

## Physical Dimensions and Units

Physical behavior is quantitatively represented by formulas which model relationships between physical quantities. All meaningful physical quantities comprise products and/or quotients of a limited number of types of basic **dimensions**. All *mechanical* and *electrical* quantities can be composed of just four dimensional types, mass [M], length [L], time [T], and charge [Q].

For example, a physical equation representing velocity  $v$  in terms of distance  $d$  traveled in time  $t$  is,  $v = d/t$ . Obviously the dimensions of  $d$  and  $t$  are [L] and [T], respectively. The units of  $v$  are reckoned by a *dimensional* equation,  $[L T^{-1}] = [L]/[T]$ , of the same algebraic form as the physical equation. It is sometimes convenient to interleave these two equations, as in the following example for the area  $A$  of a circle of radius  $r$ ,  $A[L^2] = \pi[1] \times r^2[L]^2$ . The **dimensionless constant**  $\pi$  is dimensionally represented as [1].

Physically meaningful formulas may *never* contain sums of different dimensions. For example, one might argue that *FatCats*[cat – fish] = 4[cat] – 6[fish] gives some very satisfied kitties, but from a physically quantitative viewpoint, it makes no sense whatsoever!

Dimensional types are quantified by **units**. For example, a length can be measured in centimeters, feet, furlongs, etc. These are all the same kind of dimension, namely [L], but the units differ. Units can be thought of as values assigned to dimensions in dimensional equations. Conversion between different units is done using dimensionless constants. For example, the distance  $d[L] = 1500[\text{ft}]$  in miles is  $d[\text{mi}] = 1500[\text{ft}] \cdot 1.89 \times 10^{-4}[\text{mi}/\text{ft}] = 0.284[\text{mi}]$ , where  $1.89 \times 10^{-4}[\text{mi}/\text{ft}] = 1[\text{mi}]/5280[\text{ft}]$  is dimensionless since  $[L/L] = [1]$ .

A universally accepted coherent system of units is the *Système International d'Unités* (SI). A useful electrical/mechanical subset of the SI units is summarized in the table below.

| Quantity        | SI Units & Abbrev. | dimensions                | commonsymbol |
|-----------------|--------------------|---------------------------|--------------|
| Mass            | kilogram [kg]      | [M]                       | $m$          |
| Length          | meter [m]          | [L]                       | (various)    |
| Time            | second [s]         | [T]                       | $t$          |
| Frequency       | Hertz [Hz]         | $[T^{-1}]$                | $f$          |
| Force           | Newton [N]         | $[M L T^{-2}]$            | $F$          |
| Energy          | Joule [J]          | $[M L^2 T^{-2}]$          | $E$          |
| Power           | Watt [W]           | $[M L^2 T^{-3}]$          | $P$          |
| Electric charge | Coulomb [C]        | [Q]                       | $q$          |
| Voltage         | Volt [V]           | $[M L^2 T^{-2} Q^{-1}]$   | $v, V$       |
| Current         | Ampere [A]         | $[T^{-1} Q]$              | $i, I$       |
| Resistance      | Ohm [ $\Omega$ ]   | $[M L^2 T^{-1} Q^{-2}]$   | $R$          |
| Inductance      | Henry [H]          | $[M L^2 Q^{-2}]$          | $L$          |
| Conductance     | Siemen [S]         | $[M^{-1} L^{-2} T Q^2]$   | $G$          |
| Capacitance     | Farad [F]          | $[M^{-1} L^{-2} T^2 Q^2]$ | $C$          |

Many physical models relate the behavior of two quantities as fixed ratios known as **dimensional constants**. For example, the spring constant  $k[M T^{-2}] = -f[M L T^{-2}]/x[L]$  relates the force  $f$  exerted by a spring in opposition to being deflected a distance  $x$ .