Two examples of degree-driven algorithm design

David L. Millman

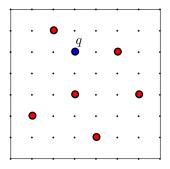
December 22, 2009

Examples:

- Reduced Precision Voronoi w/ Jack Snoeyink
- Ø Discrete Voronoi w/ Timothy M. Chan and Jack Snoeyink



Goal

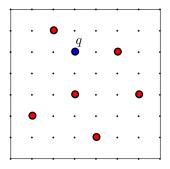


Given sites $S = \{s_1, \ldots, s_n\}$ and query points on a $U \times U$ grid U.

Compute

a data structure supporting post office queries in $O(\log n)$ time and double precision

Goal

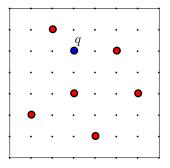


Given sites $S = \{s_1, \ldots, s_n\}$ and query points on a $U \times U$ grid U.

Compute

using **less than** quadruple precision, a data structure supporting post office queries in $O(\log n)$ time and double precision

Examples



Given sites $S = \{s_1, \ldots, s_n\}$ and query points on a $U \times U$ grid U.

Compute

using **less than** quadruple precision, a data structure supporting post office queries in $O(\log n)$ time and double precision

Results, assuming $O(n \log n) < O(U^2)$

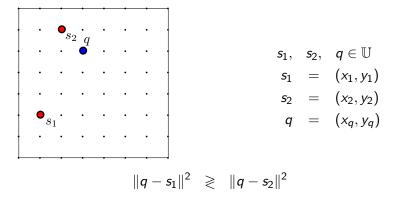
- RP-Voronoi 3x precision, O(n log Un) expected time
- 2 Discrete Voronoi 2x precision, $O(U^2)$ expected time

Techniques for implementing geometric algorithms with finite precision computer arithmetic:

- Rely on machine precision (+epsilon)
- Exact Geometric Computation [Y97]
- Arithmetic Filters [FW93][DP99]
- Adaptive Predicates [P92][S97]
- Topological Consistency [SI92]
- Degree-driven algorithm design [LPT99]

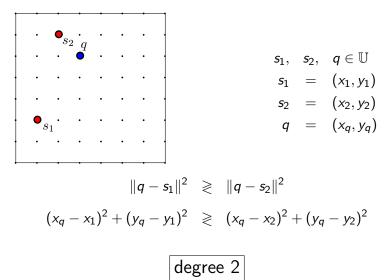
Analyzing Precision[LPT99]

Is q closer to s_1 ?



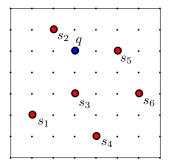
Analyzing Precision[LPT99]

Is q closer to s_1 ?



Post Office Query

Which site is q closest to?

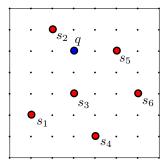


Given Sites $S = \{s_1, \ldots, s_n\}$ and query point q with $s_i, q \in \mathbb{U}$

Determine The site of *S* closest to q

Post Office Query

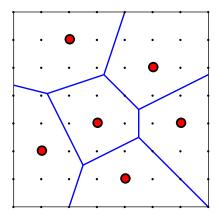
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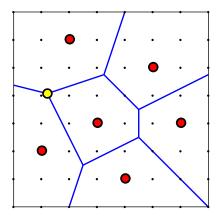
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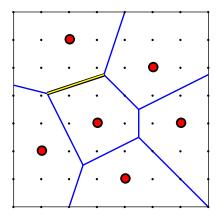
	Preprocess		Query	
	Alg	Time	Alg	Time
Brute force	-	-	deg 2	<i>O</i> (<i>n</i>)
Voronoi diagram	deg 4	$O(n \log n)$	deg 6	$O(\log n)$
Imp Voronoi [LPT99]	deg 5	$O(n \log n)$	deg 2	$O(\log n)$



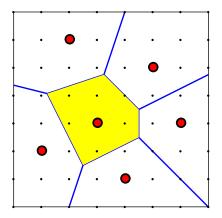
- Voronoi vertices
- Voronoi edges
- Voronoi cell
- Voronoi diagram
- Trapezoidation



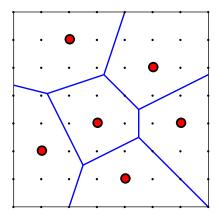
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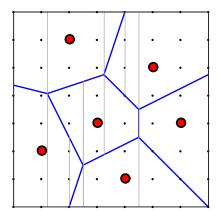
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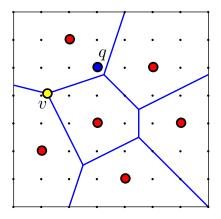
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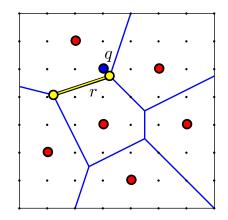
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Predicates and Their Precision

x-node:



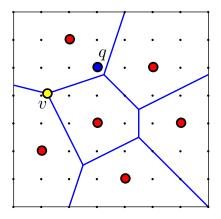
Is x_q left/right of vertex x_v ? degree 3 y-node:



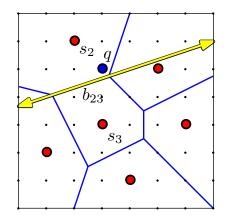
Is q above/below segment r? degree 6

Predicates and Their Precision

x-node:



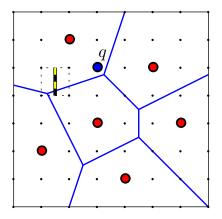
Is x_q left/right of vertex x_v ? degree 3 y-node:



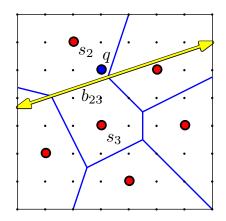
Is q closer to s_2 or s_3 ? degree 2

Predicates and Their Precision

x-node:

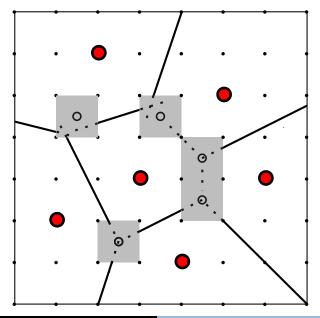


ls x_q left/right of g.c. containing v? degree 1 y-node:

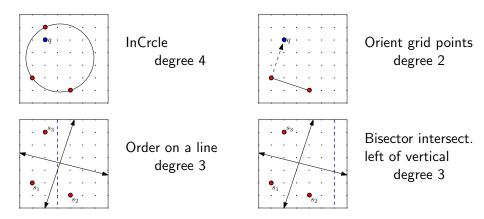


Is q closer to s_2 or s_3 ? degree 2

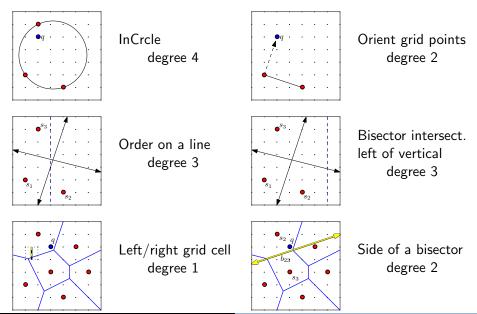
Implicit Voronoi Diagram[LPT99]



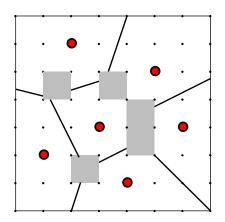
Predicate Degree



Predicate Degree



Post Office Queries with Min Precision



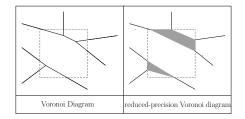
Given Sites $S = \{s_1, s_2, \dots, s_n\} \subset \mathbb{U}$

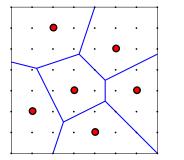
Construct

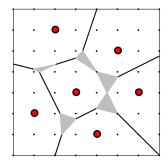
Implicit Voronoi with minimum precision.

Note

Precision < degree 4 precludes computing the Voronoi diagram. Replace connected subtrees of Voronoi edges inside a cell with their convex hulls.







Construction (preview)

Given *n* sites in \mathbb{U} .

RP-Voronoi

Rand inc construction of the RP-Voronoi of n sites in \mathbb{U} .

- Time: $O(n \log(Un))$ expected
- Space: O(n) expected
- Precision: degree 3

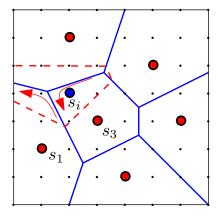
Implicit Voronoi

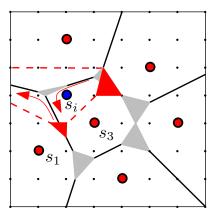
Construct LPT's implicit Voronoi from RP-Voronoi.

- Time: *O*(*n*)
- Space: O(n) expected
- Precision: degree 3

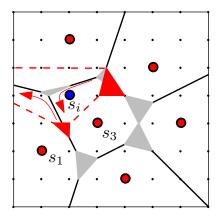
Rand Inc Construction

Invariant: Maintain RP-Voronoi as each new site is added. **Update step:** Extension of [SI92], walk the deleted tree.





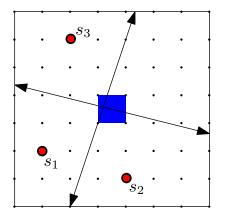
Operations for RIC



Operations:

- identify the grid cell containing a bisector intersection.
- determine the next edge in the tree walk.

Bisector Intersection



Time: $O(\log U)$ Precision: degree 3

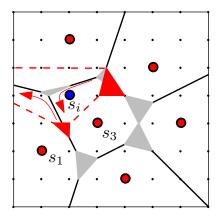
Given

Three sites s_1 , s_2 and s_3 .

Find

Grid cell containing the intersection of bisectors b_{12} and b_{13} .

Operations for RIC

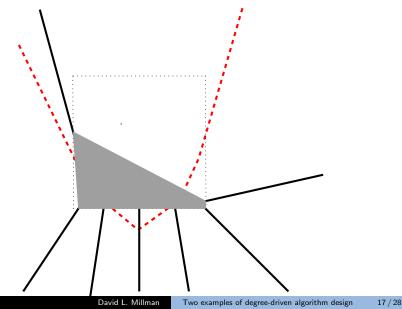


Operations:

- identify the grid cell containing a bisector intersection.
 - Time: *O*(log *U*) Precision: degree 3
- determine the next edge in the tree walk.

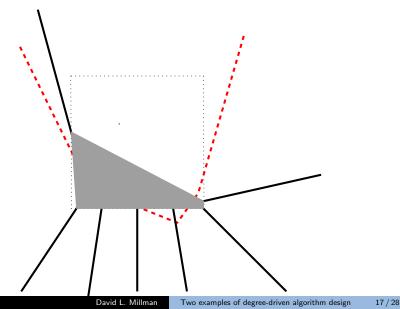
Next Edge of the Tree Walk

Where do we walk once we have found an intersection?



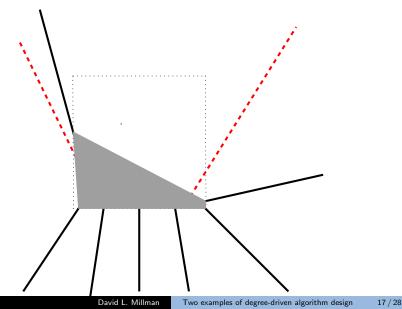
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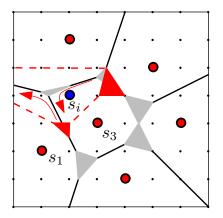


Next Edge of the Tree Walk

Where do we walk once we have found an intersection?



Operations for RIC



Operations:

• identify the grid cell containing a bisector intersection.

Time: $O(\log U)$ Precision: degree 3

• determine the next edge in the tree walk.

Time: $O(\log n)$ Precision: degree 3 Update step to add a new site s_i

- (1) Find cell containing s_i
- (2) Identify bisectors and cells in the new cell of s_i
- (3) Walk tree inside cell of s_i
 - (a) Binary search bisector for crossing
 - (b) Compute grid intersection with cell s_i

RIC Facts for Voronoi

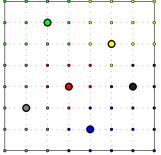
- Creates Θ(n) vertices expected
- Point location takes $\Theta(n \log n)$ expected

Charging scheme

Binary searchers for (3a) $O(\log U)$ and (3b) $O(\log n)$ charged to vertex creation.

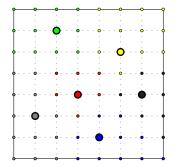
Therefore, It takes O(n) space and $O(n(\log n + \log U))$ time to build the reduced-precision Voronoi diagram of *n* sites on a grid of size *U* with degree 3.

Discrete Voronoi Diagram



Given A grid of size U and Sites $S = \{s_1, \ldots, s_n\} \subset \mathbb{U}$

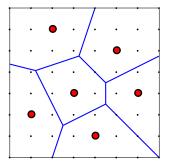
Discrete Voronoi Diagram



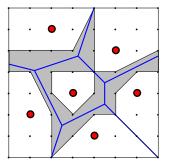
Given A grid of size U and Sites $S = \{s_1, \ldots, s_n\} \subset \mathbb{U}$

Label Each grid point of $\mathbb U$ with the closest site of S

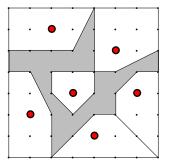
	Alg	Time
Brute Force	deg 2	$O(nU^2)$
Query the Voronoi diagram	deg 4	$O(U^2 \log n)$
Nearest Neighbor Trans. [B90]	deg 4	$O(nU^2)$ $O(U^2 \log n)$ $O(U^2)$
Discrete Voronoi diagram [C06]	deg 3	$O(U^2)$
GPU Hardware [H99]	-	$\Theta(nU^2)$



- \bullet Partition of $\mathbb U$
- *n* convex polygons
 {C(s₁),...,C(s_n)}

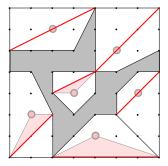


- \bullet Partition of $\mathbb U$
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- Where $C(s_i)$ is the convex hull of the grid points in the Voronoi cell of s_i



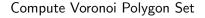
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• Grey gaps



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- Grey gaps
- Proxy segment

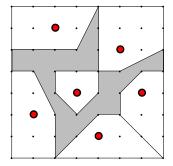






Compute trapezoid graph of proxies





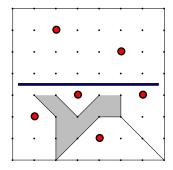
Compute Voronoi Polygon Set

- Time: $O(U^2)$ expected time
- Space: $O(n \log U)$
- Precision: degree 2



Compute trapezoid graph of proxies





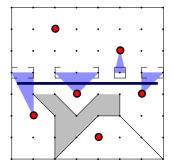
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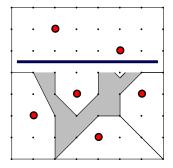
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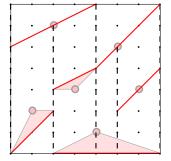


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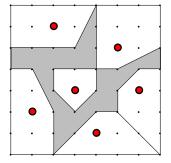
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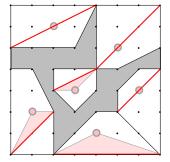
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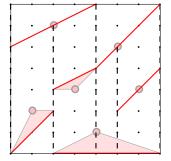
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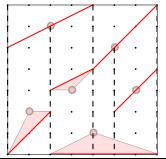




Compute Voronoi Polygon Set



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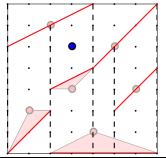
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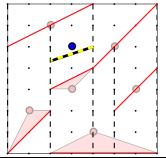
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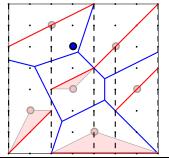
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Compute Voronoi Polygon Set



Compute trapezoid graph of proxies



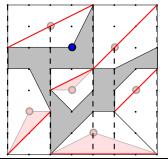
- Time: $O(\log n)$ expected
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Compute Voronoi Polygon Set



Compute trapezoid graph of proxies



- Time: $O(\log n)$ expected
- Precision: degree 2

Results

Assuming $O(n \log n) < O(U^2)$

Compute Voronoi Polygon Set

- Time: $O(U^2)$ expected time
- Space: $O(n \log U)$ and O(n) for proxies only
- Precision: degree 2

Query Post Office Structure

- Time: $O(\log n)$ expected
- Precision: degree 2

Compute 2D discrete Voronoi

- Time: $O(U^2)$ expected time.
- Space: O(n+U)
- Precision: degree 2

Construct degree 2 post office query structure, called D2-Voronoi

- Time: $O(n \log n \log U)$ expected
- Space: O(n) expected
- Precision: degree 2
- Query time: $O(\log n)$
- Query precision: degree 2

Optimized implementations and experiments for ...

• RP-Voronoi, Discrete Voronoi, D2-Voronoi

Can we ...

- Remove additive log U factor in RP-Voronoi?
- Remove multiplicative log U factor in D2-Voronoi?
- Or, show some lower bound inherent in reduced precision?
- generalize to higher dimension?
- treat precision as a limited resource (like time and space) when solving other algorithmic problems?

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Thank you!

Contact information

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