

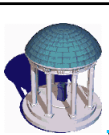
The University of North Carolina at Chapel Hill

COMP 144 Programming Language Concepts
 Spring 2002

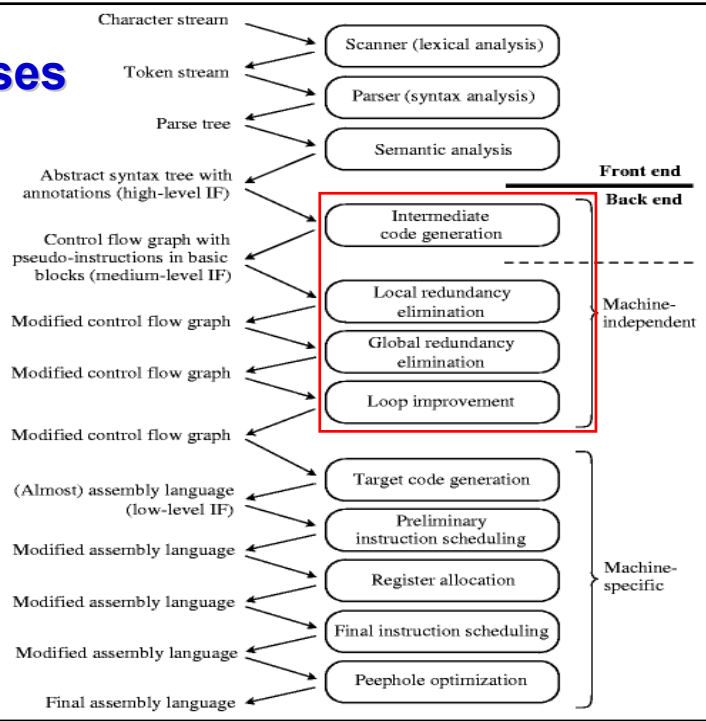
Lecture 35: In-line Expansion and Local Optimization

Felix Hernandez-Campos
 April 19

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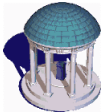
Phases





Subroutine In-line Expansion

- Subroutines may be expanded in-line at the point of the call
 - Rather than use a stack-based calling convention
- In-line expansion saves subroutine overheads and help code improvement
- In-line expansion may be decided by the compiler based on some optimization heuristics
 - *E.g.* short, non-recursive subroutines are always in-lined in some languages



Subroutine In-line Expansion

- In-line expansion can also be *suggested* by the programmer
 - *E.g.* C++

```
inline int max (int a, int b) {  
    return a > b ? a : b;  
}
```
 - *E.g.* Ada

```
function max(a, b : integer) return integer is  
begin  
    if a > b then return a; else return b; end if;  
end max;  
pragma inline (max);
```



Macros and In-line Expansion

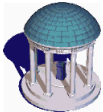
- What is the difference between a macro and a programmer suggested expansion?
 - Optional in the second case
 - Most importantly, in-line expansion is an implementation technique with no effect in program semantics
- E.g.

```
#define MAX(a,b) ((a) > (b) ? (a) : (b))
```

- No type checking
- What happens after `MAX(x++, y++)`?
- The larger argument is incremented twice

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In-line Expansion

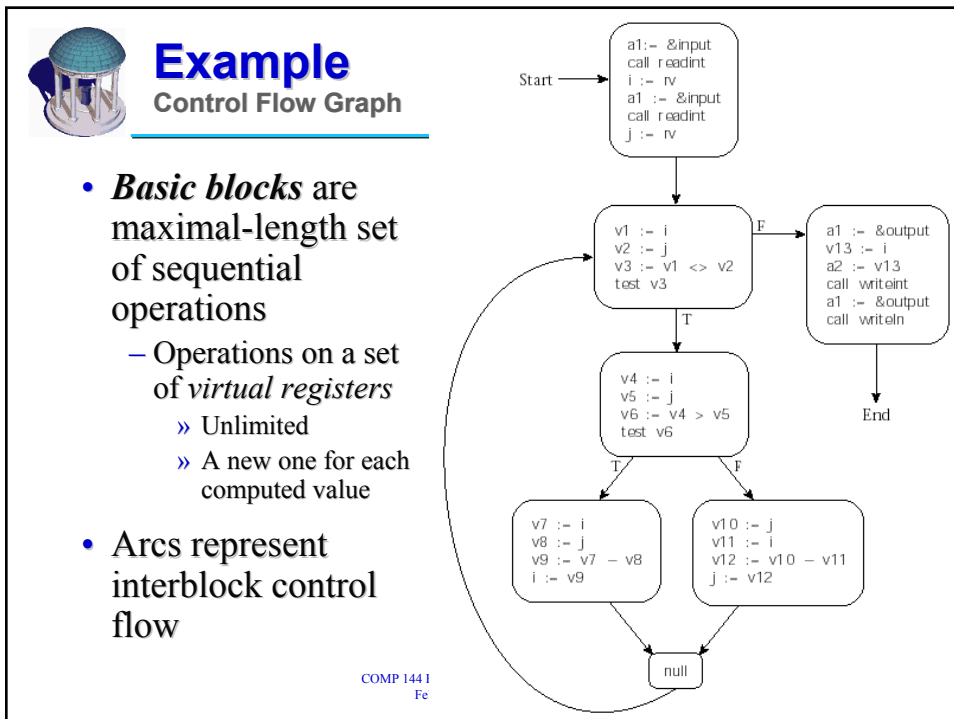
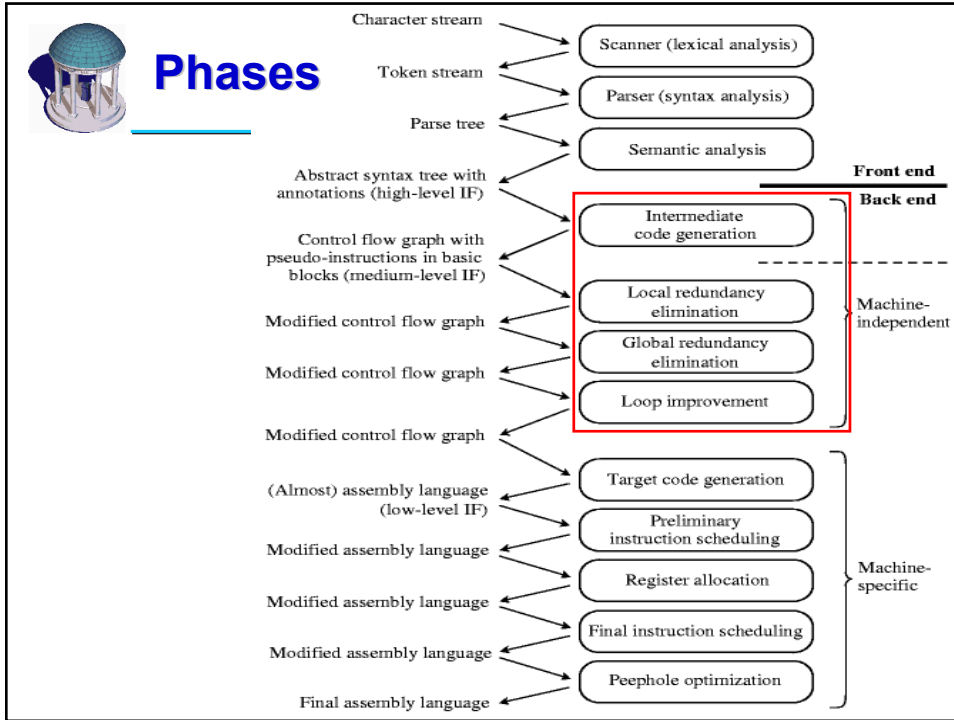
- In-line expansion has some disadvantages
 - Increase in code size
 - It cannot be used with recursive subroutines
- It is sometimes useful to expand the first case in a recursion subroutine
 - *Optimize the common case rule*

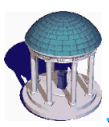
**Most hash chains
are only
one bucket long**

```
range_t bucket_contents (bucket #b, domain_t x)
{
    if (b->key == x)
        return b->val;
    else if (b->next == 0)
        return ERROR;
    else
        return bucket_contents (b->next, x);
}
```

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Redundancy Elimination in Basic Blocks

- We will consider the example on the right
- It computes the binomial coefficients

$$\binom{n}{m}$$

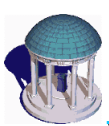
for $0 \leq m \leq n$

- It is based on

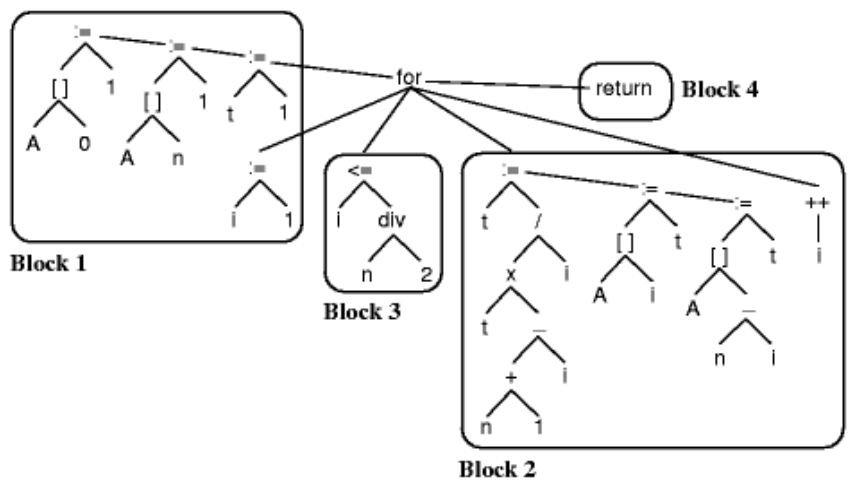
$$\binom{n}{m} = \binom{n}{n-m}$$

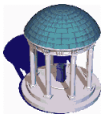
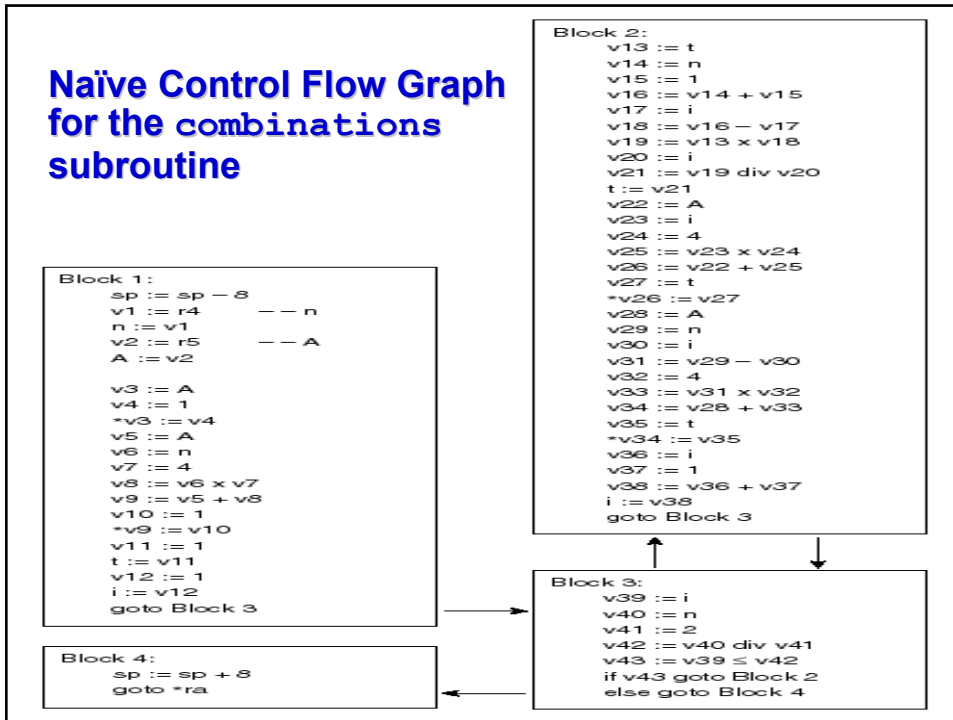
```

combinations (int n, int *A) {
    int i, t;
    A[0] = 1;
    A[n] = 1;
    t = 1;
    for (i = 1; i <= n/2; i++) {
        t = (t * (n+1-i)) / i;
        A[i] = t;
        A[n-i] = t;
    }
}
    
```



Syntax Tree for the combinations subroutine





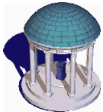
Naïve Control Flow Graph

- Uses virtual registers
 - A new register for each new value
- *ra* is the return address, *fp* is the frame pointer
- *n*, *A*, *I* and *t* perform the appropriate displacement addressing with respect to the stack pointer (*sp*) register
- Parameter passing using *r4* and *r5*



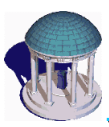
Value Numbering

- How can we eliminate redundant loads and computations?
 - *Expression DAG*
 - *Value numbering*
- In value numbering, the compiler assigns the same name (*i.e.*, *number*) to any two or symbolically equivalent computations (*i.e.*, *values*)
- A dictionary is used to keep track of values that have already been loaded or computed



Value Numbering

- If a value is already in a register, reuse that register
 - *E.g.*, the load instruction can be eliminated $v_i := x$ if the value x is already in register v_j
 - » *Replace all uses of v_i by v_j*
- Similarly, we can get rid of small constants using immediate value



Value Numbering

- In $v_i := v_j \text{ op } v_k$, we can use constant folding if the values in v_j and v_k are known to be constants
 - Local constant folding and constant propagation
 - At the same time, strength reduction and useless abstraction elimination
- A key that combine the registers and the operator is used to keep track of the previous operation in the dictionary

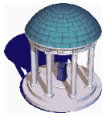
Control Flow Graph for combinations after *local redundancy elimination* and *strength reduction*

```
Block 1:  
sp := sp - 8  
v1 := r4      -- n  
n := v1  
v2 := r5      -- A  
A := v2  
*v2 := 1  
v8 := v1 << 2  
v9 := v2 + v8  
*v9 := 1  
t := 1  
i := 1  
goto Block 3
```

```
Block 4:  
sp := sp + 8  
goto *ra
```

```
Block 2:  
v13 := t  
v14 := n  
v16 := v14 + 1  
v17 := i  
v18 := v16 - v17  
v19 := v13 x v18  
v21 := v19 div v17  
v22 := A  
v25 := v17 << 2  
v26 := v22 + v25  
*v26 := v21  
v31 := v14 - v17  
v33 := v31 << 2  
v34 := v22 + v33  
*v34 := v21  
v38 := v17 + 1  
t := v21  
i := v38  
goto Block 3
```

```
Block 3:  
v39 := i  
v40 := n  
v42 := v40 >> 1  
v43 := v39 ≤ v42  
if v43 goto Block 2  
else goto Block 4
```

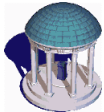



Reading Assignment

- Read Scott
 - Sect. 8.2.3
 - Ch. 13.3

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Peephole Optimization Common Techniques

Elimination of redundant loads and stores

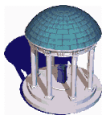
$r2 := r1 + 5$		$r2 := r1 + 5$
$i := r2$		$i := r2$
$r3 := i$	becomes	$r4 := r2 \times 3$
$r4 := r3 \times 3$		

Constant folding

$r2 := 3 \times 2$	becomes	$r2 := 6$
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Peephole Optimization Common Techniques

Constant propagation

$r2 := 4$
 $r3 := r1 + r2$
 $r2 := \dots$

becomes

$r2 := 4$
 $r3 := r1 + 4$
 $r2 := \dots$

and then

$r3 := r1 + 4$
 $r2 := \dots$

$r2 := 4$
 $r3 := r1 + r2$
 $r3 := *r3$

becomes

$r3 := r1 + 4$
 $r3 := *r3$

and then

$r3 := *(r1+4)$

$r1 := 3$
 $r2 := r1 \times 2$

becomes

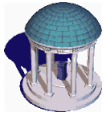
$r1 := 3$
 $r2 := 3 \times 2$

and then

$r1 := 3$
 $r2 := 6$

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Peephole Optimization Common Techniques

Copy propagation

$r2 := r1$
 $r3 := r1 + r2$
 $r2 := 5$

becomes

$r2 := r1$
 $r3 := r1 + r1$
 $r2 := 5$

and then

$r3 := r1 + r1$
 $r2 := 5$

Strength reduction

$r1 := r2 \times 2$ becomes $r1 := r2 + r2$ or $r1 := r2 \ll 1$

$r1 := r2 / 2$ becomes $r1 := r2 \gg 1$

$r1 := r2 \times 0$ becomes $r1 := 0$

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Peephole Optimization Common Techniques

Elimination of useless instructions

$r1 := r1 + 0$

$r1 := r1 \times 1$