Virtual Memory and Address Translation

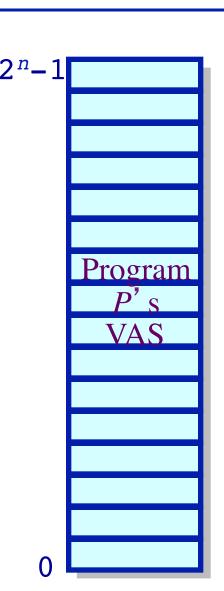
Review

- Program addresses are virtual addresses.
 - ➤ Relative offset of program regions can not change during program execution. E.g., heap can not move further from code.
 - Virtual addresses == physical address inconvenient.
 - Program location is compiled into the program.
- A single offset register allows the OS to place a process' virtual address space anywhere in physical memory.
 - Virtual address space must be smaller than physical.
 - > Program is swapped out of old location and swapped into new.
- Segmentation creates external fragmentation and requires large regions of contiguous physical memory.
 - > We look to fixed sized units, memory pages, to solve the problem.

Virtual Memory

Concept

- Key problem: How can one support programs that require more memory than is physically available?
 - ➤ How can we support programs that do not use all of their memory at once?
- Hide physical size of memory from users
 - ➤ Memory is a "large" *virtual address space* of 2ⁿ bytes
 - Only portions of VAS are in physical memory at any one time (increase memory utilization).
- Issues
 - > Placement strategies
 - Where to place programs in physical memory
 - > Replacement strategies
 - What to do when there exist more processes than can fit in memory
 - Load control strategies
 - Determining how many processes can be in memory at one time



Realizing Virtual Memory

Paging

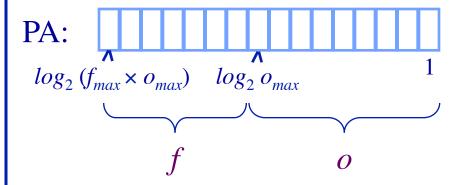
- Physical memory partitioned into equal sized
 page frames
 - Page frames avoid external fragmentation.

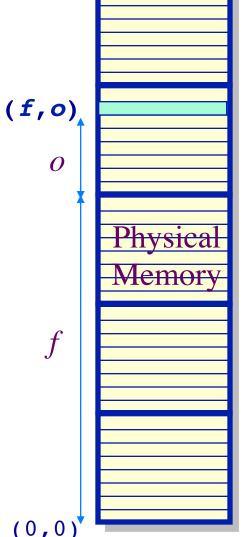
A memory address is a pair (f, o)

f — frame number (f_{max} frames)

o — frame offset (o_{max} bytes/frames)

Physical address = $o_{max} \times f + o$

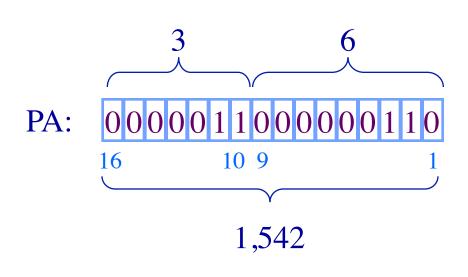


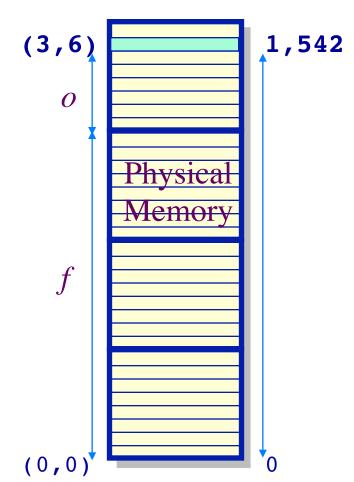


Physical Address Specifications

Frame/Offset pair v. An absolute index

- Example: A 16-bit address space with $(o_{max} =)$ 512 byte page frames
 - ➤ Addressing location (3, 6) = 1,542





Questions

- The offset is the same in a virtual address and a physical address.
 - > A. True
 - ➤ B. False

Realizing Virtual Memory

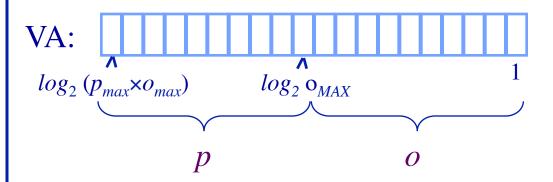
Paging

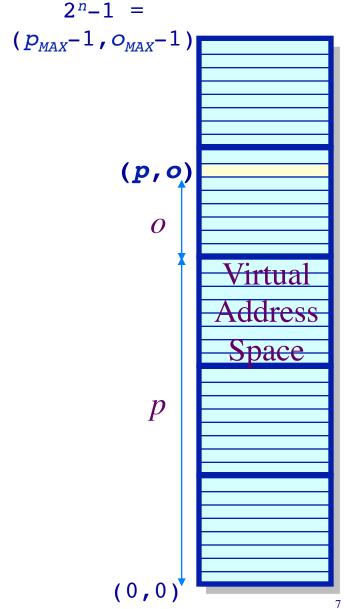
 A process's virtual address space is partitioned into equal sized pages

A virtual address is a pair (p, o)

- p page number (p_{max} pages)
- o page offset (o_{max} bytes/pages)

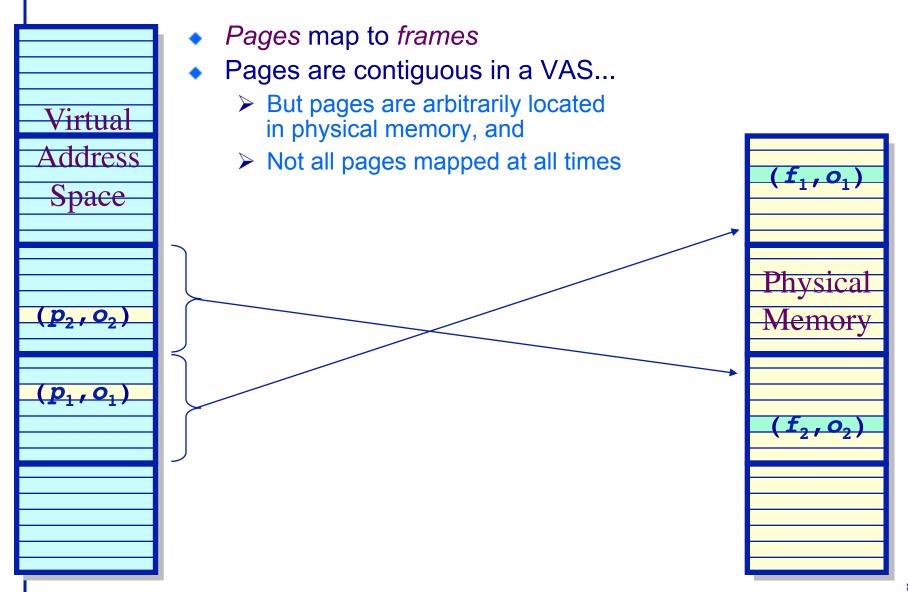
Virtual address = $o_{max} \times p + o$





Paging

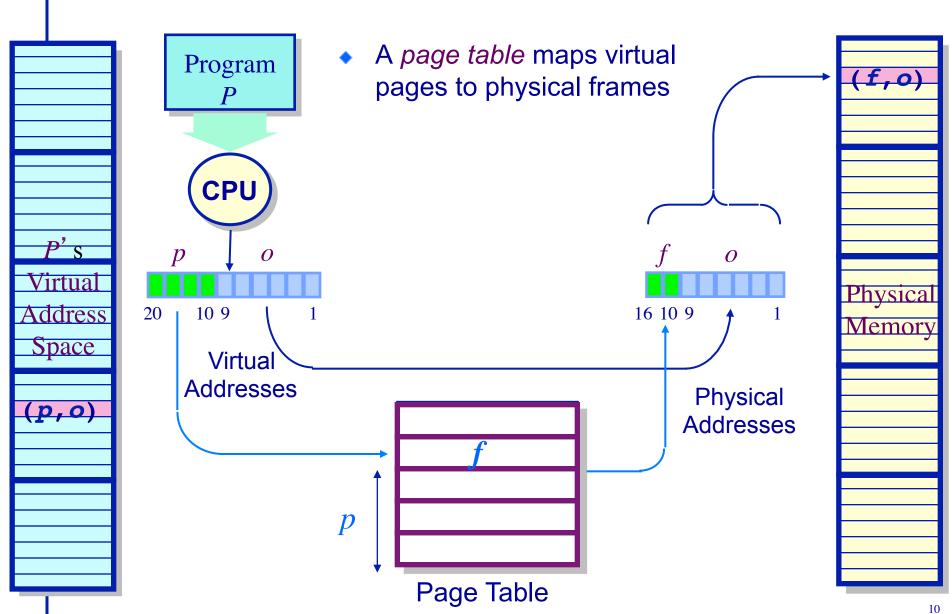
Mapping virtual addresses to physical addresses



Frames and pages

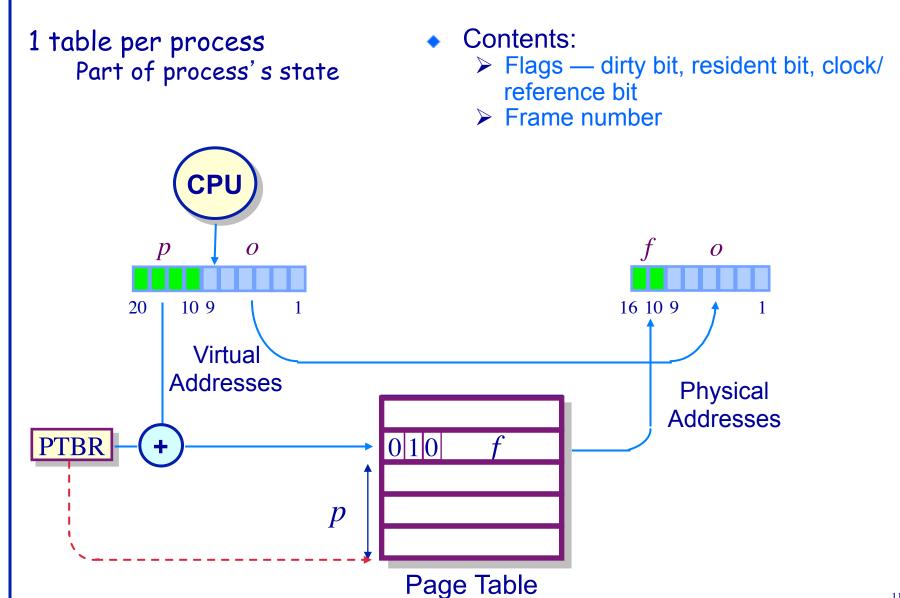
- Only mapping virtual pages that are in use does what?
 - > A. Increases memory utilization.
 - > B. Increases performance for user applications.
 - C. Allows an OS to run more programs concurrently.
 - ➤ D. Gives the OS freedom to move virtual pages in the virtual address space.
- Address translation and changing address mappings are
 - > A. Frequent and frequent
 - ➤ B. Frequent and infrequent
 - > C. Infrequent and frequent
 - > D. Infrequent and infrequent

Paging Virtual address translation



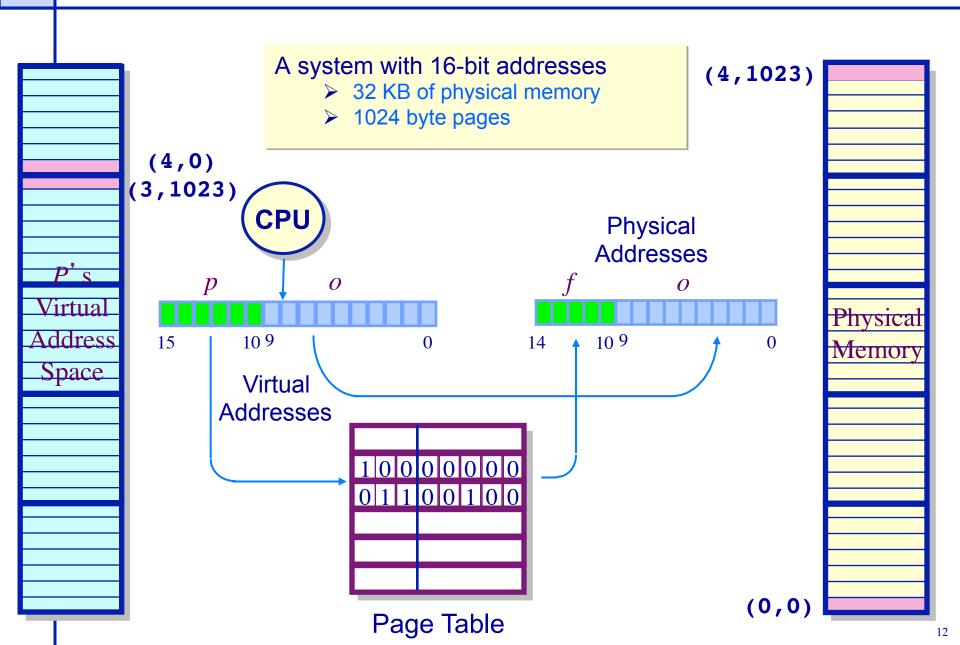
Virtual Address Translation Details

Page table structure



Virtual Address Translation Details

Example



Virtual Address Translation

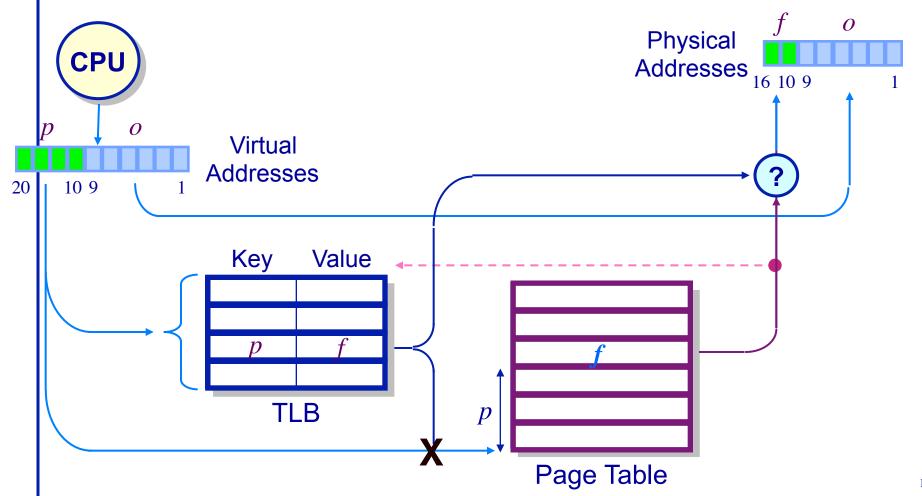
Performance Issues

- Problem VM reference requires 2 memory references!
 - One access to get the page table entry
 - One access to get the data
- Page table can be very large; a part of the page table can be on disk.
 - ➤ For a machine with 64-bit addresses and 1024 byte pages, what is the size of a page table?
- What to do?
 - Most computing problems are solved by some form of...
 - Caching
 - Indirection

Virtual Address Translation

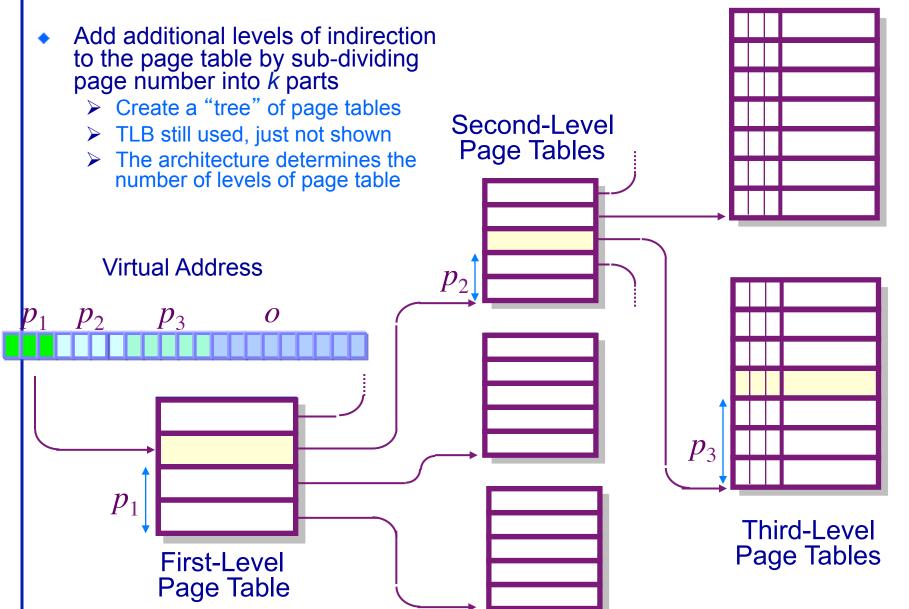
Using TLBs to Speedup Address Translation

- Cache recently accessed page-to-frame translations in a TLB
 - > For TLB hit, physical page number obtained in 1 cycle
 - > For TLB miss, translation is updated in TLB
 - ➤ Has high hit ratio (why?)



Dealing With Large Page Tables

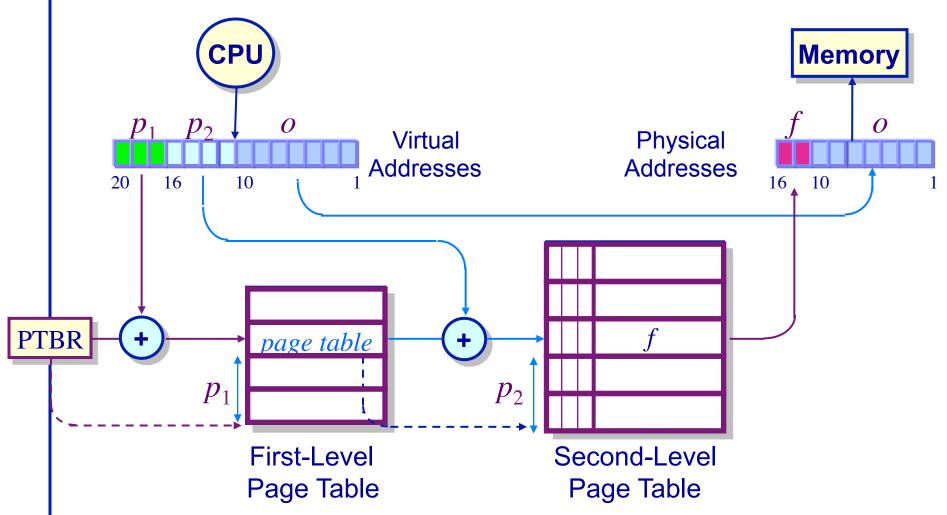
Multi-level paging



Dealing With Large Page Tables

Multi-level paging

Example: Two-level paging



The Problem of Large Address Spaces

- With large address spaces (64-bits) forward mapped page tables become cumbersome.
 - E.g. 5 levels of tables.
- Instead of making tables proportional to size of virtual address space, make them proportional to the size of physical address space.
 - Virtual address space is growing faster than physical.
- Use one entry for each physical page with a hash table
 - > Translation table occupies a very small fraction of physical memory
 - > Size of translation table is independent of VM size
- Page table has 1 entry per virtual page
- Hashed/Inverted page table has 1 entry per physical frame

Virtual Address Translation

Using Page Registers (aka Hashed/Inverted Page Tables)

- Each frame is associated with a register containing
 - > Residence bit: whether or not the frame is occupied
 - Occupier: page number of the page occupying frame
 - Protection bits
- Page registers: an example
 - Physical memory size: 16 MB
 - ➤ Page size: 4096 bytes
 - Number of frames: 4096
 - Space used for page registers (assuming 8 bytes/register): 32 Kbytes
 - ➤ Percentage overhead introduced by page registers: 0.2%
 - ➤ Size of virtual memory: irrelevant

Page Registers

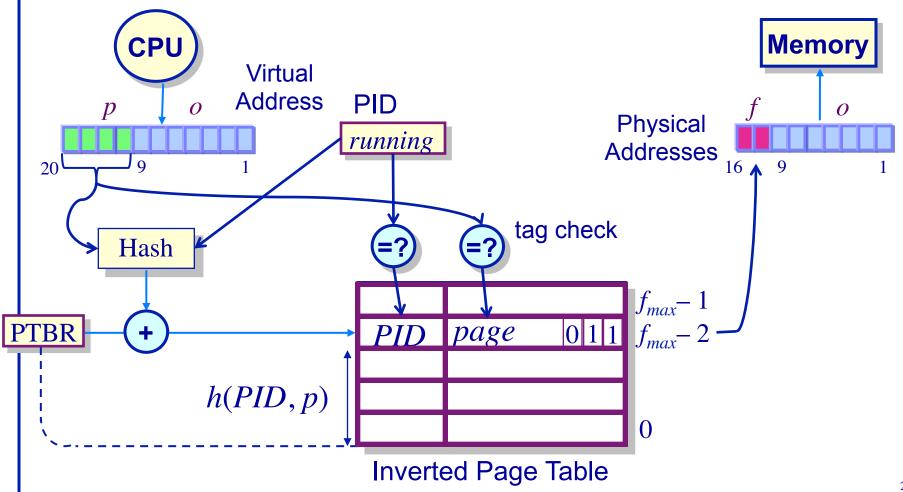
How does a virtual address become a physical address?

- CPU generates virtual addresses, where is the physical page?
 - Hash the virtual address
 - Must deal with conflicts
- TLB caches recent translations, so page lookup can take several steps
 - > Hash the address
 - Check the tag of the entry
 - Possibly rehash/traverse list of conflicting entries
- TLB is limited in size
 - ➤ Difficult to make large and accessible in a single cycle.
 - ➤ They consume a lot of power (27% of on-chip for StrongARM)

Indexing Hashed Page Tables

Using Hash Tables

- Hash page numbers to find corresponding frame number
 - Page frame number is not explicitly stored (1 frame per entry)
 - > Protection, dirty, used, resident bits also in entry



Searching Hahed Page Tables

Using Hash Tables

- Page registers are placed in an array
- Page i is placed in slot f(i) where f is an agreed-upon hash function
- To lookup page i, perform the following:
 - Compute f(i) and use it as an index into the table of page registers
 - Extract the corresponding page register
 - > Check if the register tag contains *i*, if so, we have a hit
 - ➤ Otherwise, we have a miss

Searching Hashed Page Tables

Using Hash Tables (Cont'd.)

- Minor complication
 - ➤ Since the number of pages is usually larger than the number of slots in a hash table, two or more items *may* hash to the same location
- Two different entries that map to same location are said to collide
- Many standard techniques for dealing with collisions
 - Use a linked list of items that hash to a particular table entry
 - Rehash index until the key is found or an empty table entry is reached (open hashing)

Questions

Why use hashed/inverted page tables?

- > A. Forward mapped page tables are too slow.
- ➤ B. Forward mapped page tables don't scale to larger virtual address spaces.
- ➤ C. Inverted pages tables have a simpler lookup algorithm, so the hardware that implements them is simpler.
- ➤ D. Inverted page tables allow a virtual page to be anywhere in physical memory.

Virtual Memory (Paging)

The bigger picture

- A process's VAS is its context
 - Contains its code, data, and stack
- Code pages are stored in a user's file on disk
 - Some are currently residing in memory; most are not
- Data and stack pages are also stored in a file
 - ➤ Although this file is typically not visible to users
 - > File only exists while a program is executing
- OS determines which portions of a process's VAS are mapped in memory at any one time



 References to non-mapped pages generate a page fault

Page fault handling steps:

Processor runs the interrupt handler

OS blocks the running process

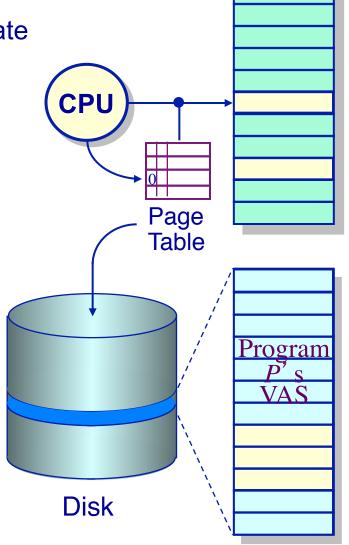
OS starts read of the unmapped page

OS resumes/initiates some other process

Read of page completes

OS maps the missing page into memory

OS restart the faulting process



Virtual Memory Performance

Page fault handling analysis

- To understand the overhead of paging, compute the effective memory access time (EAT)
 - > EAT = memory access time × probability of a page hit + page fault service time × probability of a page fault
- Example:
 - ➤ Memory access time: 60 ns
 - > Disk access time: 25 ms
 - \triangleright Let p = the probability of a page fault
 - \rightarrow EAT = 60(1-p) + 25,000,000p
- To realize an EAT within 5% of minimum, what is the largest value of p we can tolerate?

Virtual Memory Summary

- Physical and virtual memory partitioned into equal size units
- Size of VAS unrelated to size of physical memory
- Virtual pages are mapped to physical frames
- Simple placement strategy
- There is no external fragmentation
- Key to good performance is minimizing page faults

Segmentation vs. Paging

- Segmentation has what advantages over paging?
 - > A. Fine-grained protection.
 - ➤ B. Easier to manage transfer of segments to/from the disk.
 - C. Requires less hardware support
 - > D. No external fragmentation
- Paging has what advantages over segmentation?
 - > A. Fine-grained protection.
 - B. Easier to manage transfer of pages to/from the disk.
 - C. Requires less hardware support.
 - ➤ D. No external fragmentation.