is processed within d time units
- For task i with rate specification (x_i, y_i, d_i) , the j^{th} event for task i , arriving at time $t_{i,j}$, will be processed by time

$$D(i, j) = \begin{cases} t_{i,j} + d_i & \text{if } 1 \leq j \leq x_i \\ \text{MAX}(t_{i,j} + d_i, D(i, j-x_i) + y_i) & \text{if } j > x_i \end{cases}$$

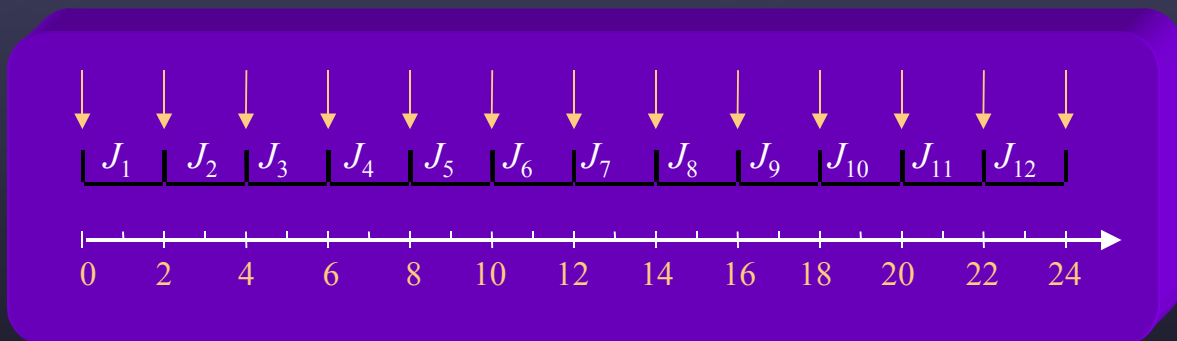
- Deadlines occur at least d time units after a job is released
- Deadlines separated by at least y time units

5



Rate-Based Execution

Example: Periodic arrivals, periodic service



- Task with rate specification $(x = 1, y = 2, d = 2)$

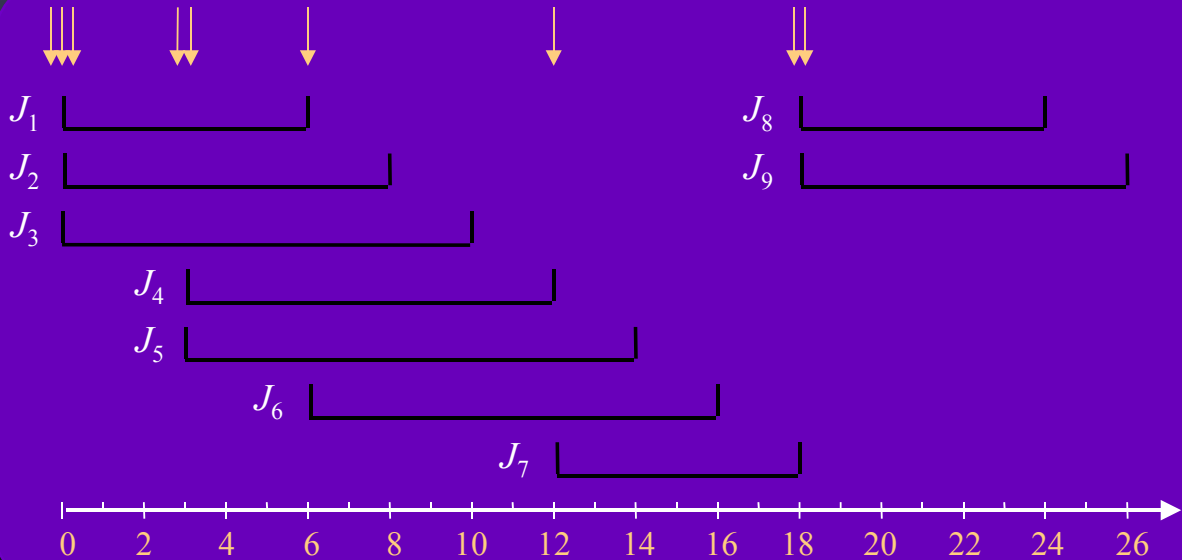
$$D(i, j) = \begin{cases} t_{i,j} + d_i & \text{if } 1 \leq j \leq x_i \\ \text{MAX}(t_{i,j} + d_i, D(i, j-x_i) + y_i) & \text{if } j > x_i \end{cases}$$

6



Rate-Based Execution

Bursty arrivals



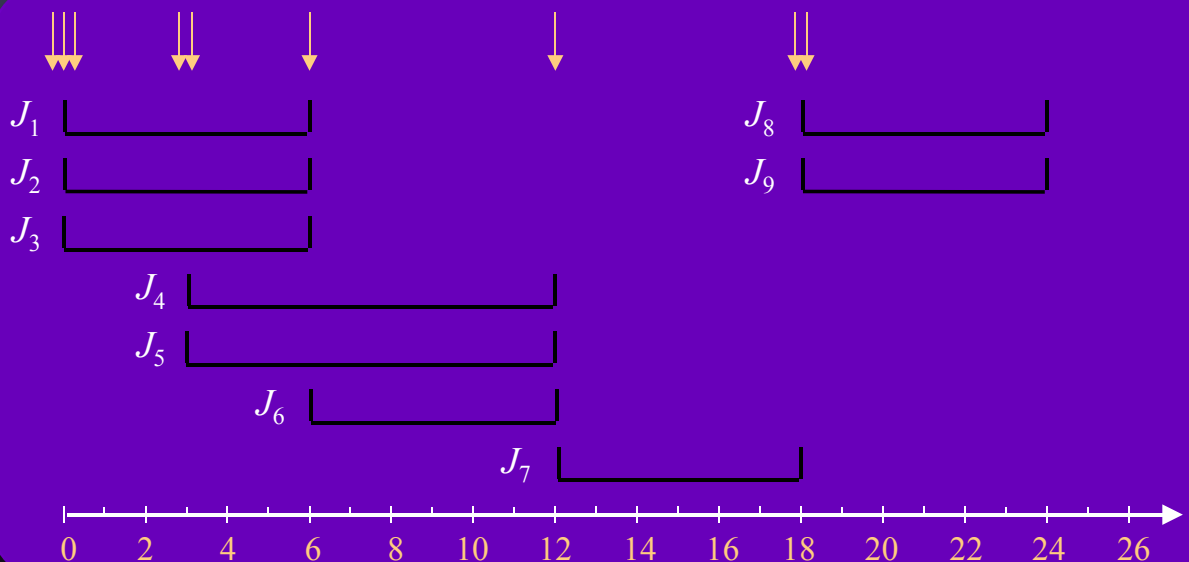
- Task with rate specification $(x = 1, y = 2, d = 6)$

7



Rate-Based Execution

Bursty arrivals



- Task with rate specification $(x = 3, y = 6, d = 6)$

8

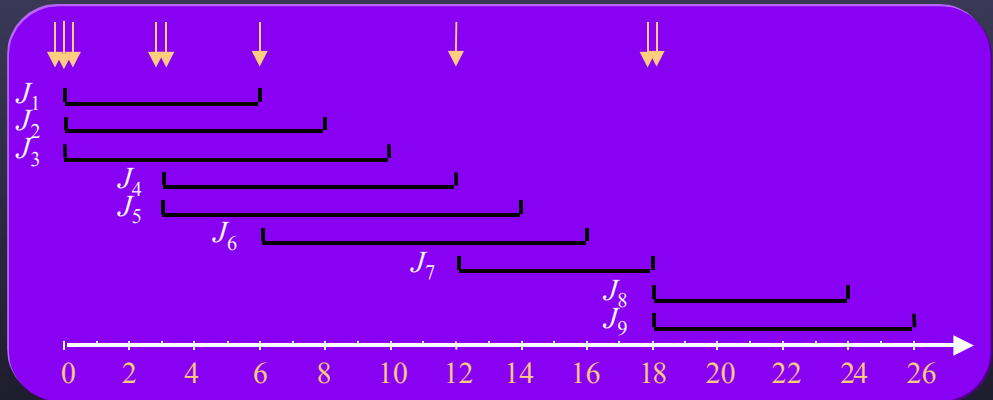


Rate-Based Execution

Comparison of different rate specifications

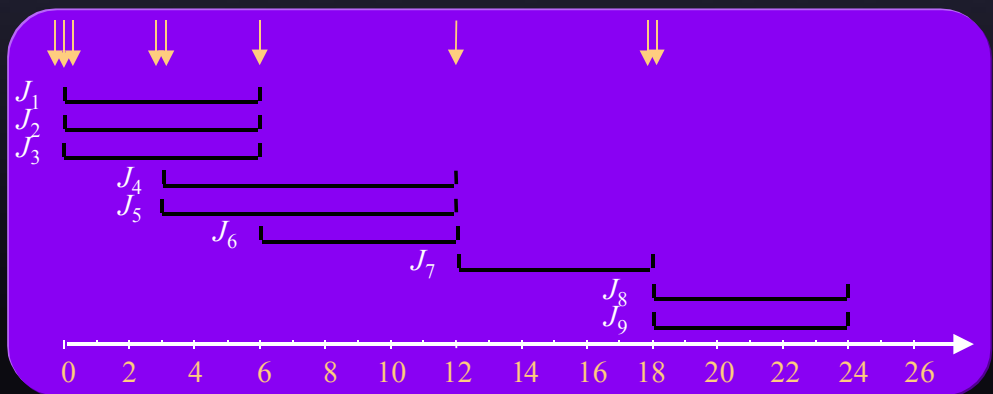
Rate specification

$(x = 1, y = 2, d = 6)$



Rate specification

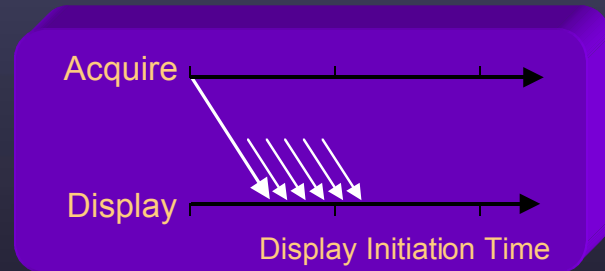
$(x = 3, y = 6, d = 6)$



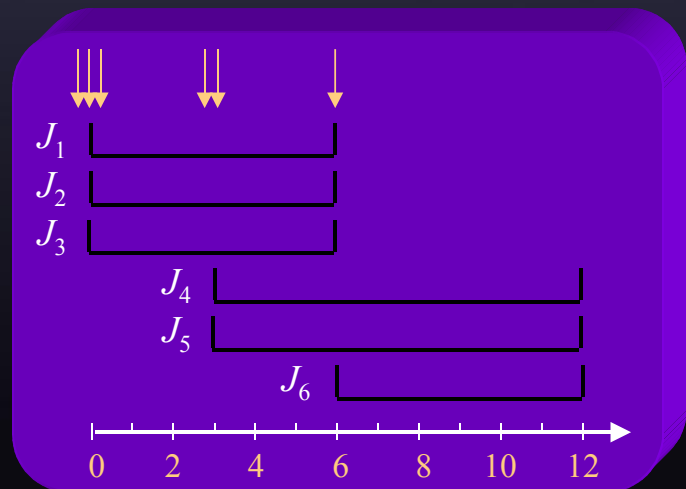
Using RBE Tasks

What problems do they solve?

- RBE tasks provide a more natural way of modeling inbound packet processing of fragmented messages



Rate specification
 $(x = 3, y = 6, d = 6)$





A Theory of Rate-Based Execution

Feasibility under preemption constraints

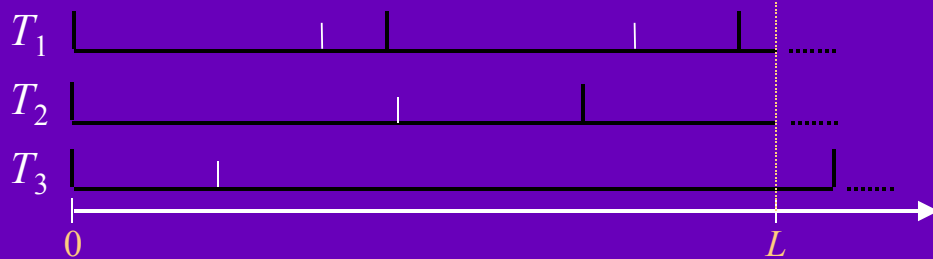
- Feasibility conditions for periodic and sporadic tasks, for all other known execution environments, also hold for *RBE* tasks
 - Feasibility under non-preemptive scheduling
 - Feasibility under scheduling with critical sections
 - Feasibility under scheduling with interrupt handlers
- Thus feasibility is not inherently a function of release times
 - Under deadline-driven scheduling, feasibility is a function of the implementation of a task set
 - Under static-priority scheduling, feasibility is a function of the behavior of the external environment

11



Feasibility of RBE Tasks

Feasibility under preemptive scheduling



- Feasibility conditions of *RBE* tasks with rate specifications (x, y, c, d) are precisely the same as for periodic tasks

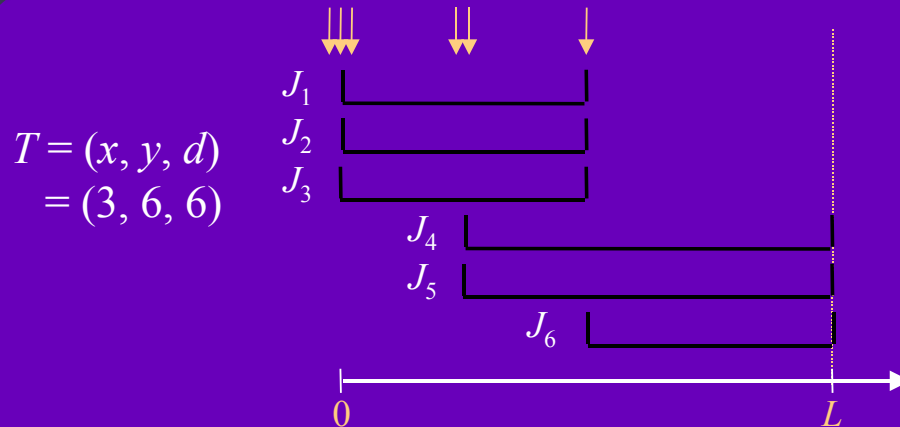
$$\forall L, L > 0: L \geq \sum_{i=1}^n \left\lfloor \frac{L - d_i + y_i}{y_i} \right\rfloor x_i c_i$$

12



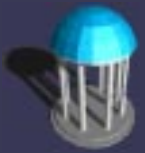
A Theory of Rate-Based Execution

On the relationship to periodic tasks



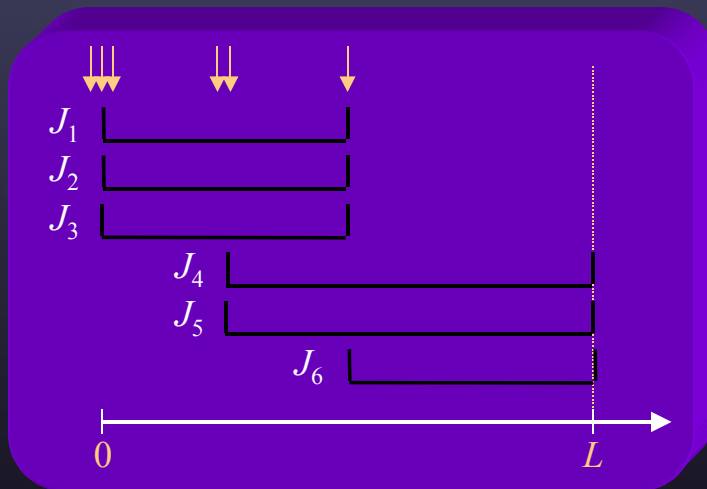
- But can't an RBE task be modeled as x instances of a periodic task (with some appropriate precedence relationship between instances)?

13



A Theory of Rate-Based Execution

A corollary on static priority scheduling



$$L \geq \sum_{j=1}^i \left\lceil \frac{L}{p_j} \right\rceil c_j$$

- Under a static priority scheduling scheme, the processor demand in any interval can be unbounded
 - Thus event driven, rate-based execution is not possible under static priority scheduling schemes

14



A Theory of Rate-Based Execution Summary

- Traditional Liu & Layland theory is not directly applicable to distributed real-time systems
- The theory of scheduling periodic & sporadic tasks applies verbatim to RBE tasks
 - Polynomial & pseudo-polynomial time schedulability conditions exist for
 - » Preemptive scheduling
 - » Non-preemptive scheduling
 - » Scheduling with interrupt handlers
 - » Scheduling with critical sections
 - The *earliest-deadline-first* scheduling algorithm is optimal

15



A Theory of Rate-Based Execution Summary

- The feasibility of a set of “periodic tasks” was never inherently a function of the periodic arrival requirement
 - The only requirement is that exist a minimal separation between deadlines
- But if static priority scheduling methods are employed then (in the worst case) periodic arrivals are required
 - Static priority methods require a well-behaved external environment
 - Deadline methods require a well-behaved operating system

16