Virtual Memory: Paging

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Portions courtesy Emmett Witchel and Kevin Jeffay
Review

• Program addresses are virtual addresses.
  – Relative offset of program regions can not change during program execution. E.g., heap can not move further from code.
  – (Virtual address == physical address) is inconvenient.
    • Program location is compiled into the program.

• Segmentation:
  – Simple: two registers (base, offset) sufficient
  – Limited: Virtual address space must be <= physical
  – Push complexity to space management:
    • Must allocate physically contiguous region for segments
    • Must deal with external fragmentation
    • Swapping only at segment granularity

• Key idea for today: Fixed size units (pages) for translation
  • More complex mapping structure
  • Less complex space management
Virtual Memory

• **Key problem:** How can one support programs that require more memory than is physically available?
  – How can we support programs that do not use all of their memory at once?

• Hide physical size of memory from users
  – Memory is a “large” *virtual address space* of $2^n$ bytes
  – Only portions of VAS are in physical memory at any one time (increase memory utilization).

• Issues
  – Placement strategies
    • Where to place programs in physical memory
  – Replacement strategies
    • What to do when there exist more processes than can fit in memory
  – Load control strategies
    • Determining how many processes can be in memory at one time
Solution: Paging

- Physical memory partitioned into equal sized *page frames*
  - Example page size: 4KB
- Memory only allocated in page frame sized increments
  - No external fragmentation
  - Can have internal fragmentation
    (rounding up smaller allocations to 1 page)
- Can map any page-aligned virtual address to a physical page frame
Abstraction: 1:1 mapping of page-aligned virtual addresses to physical frames

- Imagine a **big ole’ table (BOT):**
  - The size of memory / the size of a page frame
- Address translation is a 2-step process
  1. Map virtual page onto physical frame (using BOT)
  2. Add offset within the page
A physical address can be split into a pair \((f, o)\)

- \(f\) — frame number (\(f_{\text{max}}\) frames)
- \(o\) — frame offset (\(o_{\text{max}}\) bytes/frames)

Physical address = \(o_{\text{max}} \times f + o\)

As long as a frame size is a power of 2, easy to split address using bitwise shift operations
- Prepare for lots of power-of-2 arithmetic…
Suppose a 16-bit address space with \( o_{\text{max}} \) = 512 byte page frames.
- Reminder: 512 == \( 2^9 \)
- Address 1,542 can be translated to:
  - Frame: \( \frac{1,542}{512} = 1,542 \gg 9 = 3 \)
  - Offset: \( 1,542 \% 512 = 1,542 \& (512-1) = 6 \)
- More simply: \((3,6)\)
Virtual Page Addresses

- A process’s virtual address space is partitioned into equal sized *pages*
  - \(|\text{page}| = |\text{page frame}|\)

A virtual address is a pair \((p, o)\)

- \(p\) — page number \((p_{\text{max}}\) pages\)
- \(o\) — page offset \((o_{\text{max}}\) bytes/pages\)

Virtual address = \(o_{\text{max}} \times p + o\)

\[2^{n-1} = (p_{\text{MAX}}-1, o_{\text{MAX}}-1)\]
Page mapping

- Pages map to *frames*
- Pages are contiguous in a VAS...
  - But pages are arbitrarily located in physical memory, and
  - Not all pages mapped at all times
Questions

• The offset is the same in a virtual address and a physical address.
  – A. True
  – B. False
Page Tables (aka Big Ole’ Table)

- A page table maps virtual pages to physical frames
1 table per process  
Part of process metadata/state

• Contents:
  – Flags — dirty bit, resident bit, clock/reference bit
  – Frame number

![Diagram of page table and virtual/physical addresses](image)
A system with 16-bit addresses
- 32 KB of physical memory
- 1024 byte pages
Performance Issues with Paging

• Problem — VM reference requires 2 memory references!
  – One access to get the page table entry
  – One access to get the data

• Page table can be very large; a part of the page table can be on disk.
  – For a machine with 64-bit addresses and 1024 byte pages, what is the size of a page table?

• What to do?
  – Most computing problems are solved by some form of...
    • Caching
    • Indirection
Using a TLB to Cache Translations

- Cache recently accessed page-to-frame translations in a TLB
  - For TLB hit, physical page number obtained in 1 cycle
  - For TLB miss, translation is updated in TLB
  - Has high hit ratio (why?)
Dealing with Large Tables

- Add additional levels of indirection to the page table by sub-dividing page number into $k$ parts
  - Create a “tree” of page tables
  - TLB still used, just not shown
  - The architecture determines the number of levels of page table

Virtual Address

$$p_1 \rightarrow p_2 \rightarrow p_3 \rightarrow o$$

First-Level Page Table

Second-Level Page Tables

Third-Level Page Tables

Dealing with Large Tables
Dealing with Large Tables

- **Example**: Two-level paging

![Diagram showing two-level paging](image)
Large Virtual Address Spaces

- With large address spaces (64-bits) forward mapped page tables become cumbersome.
  - E.g. 5 levels of tables.

- Instead of making tables proportional to size of virtual address space, make them proportional to the size of physical address space.
  - Virtual address space is growing faster than physical.

- Use one entry for each physical page with a hash table
  - Translation table occupies a very small fraction of physical memory
  - Size of translation table is independent of VM size

- Page table has 1 entry per virtual page
- Hashed/Inverted page table has 1 entry per physical frame
Frames and pages

• Only mapping virtual pages that are in use does what?
  – A. Increases memory utilization.
  – B. Increases performance for user applications.
  – C. Allows an OS to run more programs concurrently.
  – D. Gives the OS freedom to move virtual pages in the virtual address space.

• Address translation and changing address mappings are
  – A. Frequent and frequent
  – B. Frequent and infrequent
  – C. Infrequent and frequent
  – D. Infrequent and infrequent
Hashed/Inverted Page Tables

• Each frame is associated with a register containing
  – Residence bit: whether or not the frame is occupied
  – Occupier: page number of the page occupying frame
  – Protection bits

• Page registers: an example
  – Physical memory size: 16 MB
  – Page size: 4096 bytes
  – Number of frames: 4096
  – Space used for page registers (assuming 8 bytes/register): 32 Kbytes
  – Percentage overhead introduced by page registers: 0.2%
  – Size of virtual memory: irrelevant
Inverted Page Table Lookup

• CPU generates virtual addresses, where is the physical page?
  – Hash the virtual address
  – Must deal with conflicts

• TLB caches recent translations, so page lookup can take several steps
  – Hash the address
  – Check the tag of the entry
  – Possibly rehash/traverse list of conflicting entries

• TLB is limited in size
  – Difficult to make large and accessible in a single cycle.
  – They consume a lot of power (27% of on-chip for StrongARM)
Inverted Page Table Lookup

- Hash page numbers to find corresponding frame number
  - Page frame number is not explicitly stored (1 frame per entry)
  - Protection, dirty, used, resident bits also in entry

$h(PID, p)$
Searching Inverted Page Tables

• Page registers are placed in an array

• Page $i$ is placed in slot $f(i)$ where $f$ is an agreed-upon hash function

• To lookup page $i$, perform the following:
  – Compute $f(i)$ and use it as an index into the table of page registers
  – Extract the corresponding page register
  – Check if the register tag contains $i$, if so, we have a hit
  – Otherwise, we have a miss
Searching Inverted Page Tables

• Minor complication
  – Since the number of pages is usually larger than the number of slots in a hash table, two or more items \textit{may} hash to the same location

• Two different entries that map to same location are said to collide

• Many standard techniques for dealing with collisions
  – Use a linked list of items that hash to a particular table entry
  – Rehash index until the key is found or an empty table entry is reached (open hashing)
Observation

• One cool feature of inverted page tables is that you only need one for the entire OS
  – Recall: each entry stores PID and virtual address
  – Multiple processes can share one inverted table

• Forward mapped tables have one table per process
Questions

• Why use hashed/inverted page tables?
  – A. Forward mapped page tables are too slow.
  – B. Forward mapped page tables don’t scale to larger virtual address spaces.
  – C. Inverted pages tables have a simpler lookup algorithm, so the hardware that implements them is simpler.
  – D. Inverted page tables allow a virtual page to be anywhere in physical memory.
Swapping

- A process's VAS is its context
  - Contains its code, data, and stack

- Code pages are stored in a user's file on disk
  - Some are currently residing in memory; most are not

- Data and stack pages are also stored in a file
  - Although this file is typically not visible to users
  - File only exists while a program is executing

- OS determines which portions of a process's VAS are mapped in memory at any one time
References to non-mapped pages generate a page fault
- Remember Interrupts?

Page fault handling steps:
Processor runs the interrupt handler
OS blocks the running process
OS starts read of the unmapped page
Read of page completes
OS resumes/initiates some other process
OS maps the missing page into memory
OS restart the faulting process
Performance Analysis

• To understand the overhead of swapping, compute the effective memory access time (EAT)
  
  \[ EAT = \text{memory access time} \times \text{probability of a page hit} + \text{page fault service time} \times \text{probability of a page fault} \]

• Example:
  
  – Memory access time: 60 ns
  – Disk access time: 25 ms
  – Let \( p \) = the probability of a page fault
  
  \[ EAT = 60(1-p) + 25,000,000p \]

• To realize an EAT within 5% of minimum, what is the largest value of \( p \) we can tolerate?
Segmentation vs. Paging

• Segmentation has what advantages over paging?
  – A. Fine-grained protection.
  – B. Easier to manage transfer of segments to/from the disk.
  – C. Requires less hardware support
  – D. No external fragmentation

• Paging has what advantages over segmentation?
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Meta-Commentary

• Paging is really efficient when memory is relatively scarce
  – But comes with higher latency, higher management costs in hardware and software

• But DRAM is getting more abundant!
  – Push for larger page granularity (fewer levels of page tables)
  – Or just go back to segmentation??
    • If everything fits into memory with space to spare, why not?
Summary

- Physical and virtual memory partitioned into equal size units
- Size of VAS unrelated to size of physical memory
- Virtual *pages* are mapped to physical *frames*
- Simple placement strategy
- There is no external fragmentation
- Key to good performance is minimizing page faults