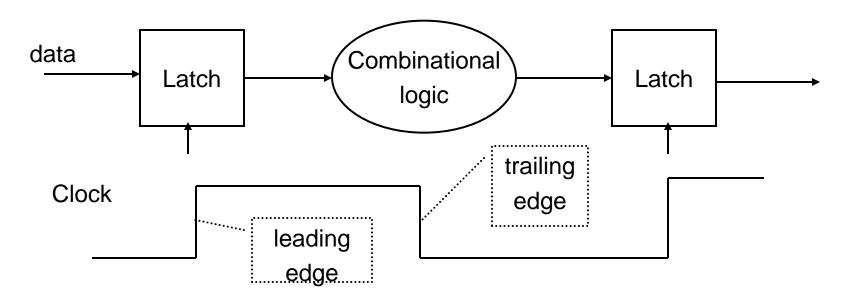
Control & Execution

Finite State Machines for Control

MIPS Execution

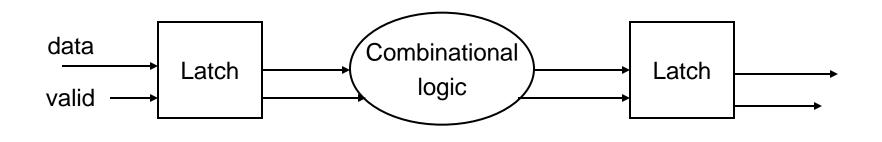
Synchronous Systems



On the leading edge of the clock, the input of a latch is transferred to the output and held.

We must be sure the output of the combinational logic has *settled* before the next leading clock edge.

Asynchronous Systems



No clock!

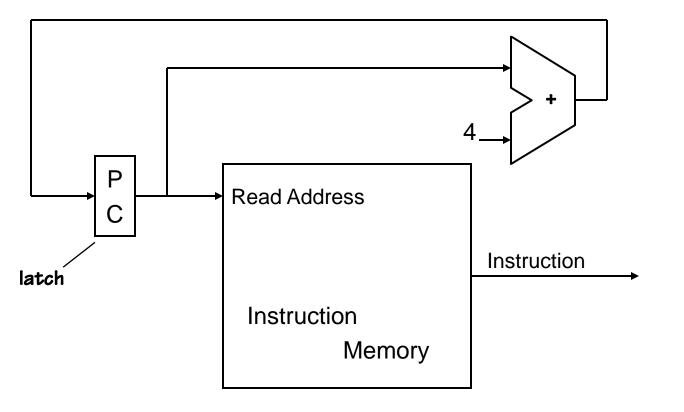
The data carries a "valid" signal along with it

System goes at greatest possible speed.

Only "computes" when necessary.

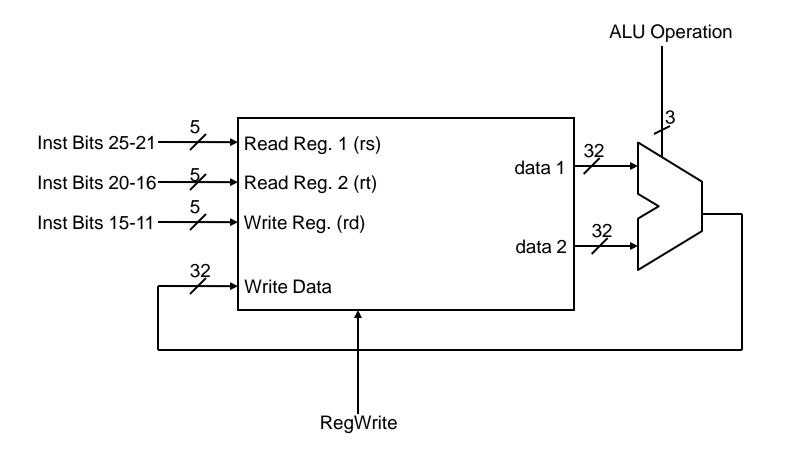
Everything we look at in this class will be synchronous

Fetching Sequential Instructions

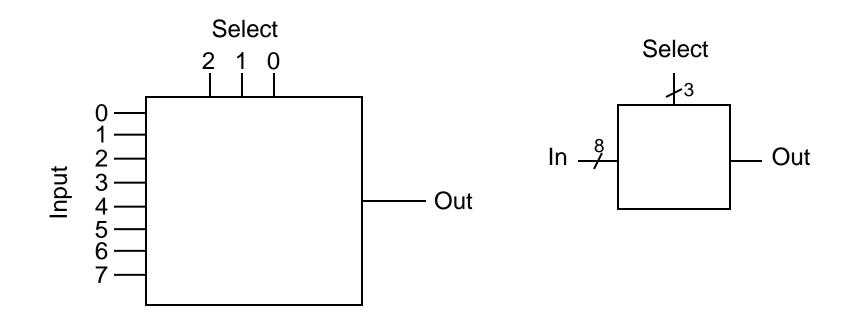


How about branch?

Datapath for R-type Instructions

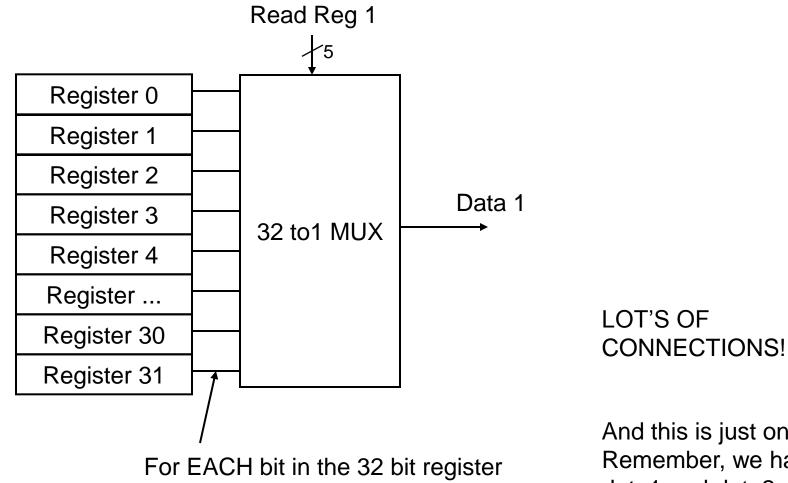


MUX Blocks



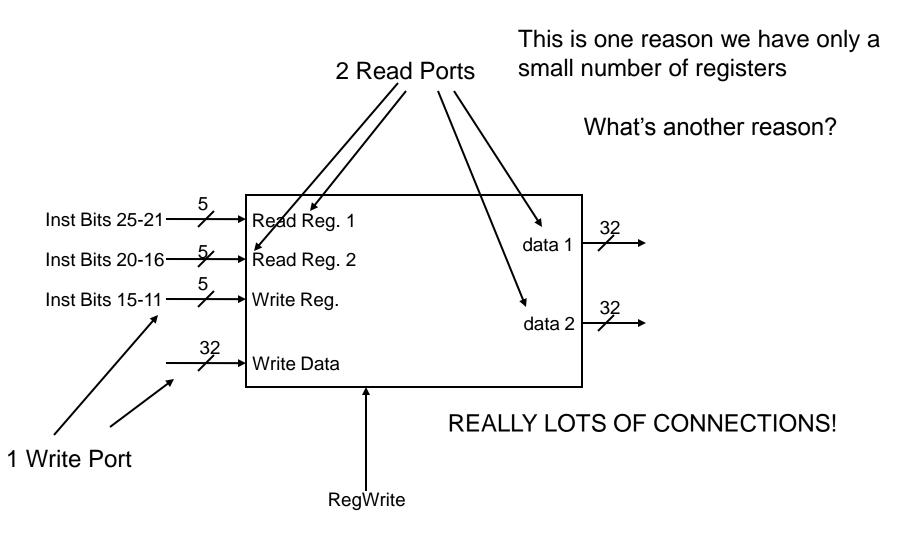
The select signal determines which of the inputs is connected to the output

Inside there is a 32 way MUX per bit



And this is just one port! Remember, we have data1 and data2 coming out of the register file!

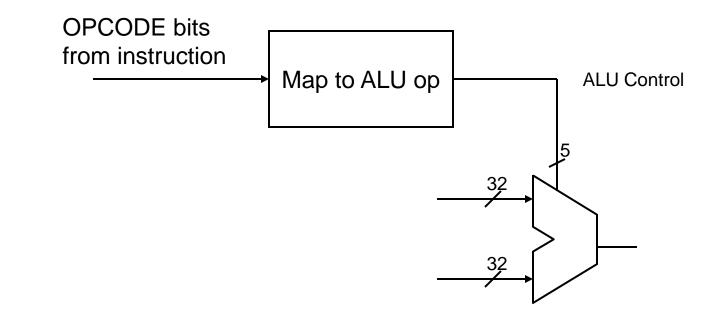
Our Register File has 3 ports



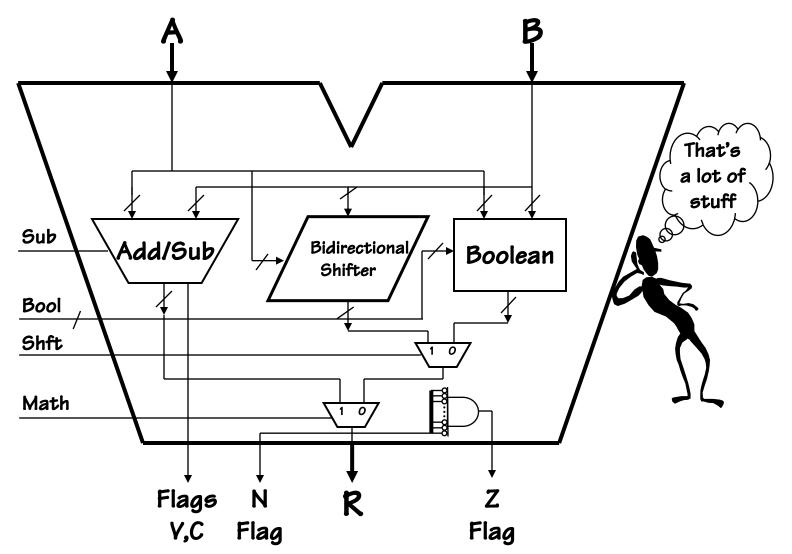
Implementing Logical Functions

Suppose we want to map M input bits to N output bits

For example, we need to take the OPCODE field from the instruction and determine what OPERATION to send to the ALU.



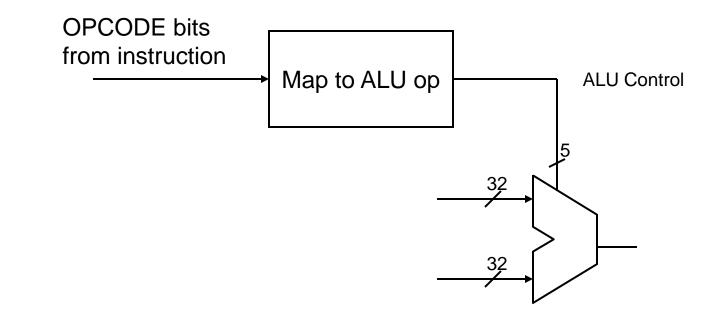
Remember our ALU?



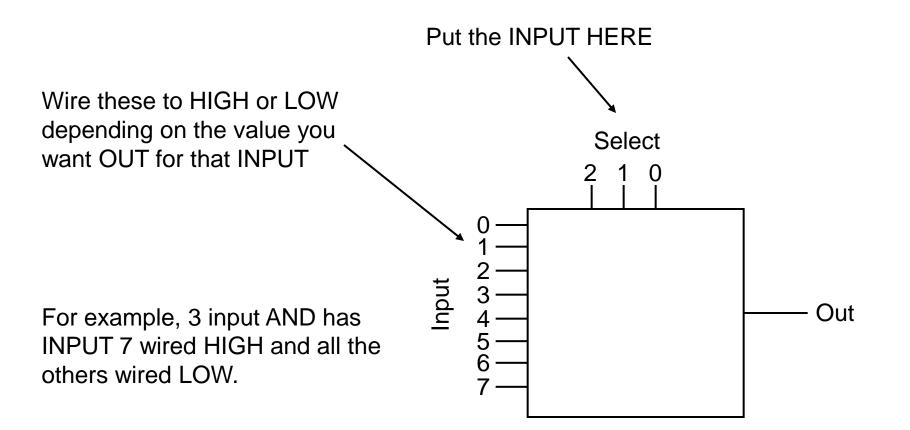
Implementing Logical Functions

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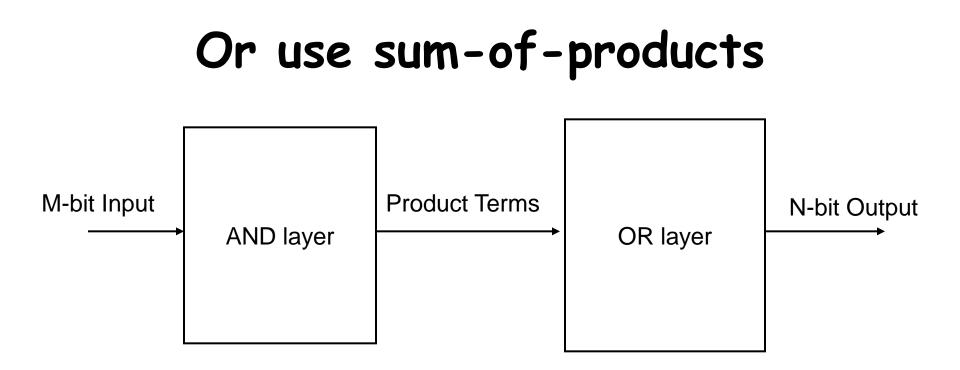


We can get 1 bit out with a MUX



Or use a ROM





Think of the SUM of PRODUCTS form.

The AND layer generates the products of various input bits

The OR layer combines the products into various outputs

You could also use two NAND layers instead

Could be implemented using Boolean gates, or also using a "programmable logic array" (PLA) [similar to a PROM, but both the AND and the OR parts are programmable].

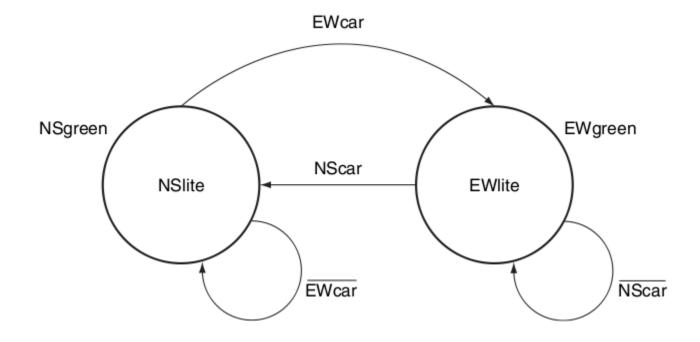
Finite State Machines

- •A set of STATES
- •A set of INPUTS
- •A set of OUTPUTS

•A function to map the STATE and the INPUT into the next STATE and an OUTPUT

Remember automata?

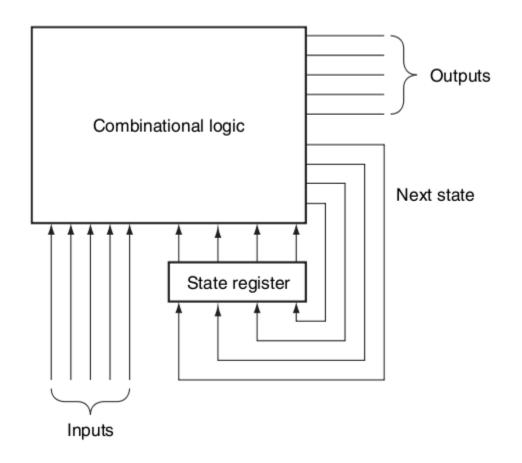
Traffic Light Controller



Controller State Table

Inputs			Outputs		
State	NScar	EWcar	Next	NSlight	EWlight
NSgreen	0	0	NSgreen	1	0
NSgreen	0	1	EWgreen	0	1
NSgreen	1	0	NSgreen	1	0
NSgreen	1	1	EWgreen	0	1
EWgreen	0	0	EWgreen	0	1
EWgreen	0	1	EWgreen	0	1
EWgreen	1	0	NSgreen	1	0
EWgreen	1	1	NSgreen	1	0

Implementing an FSM



FSM Example: Recognizing Numbers

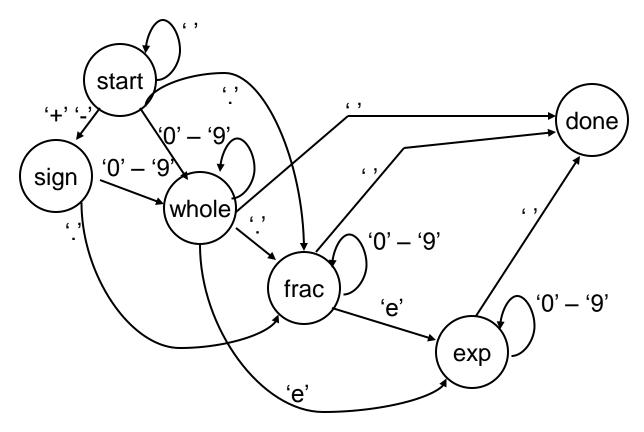
Recognize the regular expression for floating point numbers

```
[\t]^{*} [-+]?[0-9]^{*}(. [0-9]^{*})? (e[-+]?[0-9]+)?
```

Examples: +123.456e23 .456 1.5e-10 -123

"a" matches itself
"[abc]" matches one of a, b, or c
"[a-z]" matches one of a, b, c, d, ..., x, y, or z
"0*" matches zero or more 0's ("", "0", "00", "0000")
"Z?" matches zero or 1 Z's

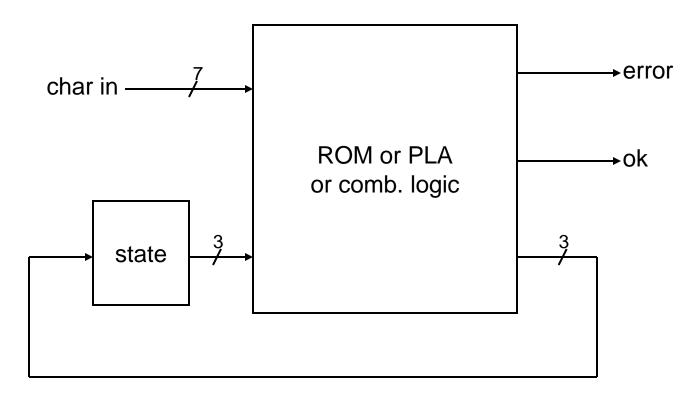
FSM Diagram



FSM Table

- IN : STATE → NEW STATE
- i': start \rightarrow start $(0' | (1' | ... | (9' : start \rightarrow whole))$ '+' | '-' : start \rightarrow sign \therefore start \rightarrow frac $(0' | (1' | ... | (9' : sign \rightarrow whole))$ '.': sign \rightarrow frac $(0' | (1' | ... | (9' : whole \rightarrow whole))$ \therefore whole \rightarrow frac '': whole \rightarrow done 'e': whole $\rightarrow \exp$
- 'e' : frac \rightarrow exp $(0' | (1' | \dots | (9') : \text{frac} \rightarrow \text{frac})$ '': frac \rightarrow done $(0' | (1' | \dots | (9' : exp \rightarrow exp))$ '': exp \rightarrow done STATE ASSIGNMENTS start = 0 = 000sign = 1 = 001whole = 2 = 010frac = 3 = 011exp = 4 = 100done = 5 = 101error = 6 = 110

FSM Implementation



- Our ROM has:
- •10 inputs
- •5 outputs

FSM Summary

- With JUST a register and some logic, we can implement complicated sequential functions like recognizing a FP number.
- This is useful in its own right for compilers, input routines, etc.
- The reason we're looking at it here is to see how designers implement the complicated sequences of events required to implement instructions
- Think of the OP-CODE as playing the role of the input character in the recognizer. The character AND the state determine the next state (and action).

Five Execution Steps

- 1. Instruction Fetch
- 2. Instruction Decode and Register Fetch
- 3. Execution, Memory Address Computation, or Branch Completion
- 4. Memory Access or R-type instruction completion
- 5. Memory Read Completion

INSTRUCTIONS TAKE FROM 3 - 5 CYCLES! An FSM looks at the op-code to determine how many...

Step 1: Instruction Fetch

Use PC to get instruction and put it in the Instruction Register. Increment the PC by 4 and put the result back in the PC. Can be described succinctly using RTL "Register-Transfer Language"

IR = Memory[PC]; IR is "Instruction Register"
PC = PC + 4;

Step 2: Instruction Decode and Register Fetch

Read registers rs and rt in case we need them Compute the branch address in case the instruction is a branch

RTL:

```
A = Reg[IR[25-21]];
B = Reg[IR[20-16]];
ALUOut = PC + (sign-extend(IR[15-0]) << 2);</pre>
```

We aren't setting any control lines based on the instruction type (we are busy "decoding" it in our control logic)

Step 3 (instruction dependent)

ALU is performing one of three functions, based on instruction type

Memory Reference: ALUOut = A + sign-extend(IR[15-0]);

R-type: ALUOut = A op B;

Branch:

if (A==B) PC = ALUOut;

Step 4 (R-type or memory-access)

Loads and stores access memory

R-type instructions finish

Reg[IR[15-11]] = ALUOut;

Step 5 Memory Read Completion

Reg[IR[20-16]] = MDR;

Summary:

	Action for R-type	Action for memory-reference	Action for	Action for		
Step name	instructions	instructions	branches	jumps		
Instruction fetch	IR = Memory[PC]					
		PC = PC + 4				
Instruction	A = Reg [IR[25-21]]					
decode/register fetch	le/register fetch B = Reg [IR[20-16]]					
	ALUOut = PC + (sign-extend (IR[15-0]) << 2)					
Execution, address	ALUOut = A op B	ALUOut = A + sign-extend	if (A ==B) then	PC = PC [31-28] II		
computation, branch/		(IR[15-0])	PC = ALUOut	(IR[25-0]<<2)		
jump completion						
Memory access or R-type	Reg [IR[15-11]] =	Load: MDR = Memory[ALUOut]				
completion	ALUOut	or				
		Store: Memory [ALUOut] = B				
Memory read completion		Load: Reg[IR[20-16]] = MDR				