## Core-stateless Guaranteed Throughput Networks\*

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Abstract — End-to-end throughput guarantee is an important service semantics that network providers would like to offer to their customers. A network provider can offer such service semantics by deploying a network where each router employs a fair packet scheduling algorithm. Unfortunately, these scheduling algorithms require every router to maintain per-flow state and perform perpacket flow classification; these requirements limit the scalability of the routers. In this paper, we propose the *Core-stateless Guaranteed Throughput (CSGT)* network architecture—the first workconserving architecture that, without maintaining per-flow state or performing per-packet flow classification in core routers, provides to flows throughput guarantees that are within an additive constant of what is attained by a network of core-stateful fair routers.

## 1 Introduction

With the commercialization of the Internet, there is a significant incentive for network service providers to export richer service semantics ---with respect to end-to-end delay and throughput guarantees- to customers. Over the past decade, several packet scheduling algorithms that enable a network to offer such richer semantics have been proposed [2, 6, 9, 19]. A network can, for instance, provide end-to-end delay guarantees by employing Virtual Clock [20] and Delay Earliest-Due-Date (Delay EDD) [14, 18] scheduling algorithms; and delay-cum-throughput guarantees by employing fair packet scheduling algorithms --such as Weighted Fair Queuing(WFQ) [6, 12], Start-time Fair Queuing (SFQ) [9], and Self-clocked Fair Queuing (SCFQ) [7]- in routers. Unfortunately, these scheduling algorithms require every router to maintain per-flow state and perform per-packet flow classification; these requirements limit the scalability of the routers, especially routers in the core of the network that may carry a very large number of flows.

The topic of designing scalable network architectures that can export to flows<sup>1</sup> rich service semantics, but without maintaining per-flow state or performing per-packet flow classification in core routers, has received considerable attention in the recent past [10, 17, 21]. For instance, the Core-stateless Jitter Virtual Clock (CJVC) scheduling algorithm [17] and the class of Core-stateless Guaranteed Rate (CSGR) algorithms [10] enable a network to provide end-to-end delay guarantees similar to their core-stateful counterparts. CJVC also provides end-to-end throughput guarantees, but at the expense of making the network non-work-conserving. There have also been attempts at designing core-stateless versions of *fair* scheduling algorithms [4, 5, 13, 16]. Most of these attempts only provide *statistical* fairness at large time-scales; they do not provide any fairness or throughput guarantees for Harrick M. Vin Department of Computer Sciences University of Texas at Austin

short-lived flows or for short intervals of interest in long-lived flows.

In this paper, we propose the Core-stateless Guaranteed Throughput (CSGT) network architecture—the *first* workconserving network architecture that provides throughput guarantees to flows over finite time-scales, but without maintaining per-flow state in core routers. We develop the architecture in two steps. First, we show that for a network to provide end-to-end throughput guarantees, it must also provide end-to-end delay guarantees. Second, we demonstrate that two simple mechanisms —tag re-use and source rate control— when integrated with a work-conserving, corestateless network that provides end-to-end delay guarantees, lead to the design of a CSGT network that provides end-toend throughput bounds within an *additive constant* of that attained by a core-stateful network of fair servers.

The rest of this paper is organized as follows. In Section 3, we formulate the problem of providing end-to-end throughput guarantees. In Section 4, we present our CSGT network architecture, and derive bounds on the end-to-end throughput. Section 5 discusses deployment considerations. We summarize our contributions in Section 6.

# 2 Notation and Assumptions

Throughout this paper, we use the following symbols and notations.

$\sim^k$		the $k^{th}$ packet of flow $f$
$p_f$	•	
$a_{f,j}^k$	:	arrival time of $p_f^k$ at node $j$ on its path
$d_{f,j}^k$	:	departure time of $p_f^k$ from node $j$
$l_f^k$	:	length of packet $p_f^k$
$r_f$	:	rate reserved for flow $f$
$\pi_j$	:	upper bound on propagation delay of
		the link connecting node $j$ and $(j + 1)$
$C_j$	:	outgoing link capacity at node $j$

*H* denotes the number of routers along the path of flow *f*. The source of flow *f* is connected to router 1 and the destination is connected to router *H*. A source is said to transmit packets *at least at its reserved rate*  $r_f$ , if  $a_{f,1}^k \leq a_{f,1}^{k-1} + \frac{l_f^{k-1}}{r_f}$ . The  $k^{th}$  packet,  $p_f^k$ , transmitted from the source, is said to have a *sequence number* of *k*. Throughout our analysis, we use the terms *server* and *router* interchangeably; further, we assume that the sum of rates reserved for flows at any server does not exceed the server capacity (i.e., the link bandwidth). For improving readability, we include the proofs of all the Lemmas and Theorems in the appendix.

# 3 Problem Formulation

A flow f with reserved rate  $r_f$  expects the network to provide, during any time interval, throughput at least at rate  $r_f$ . This

<sup>\*</sup> This work appeard at IEEE INFOCOM, San Fransisco, CA, April 2003. <sup>1</sup>We refer to a sequence of packets transmitted by a source as a *flow*.

service semantic is captured in the following definition of an end-to-end throughput guarantee:

**Definition 1** For a flow f, whose source transmits packets at least at its reserved rate  $r_f$ , a network is said to provide an end-to-end throughput guarantee if in any time interval  $[t_1, t_2]$ , the network guarantees a minimum throughput,  $W_{f,H}(t_1, t_2)$ , to flow f given by:

$$W_{f,H}(t_1, t_2) > r_f(t_2 - t_1) - r_f \gamma_{f,H}^{net}$$
(1)

where H is the path length traversed by flow f and  $\gamma_{f,H}^{net}$  is a constant that depends on the traffic and server characteristics at nodes along the path.

From the definition, a network guarantees a non-zero throughput to flow f if  $t_2 - t_1 > \gamma_{f,H}^{net}$ ; thus, the value of  $\gamma_{f,H}^{net}$  bounds the longest time interval for which a flow may receive no throughput from the network. Clearly, the smaller the value of  $\gamma_{f,H}^{net}$ , the better the quality of network service for applications that require sustained network throughput.

Observe that most networks that reserve a rate for each flow guarantee an *average* throughput at the reserved rate; however, these networks differ in the time-scales (namely, the value of  $\gamma_{f,H}^{net}$ ) at which this guarantee is provided. For instance, for a network where each router employs an unfair packet scheduling algorithm (e.g., Virtual Clock or Delay EDD), the throughput received by a flow during a time interval is a function of the throughput received by the flow in the past. In fact, for such networks,  $\gamma_{f,H}^{net}$  is not bounded, indicating that an unfair network cannot guarantee non-zero throughput at finite time scales. To provide throughput guarantees at short time-scales, networks employ fair packet scheduling algorithms at routers [3, 6, 7, 9]. Fair scheduling algorithms ensure that in any time interval in which two flows are backlogged, they receive service in proportion to their reserved rates. It can be shown that, when coupled with admission control, a network of fair servers provides an endto-end throughput guarantee with  $\gamma_{f,H}^{net} = (H+1)\frac{l_f^{max}}{r_f} +$  $\sum_{j=1}^{H-1} \pi_j + \sum_{j=1}^{H} \gamma_{f,j}, \text{ where } \gamma_{f,j} \text{ characterizes the throughput guarantee provided by fair server } j \text{ in isolation [1, 11].}$ 

To provide throughput guarantees, existing fair scheduling algorithms define a concept of *virtual time* at each router; the virtual time at a router is inherently a function of the current state of each flow passing through the router. Implementations of fair scheduling algorithms, therefore, require every router to maintain per-flow state and perform per-packet flow classification. In this paper, our objective is to design a work-conserving core-stateless network architecture<sup>2</sup> that provides deterministic end-to-end throughput guarantees, similar to those provided by a network where each router employs a fair scheduling algorithm.

# 4 CSGT Networks

We design core-stateless guaranteed throughput networks in two steps. First, we show that for a network to provide throughput bounds similar to those in fair networks, it *must* also provide end-to-end delay guarantees. Second, we demonstrate that two mechanisms —tag re-use and source rate control— when integrated with a core-stateless network that provides end-to-end delay guarantees, lead to the design of the Core-stateless Guaranteed Throughput (CSGT) networks that provide end-to-end throughput bounds within an *additive constant* of that attained by a core-stateful network of fair servers. Throughout this section, we assume that a source transmits equal-sized packets.

## 4.1 Need for Delay Guarantees

Let the *expected arrival time* of a packet  $p_f^k$  of flow f at the first server,  $EAT(p_f^k)$ , be defined as:

$$\begin{split} &EAT(p_{f}^{1}) &= a_{f,1}^{1} \\ &EAT(p_{f}^{k}) &= \max\left(a_{f,1}^{k}, EAT(p_{f}^{k-1})\right) + \frac{l_{f}^{k-1}}{r_{f}}, \; k > 1 \end{split}$$

Then, a network is said to provide an *end-to-end delay guar*antee to flow f, if, for all packets  $p_f^k$ , the network provides an upper bound on  $(d_{f,H}^k - EAT(p_f^k))$ , where  $d_{f,H}^k$  is the departure time for packet  $p_f^k$  from node H. We use this definition of end-to-end delay guarantee to prove Theorem 1.

**Theorem 1** If a network provides lower-bounds on throughput of the form:  $W_{f,H}(t_1, t_2) \ge r_f(t_2 - t_1) - \Phi$  to any flow f whose source transmits at least at its reserved rate, then it also provides to flow f an end-to-end delay guarantee of the form:  $d_{f,H}^k - EAT_1(p_f^k) \le \frac{\Phi + l_f^{max}}{r_f}$ .

The converse of Theorem 1 indicates that a network that does not provide delay guarantee to packets cannot provide throughput bounds. Hence, a work-conserving, core-stateless network that provides delay guarantee is a crucial building block for designing CSGT networks.

In [10], the authors propose Core-stateless Guaranteed Rate (CSGR) networks that provide the same delay guarantee as a network that employs stateful scheduling algorithms from the Guaranteed Rate (GR) class at the core routers. As we illustrate below, a work-conserving CSGR network, however, does not provide throughput guarantees at short time-scales. Our design of a CSGT network uses the CSGR network as a building block and enhances it with a set of end-to-end mechanisms that allow the network to retain its delay properties while providing throughput guarantees at short time-scales. We describe the derivation of a CSGT network in the context of a Core-stateless Virtual Clock (CSVC) network [10, 21]—a specific instance of the class of CSGR networks.

<sup>&</sup>lt;sup>2</sup>Throughout this paper, the core-stateless property refers to a network that does not require its core routers to maintain per-flow state or perform per-packet flow classification.

## 4.2 Defining CSGT Networks

**CSVC Networks** A CSVC network consists of two types of routers: *edge routers* and *core routers*. Edge routers maintain per-flow state and perform per-packet flow classification. The *ingress* router —the edge router where a flow enters the network— assigns to each packet  $p_f^k$  a *service tag vector*  $[VCore_{f,1}^k, VCore_{f,2}^k, ..., VCore_{f,H}^k]$  where H is the number of servers along the path, and  $VCore_{f,j}^k$ , the service tag value for server j, is derived as follows<sup>3</sup>:

$$VCore_{f,1}^{k} = \max\left(a_{f,1}^{k}, VCore_{f,1}^{k-1}\right) + \frac{l_{f}^{k}}{r_{f}}$$
$$VCore_{f,j}^{k} = VC_{f,1}^{k} + \sum_{h=1}^{j-1} (\beta_{f,h} + \pi_{h} + \max_{1 \le i \le k} \frac{l_{f}^{i}}{r_{f}}), \ j \ge 1$$

where  $VCore_{f,1}^0 = 0$  and  $\beta_{f,h} = \frac{l_h^{max}}{C_h}$ . At both the edge and core routers, packets are transmitted in the increasing order of their service tags. Note that the core routers only perform a sorting operation on the tag values; there is no need to maintain per-flow state or perform per-packet flow classification.

It has been shown that a CSVC network provides a *dead-line guarantee* [10, 21]: packet  $p_f^k$  is guaranteed to depart server *j* by  $(VCore_{f,j}^k + \beta_{f,j})$ . However, the following example shows that a CSVC network does not provide throughput guarantees at finite time-scales.

**Example 1** Consider the first server, with a transmission capacity of 10 packets/sec, in a CSVC network. Let the sum of reserved rates of all flows be equal to the capacity. Let the rate reserved by a flow f be 1 packet/sec. At time t = 0, let f be the only backlogged flow. In this setting, by t = 1, 10 packets of flow f are serviced by the server; further,  $VCore_{f,1}^{11} = 11$ . Now, let all other flows become backlogged at time t = 1. Since the server services packets in the increasing order of virtual clock values, packet  $p_f^{11}$  may not be serviced until t = 10; hence, flow f receives no throughput during the interval [2, 10]. Given any time interval of arbitrary length, it is easy to extend this example to show that flow f receives no throughput during the interval of interest. Therefore, for any interval length, the CSVC server does not provide any non-trivial (non-zero) lower bound on throughput.

In the above example, until time t = 1, because of the availability of idle bandwidth and the work-conserving nature

of the CSVC server, flow f receives service at a rate greater than its reserved rate. Due to the way deadlines are computed, though, during the same period, flow f accumulates a *debit* at the rate  $r_f$  (indicated by the increase in its VCore value much beyond current time t), and is subsequently penalized for the duration of the accumulated debit once all the other flows become backlogged. It is important for networks to provide throughput guarantees at short time-scales, independent of the past usage of idle bandwidth by a flow, for two reasons:

- 1. In many settings, it is difficult for sources to predict precisely their bandwidth requirements at short time-scales. For instance, the bit-rate requirement of a variable bitrate video stream may vary considerably and over short time-scales. Suppose a video stream, with a reserved bit-rate of 1Mbps, transmits at 2Mbps for 4 seconds using idle bandwidth. In a network that does not provide throughput guarantees, the video stream may not receive any throughput at all in the next 4 seconds. The performance of the video application in such a network may therefore be unacceptable.
- 2. It is in the best interest of a network to allow sources to transmit data in transient bursts (i.e., at a rate greater than the reserved rate); bursty transmissions allow a network to benefit from statistical multiplexing of the available network bandwidth among competing traffic. In networks that penalize sources for using idle bandwidth, however, sources have no incentive to transmit bursts into the network. They may prefer to use constant bitrate flows, instead of allowing the network to enforce arbitrary penalties. This, in turn, would reduce the statistical multiplexing gains and thereby reduce the overall utilization of network resources.

It is important to observe that while a CSVC network does not provide lower bounds on throughput at finite time-scales, it does guarantee an *average* throughput at the rate of  $r_f$  to a backlogged flow f over infinite time-scales. This implies that, the throughput of flow f in any interval  $[t_1, t_2]$  would be below its reserved rate  $r_f$  only if the flow f receives service at a rate higher than  $r_f$  prior to  $t_1$ . In such an event, there must exist  $t', t'' < t_1$  such that during interval [t', t''], packets of flow f arrive at the destination much ahead of their deadline guarantee (derived based on the reserved rate  $r_f$ ). More formally, for packets  $p_f^k$  that reach destination at time t during the interval [t', t''],  $VCore_{f,H}^k \gg t$ .

**The Principle of Deadline Re-use** The property of allowing a flow to accumulate arbitrarily large amount of debit —by increasing the deadline values (or service tag values) assigned to packets of the flow much beyond the current time— is central to the inability of CSVC networks to provide throughput guarantees at small time-scales. Hence, for a network to provide throughput bounds at small time-scales, it must reduce debit accumulation; this can be achieved by

<sup>&</sup>lt;sup>3</sup>In practice, the ingress router computes only  $VCore_{f,1}^k$  for packet  $p_f^k$ . Before transmitting the packet, it encodes in the packet header a quantity called the *slack*—the difference between  $VCore_{f,1}^k$  and the actual departure time—and  $\max_{1 \le i \le k} \frac{l_f^i}{r_f}$ . When the second router receives the packet, it adds the slack,  $\beta_2$ , and  $\max_{1 \le i \le k} \frac{l_f^i}{r_f}$ , to the arrival time of the packet to compute  $VCore_{f,2}^k$  [10]. Subsequent routers compute their local VCore values in a similar manner.

allowing the ingress routers to re-use for future packets the deadline (or service tag) values of packets that reach the destination much prior to their deadlines. This is the central concept in transforming a CSVC network into a CSGT network that provides throughput bounds.

**The Definition of CSGT Network** A CSGT network, like the CSVC network, consists of two types of routers: *edge routers* and *core routers*. The ingress edge router, in addition to maintaining per-flow state, maintains a sorted-list  $\mathcal{R}$  of re-usable tag vectors. On receiving a packet  $p_f^k$  of flow f, the ingress router assigns to it a *service tag vector*  $[F_1(p_f^k), F_2(p_f^k), ..., F_H(p_f^k)]$  where H is the number of servers along the path, and  $F_j(p_f^k)$  is the service tag for server j. The assignment of the tag vector to packet  $p_f^k$  proceeds as follows: If  $\mathcal{R} \neq \emptyset$ , an incoming packet is assigned the smallest tag vector from  $\mathcal{R}$ . Otherwise, a new tag vector is created as follows:

$$F_1(p_f^k) = \max\left(a_{f,1}^k, \hat{F}_f(a_{f,1}^k)\right) + \frac{l_f^k}{r_f}$$
(2)

$$F_j(p_f^k) = F_1(p_f^k) + \sum_{h=1}^{j-1} (\beta_{f,h} + \pi_h + \max_{1 \le i \le k} \frac{l_f^i}{r_f}), \ j > 1 \quad (3)$$

where  $\beta_{f,h} = \frac{l_h^{max}}{C_h}$ , and  $\hat{F}_f(t)$  is the maximum of the service tags for server 1 assigned to any packet of flow f by time t. All servers in the CSGT network transmit packets in the increasing order of their service tags for that server.

Observe that if  $\mathcal{R} = \emptyset$ , then the assignment of tag vector in CSGT is identical to the CSVC network. When  $\mathcal{R} \neq \emptyset$ , then, by reusing a tag assigned to an earlier packet, CSGT prevents accumulation of unbounded debit for flow f. To instantiate such a CSGT network, we need to address the following issues.

- 1. When can an ingress server reuse a previously assigned tag vector for a new packet? What are the constraints that govern the re-usability of tag vectors? How does the ingress router create and maintain the sorted-list  $\mathcal{R}$ ? We address these questions in Section 4.2.1.
- 2. With the reuse of previously assigned tag vectors in the CSGT network, packets of flow f with higher sequence number may, in fact, carry a smaller tag value (i.e.,  $F_h(p_f^j) < F_h(p_f^i)$  even if i < j). Since the tag values determine the priority for servicing packets in each router, it is quite possible that packet  $p_f^j$  may reach the egress edge router prior to packet  $p_f^i$ , even though packet  $p_f^i$  was transmitted prior to packet  $p_f^j$  at server 1. We discuss the associated packet re-ordering requirement in Section 4.2.2.

#### 4.2.1 Maintaining the Sorted-list of Re-usable Tag Vectors

Reusing tag vectors allow CSGT networks to prevent unbounded debit accumulation for flows. Determination of whether a tag vector is eligible for reuse, however, is tricky because of two reasons.

• A CSGT network must ensure that the reuse of tag vectors for packets of flow *f* does not violate the deadline guarantees provided to *other* flows.

To meet this requirement, the tag assigned to a packet  $p_f^k$ must differ by at least  $\frac{l_f}{r_f}$  from the tags assigned to all packets  $p_f^i$  that were transmitted prior to packet  $p_f^k$  but have not reached the destination. This is because, if the separation is less than  $\frac{l_f}{r_f}$ , then flow f will be guaranteed service at a rate greater than its reserved rate  $r_f$ ; this, in turn, could violate the deadline guarantees provided to other flows.

- A CSGT network must ensure that it can provide a deadline guarantee on the re-used tag vector.
  - To meet this requirement, at the time of assigning a reusable tag to a packet, the ingress router must ensure that the tag value for the first server exceeds the current time by at least  $\frac{l_f}{r_f}$ .

Using these eligibility criteria, we formally define reusability of a tag vector as follows.

**Definition 2** A previously assigned tag vector  $[F_1, F_2, ..., F_H]$  is said to be **re-usable** for a packet  $p_f^m$  at time t if it satisfies the following properties:

$$\forall p_f^i \in \mathcal{U} : |F_j - F_j(p_f^i)| \geq \frac{l_f}{r_f} \tag{4}$$

$$t \leq F_1 - \frac{l_f}{r_f} \tag{5}$$

where  $\mathcal{U}$  is the set of packets transmitted by server 1 prior to packet  $p_f^m$  but have not reached the destination by time t.

A CSGT network can enforce these conditions as follows.

- 1. An ingress router should consider a tag vector for re-use only after a packet carrying that tag vector departs the egress router H. This ensures that condition (4) is met. This can be achieved by requiring the egress router to send, on transmitting a packet  $p_f^m$  of flow f, an acknowledgment for that packet to the ingress router for flow f. The ingress router, on receiving such an acknowledgment, can add the tag vector assigned to packet  $p_f^m$  to the sorted-list  $\mathcal{R}$  of re-usable tag vectors for flow f.
- 2. On receiving a packet  $p_f^k$  from flow f at time t, the ingress router can scan through the sorted-list  $\mathcal{R}$ , discard all the tag vectors that violate condition (5), and assign to packet  $p_f^k$  the first re-usable tag that meets condition (5).

Observe that the tag vector assigned to a packet  $p_f^m$  is likely to re-usable (i.e., satisfy condition (5)) only if packet  $p_f^m$  departs server H "sufficiently" prior to its deadline. In particular, if  $D^{min}$  is the minimum latency incurred by the acknowledgment packet to reach the ingress router, then using (5), the tag vector of packet  $p_f^m$  can be re-used only if:  $d_{f,H}^m + D^{min} \leq F_1(p_f^m) - \frac{l_f}{r_f}$ . From (3), this is the same as:

$$d_{f,H}^{m} \leq F_{H}(p_{f}^{m}) - \left(\sum_{j=1}^{H-1} (\beta_{f,j} + \pi_{j} + \max_{1 \leq i \leq m} \frac{l_{f}^{i}}{r_{f}}) + D^{min} + \frac{l_{f}}{r_{f}}\right)$$
(6)

Thus, the egress server sends an acknowledgment to the first server, *only* if packet  $p_f^k$  departs the network much before—as given by condition (6)—its deadline. We prove, in Lemma 2 (see Section 4.3), that if a CSGT network reuses tag vectors in accordance with the scheme described above, then it provides the same deadline-guarantee as a CSVC network.

#### 4.2.2 Addressing Packet Re-ordering Requirements

With the tag re-use scheme described above, in a CSGT network, packets of flow f may reach the egress router out-oforder. For applications that desire in-order delivery semantics, a CSGT network needs to employ a *sequencer* that can buffer packets received out-of-order and then deliver to the applications packets in-order. A sequencer can reside either on the egress router, on a special network appliance located between the egress edge router and the destination node, or on the destination node itself<sup>4</sup>. Figure 1 depicts the setting where a sequencer is logically inserted between the egress router and the destination node. For the simplicity of analysis, we assume zero propagation delay between the egress router and the sequencer.

Now, let us consider the issues in designing the sequencer. The following example shows that, in a naive implementation of a CSGT network, the number of packets that may need to be buffered at the sequencer is not bounded.

**Example 2** Consider the case when the tag vector of packet  $p_f^k$  becomes re-usable at the source, there are n unacknowledged packets,  $p_f^{k+1}, \ldots, p_f^{k+n}$ , with **larger** tag vectors in the network. Let the tag vector of  $p_f^k$  be re-assigned to packet  $p_f^{k+n+1}$ . Now let the tag vectors of the first (n-1) unacknowledged packets  $p_f^{k+1}, \ldots, p_f^{k+n-1}$  also become available for re-use; let these tag vectors be assigned to subsequent (n-1) packets, namely,  $p_f^{k+n+2}, \ldots, p_f^{k+n+n}$ . Consider the case where packet  $p_f^{k+n}$  departs the egress node at its deadline,  $F_H(p_f^{k+n})$ . Since packets  $p_f^{k+n+1}, \ldots, p^{k+n+n}$  have smaller deadlines, they are guaranteed to depart the egress router earlier than  $p_f^{k+n}$ . Therefore, these n packets

need to be buffered, simultaneously for some time, at the sequencer till packet  $p_f^{k+n}$  arrives. Larger the value of n, the larger the buffer space requirement at the sequencer.

In practice, a sequencer would have a fixed amount of buffer space. In order to avoid packet loss due to overflow of the sequencer buffers, therefore, the aggressiveness of sources using a CSGT network may need to be controlled. We do this by employing a *flow control algorithm* that limits the maximum number of deadlines that are simultaneously in use for packets of a flow. Specifically, the flow control algorithm ensures that at any point in time t, no packet is assigned a deadline larger than  $t + W \frac{l_f}{r_f}$ , where W is a configuration parameter. When a packet arrives at time t, if no deadline smaller than  $t + W \frac{l_f}{r_f}$  is available for assigning to it, the packet is held till one is available.

Observe that a large value of W increases the buffer space requirement at the sequencer (Example 2). A small value of W, on the other hand, limits the extent to which the source can utilize idle bandwidth in the network. In fact, if W = 1, the first server does not transmit a packet before its expected arrival time; in this case the server reduces to the non-workconserving Jitter Virtual Clock server. In practice, the largest value of W—such that buffer overflow at the sequencer can be avoided—should be selected. If B denotes the available sequencer buffer space, in units of the packet size  $l_f$ , then Lemma 1 provides a condition that when satisfied by W, avoids packet loss due to buffer overflow.

**Lemma 1** Packets of flow f will not be dropped at the sequencer due to unavailability of re-ordering buffers if W satisfies:

$$B \geq \begin{cases} (N+1)(W-1) - (N)(N+1)\frac{k^{min}}{2}, \\ if \ T^{min} \geq \frac{l_f}{r_f} \\ \frac{W(W-1)}{2k^{min}}, \qquad if \ T^{min} < \frac{l_f}{r_f} \end{cases}$$
(7)

where  $N = \lfloor \frac{W-2}{k^{min}} \rfloor$ ,  $k^{min} = \frac{T^{min}}{l_f/r_f}$ , and  $T^{min}$  is a lower bound on the round-trip time<sup>5</sup>.

Given the largest value of W that satisfies (7), there is a bound on the maximum amount of available bandwidth that a flow f can utilize. Conversely, one can provision buffer space at the sequencer that allows a flow to utilize up to a maximum bandwidth (say r'). In Appendix C, we show that to allow a source to utilize bandwidth r', the chosen value of W should

<sup>&</sup>lt;sup>4</sup>Deploying a sequencer on the destination node itself may require changes to end-hosts. Hence, the architectural options of instantiating the sequencer on the egress router or on an appliance located at the edge of the customer network may be more desirable.

 $<sup>{}^{5}</sup>T^{min}$  is a lower bound on the time difference between the transmission of a packet at the first server and the arrival of its acknowledgment at the first server. For instance, the sum of propagation and minimum transmission latencies on all the links on both the forward and reverse path qualifies as a lower bound.



Figure 1: The CSGT Network Architecture

satisfy the following condition<sup>6</sup>:

$$W \geq \frac{r'}{l_f} \left( \sum_{j=1}^{H-1} \pi_j + \sum_{j=1}^{H} \beta_{f,j} + D^{max} \right) + H + 1(8)$$

Such a value of W can then be used to provision the sequencers with the appropriate amount of buffers. In particular, given r', the maximum bandwidth that a flow should be allowed to utilize, one can derive a bound on W using (8); this value of W when substituted in (7) determines the minimum buffer requirement at the sequencer.

### 4.3 Properties of CSGT Networks

**Delay Guarantee** The following lemma proves that deadline guarantees of CSVC are preserved in a CSGT network.

**Lemma 2** A packet  $p_f^k$  is guaranteed to depart server j in a CSGT network by  $(F_j(p_f^k) + \beta_{f,j})$ .

It is important to observe that the deadlines assigned to a packet in a CSGT network are never larger than the dealines assigned to the same packet in a corresponding CSGR network. From Lemma 2, therefore, it follows that a CSGT network is guaranteed to deliver a packet no later than a CSGR network. This is true despite the additional delay introduced by the sequencer—the sequencer is guaranteed to deliver a packet  $p_f^k$  by its CSGR deadline. This is because all packets with smaller sequence numbers are guaranteed to arrive at the sequencer before their CSGR deadlines, which are smaller than the CSGR deadline of packet  $p_f^k$ .

**Throughput Guarantee** To quantify the effect of packet re-ordering on the throughput received by the applications, we define two different throughput measures. We define *network throughput* as the number of bits that depart the egress router during a given time interval, and *application throughput* as the number of bits that depart the sequencer (after re-ordering) during the interval. Note that the application throughput in any given interval may be different from the network throughput. Theorem 2 provides lower bounds on the network and application throughput in a CSGT network.

**Theorem 2** If the source of flow f transmits packets at least at its reserved rate, and  $D^{max}$  is an upper bound on

the latency after which an acknowledgment packet sent by the egress node reaches the ingress node, then the network guarantees a minimum throughput in any time interval  $[t_1, t_2]$ ,  $W_{f,H}(t_1, t_2)$ , given by:

$$W_{f,H}(t_1, t_2) > r_f(t_2 - t_1) - r_f * D^{max} - r_f\left((H+2)\frac{l_f}{r_f} + \sum_{j=1}^{H-1} \pi_j + \sum_{j=1}^{H} \beta_{f,j}\right)$$

Further, the sequencer guarantees a minimum throughput,  $W_{f}^{app}(t_{1}, t_{2})$ , given by:

$$W_{f}^{app}(t_{1}, t_{2}) > r_{f}(t_{2} - t_{1}) - r_{f} * D^{max} - W * l_{f} - r_{f} \left( (H+1)\frac{l_{f}}{r_{f}} + \sum_{j=1}^{H-1} \pi_{j} + \sum_{j=1}^{H} \beta_{f,j} \right)$$

The bound on the network throughput derived in Theorem 2 for a CSGT network differs from that provided by a corestateful network of fair servers (Section 3), by a constant term  $E_1 = r_f * [D^{max} - \sum_{j=1}^{H} (\gamma_{f,j} - \beta_{f,j})] + l_f$ . The bound on application throughput differs by the additional term  $E_2 = (W-1) * l_f$ .

Observe that for a CSGT network derived from CSVC,  $\beta_{f,j} = l^{max}/C_j$ . Further, for most fair schedulers,  $\gamma_{f,j} \ge l^{max}/C_j$ . Therefore,  $E_1 \le r_f * D^{max} + l_f$ , which is primarily governed by  $D^{max}$ , the maximum latency on the reverse path.

## 5 Evaluation of CSGT Networks 5.1 The Throughput Guarantee

Theorem 2 states that when measured over any time interval larger than  $\gamma_{f,H}^{net}$ , the network guarantees a non-zero throughput at a rate equal to the reserved rate. As discussed in Section 3, the smaller the value of  $\gamma_{f,H}^{net}$ , the better the network can support applications with stringent timeliness requirements. To evaluate the throughput guarantee of a CSGT network numerically, we compute  $\gamma_{f,H}^{net}$  for example networks, where link capacities are 100Mbps and link propagation latencies are 1ms. In figure 2(a), we plot  $\gamma_{f,H}^{net}$  against the number of hops on the end-to-end path of a sample flow with a reserved bit-rate of 10Mbps.  $D^{max}$  is varied from a multiple of 1 to 3 of the end-to-end propagation latency on the reverse path. For comparison, we also plot  $\gamma_{f,H}^{net}$  for a representative core-stateful network of fair  $WF^2Q+$  [3] servers. We observe the following:

<sup>&</sup>lt;sup>6</sup>The condition in (8) can be intuitively seen to be a form of the commonly used *delay-bandwidth product* rule-of-thumb.



Figure 2: Evaluation of a CSGT Network

- 1. When  $D^{max}$  is equal to the end-to-end link propagation latency, the throughput guarantee of the CSGT networks is similar to that of the core-stateful  $WF^2Q$ + networks.
- 2.  $\gamma_{f,H}^{net}$  increases with  $D^{max}$ . Therefore, the throughput guarantee of a CSGT network improves by provisioning low-delay feedback channels. However, even when  $D^{max}$  is three times the end-to-end propagation latency, the application is guaranteed a non-zero throughput over any time interval larger than 150ms.

These observations imply that by provisioning low-delay feedback channels, a CSGT network can provide non-zero throughput guarantees at very short time-scales, and similar to those in core-stateful networks.

#### 5.2 Sequencer Buffer Space vs. Maximum Throughput

Recall that there is a tradeoff between the amount of buffer space required at the sequencer and the maximum rate that the source is allowed to achieve. We numerically characterize this tradeoff for the same example network as above (link capacity = 100Mbps, link propagation latency = 1ms). In figure 2(b), we plot the minimum sequencer buffer space required to allow sources to achieve a given maximum bit-rate,  $R^{max}$  (varied from 2 to 5 times the reserved rate). We observe that:

- 1. To enable a flow, with a reserved bit-rate of up to 10Mbps, to achieve an end-to-end bit-rate of up to 5 times that (50Mbps), less than 1MB of sequencer buffer space is sufficient.
- 2. The buffer space requirement grows slower with increase in the bit-rate of the sample flow (for reference, we plot a line where the buffer requirement grows at the same rate as the reserved bit-rate).

These observations imply that a small amount of sequencer buffer space is sufficient to allow flows to utilize bandwidth up to multiple times their reserved rate. Further, a CSGT network can reduce the total buffer requirement at the sequencer by aggregating into a single large flow, all micro-flows that traverse the same path between a pair of edge routers.

### 5.3 Deployment Considerations

A CSGT network introduces two main overheads-namely, additional state in every packet, and additional traffic due to feedback messages-in order to provide throughput guarantees in a core-stateless architecture. To address the first overhead, several techniques for encoding state in packets efficiently have been discussed in [15]. We expect the overhead due to feedback traffic to also be small because of two reasons. First, the size of each feedback packet is small; additionally, the packetization overhead can further be reduced by acknowledging the receipt of multiple sequence numbers in the same feedback message. In applications that involve a bidirectional transfer of data, in fact, the feedback can be *piggy-backed* onto data packets transmitted on the reverse path. Second, feedback messages are transmitted only when data packets depart the network much earlier than their deadlines. This happens only when sufficient spare bandwidth is available on the forward path. While it would be useful to quantify precisely the expected amount of feedback traffic generated in practice, the lack of real testbeds and traffic characteristics prevents us from doing so.

## 6 Summary

End-to-end throughput guarantees is an important network service semantics to offer. Existing network architectures either provide throughput guarantees at the cost of introducing the complexity of per-flow state maintenance in all routers, or do not provide throughput guarantees at finite timescales. In this paper, we propose the Core-stateless Guaranteed Throughput (CSGT) network architecture—the *first* work-conserving network architecture that provides throughput guarantees to individual flows over finite time-scales, but without maintaining per-flow state in core routers. We develop the architecture in two steps. First, we show that for a network to provide end-to-end throughput guarantees, it must also provide end-to-end delay guarantees. Second, we demonstrate that two mechanisms —tag re-use and source rate control— when integrated with a work-conserving, corestateless network that provides end-to-end delay guarantees, lead to the design of CSGT network that provides end-to-end throughput bounds within an *additive constant* of what is attained by a core-stateful network of fair rate servers.

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# A Proof of Theorem 1

Consider  $t_1 = a_{f,1}^1$  and  $t_2 = d_{f,H}^k$ . Then  $W_{f,H}(a_{f,1}^1, d_{f,H}^k) = \sum_{i=1}^k l_f^i$ . Substituting into the throughput bound, we get:  $d_{f,H}^k \leq a_{f,1}^1 + \frac{\Phi}{r_f} + \sum_{i=1}^k \frac{l_f^i}{r_f}$ . Since the source transmits at least at its reserved rate,  $EAT_1(p_f^k) = a_{f,1}^1 + \sum_{i=1}^{k-1} \frac{l_f^i}{r_f}$ . Therefore,  $d_{f,H}^k - EAT_1(p_f^k) \leq \frac{\Phi + l_f^k}{r_f} \leq \frac{\Phi + l_f^max}{r_f}$ , for all k. Therefore, the network provides a delay guarantee to flow f.

# B Proof of Lemma 1

We refer to packets that are assigned re-used tags as *future* packet. We assume that a future packet is removed from the sequencer re-ordering buffers as soon as all packets with smaller sequence numbers arrive.

Let B(t) denote the occupancy of the sequencer reordering buffers of a flow f at time t. Let  $t_i$  denote the time instant at which the  $i^{th}$  future packet is removed from these buffers. For ease of analysis, we assume that even if all packets with smaller sequence numbers reach the sequencer before it, a future packet is still buffered and removed (in such as scenario, at time instances  $t_i^-$  and  $t_i$  respectively). Let  $t_0$ denote the initial time at which the source starts transmitting packets, and  $B(t_0) = 0$ . It follows that,  $B(t_i) \leq B(t_i^-) - 1$ (more than one future packets may be removed from the buffers at the same instant). The buffer occupancy in any time interval  $[t_i, t_{i+1})$  is non-decreasing with time (since no packets are removed in this interval). Therefore, the maximum buffer occupancy in this interval is given by  $B(t_{i+1}^-)$ .

Consider the first server (ingress node) at a time  $t_i$ . Consider all future packets transmitted by this server, that have not departed the sequencer (by time  $t_i$ ). Of these, let  $b_1$  denote the future packet with the smallest sequence number. Consider the set of all packets with smaller sequence numbers than packet  $b_1$ , that have not yet (at  $t_i$ ) reached the sequencer. Among these, let p' have the largest tag-vector then all of these packets would reach the sequencer at most by time ( $F_H(p') + \beta_{f,H}$ ), and the packet  $b_1$  would not need to be buffered after that. Let t' be the time at which packet p' arrives at the first server, and is assigned a tag-vector. Since all future packets that have not departed the sequencer by time  $t_i$ , have a larger sequence number than p', they are transmitted from the first server after t'. Let B" be the total number of future packets that get transmitted from the first server in the interval  $(t', F_1(p')]$ , with *smaller* tag-vectors than p'. Since p' has not reached the sequencer by  $t_i$ , any future packets transmitted after t' with *larger* tag-vectors than p' have also not reached the sequencer. Hence,  $B(t_i) \leq B$ ", and B" is the maximum number of future packets that would need to be buffered at the sequencer before p' gets delivered, that is,  $B(t_{i+1}^-) \leq B$ ".

Due to source flow control, observe that:  $t' \ge F_1(p') - W * l_f/r_f$ . The number of distinct tag-vectors that lie in the interval  $(t', F_1(p')]$  is given by:  $W' = \left\lfloor \frac{(F_1(p'))^{-} - t'}{l_f/r_f} \right\rfloor \le W - 1$ . Let  $T^{min}$  denote a lower bound on the round-trip time—the time difference between the transmission of a packet at the first server and the arrival of its acknowledgment at the first server. The maximum number of tags that can become re-usable from the interval  $(t', F_1(p')]$  after time t', which is an upper bound on  $B(t_{i+1}^{-})$ , is given by:

$$\leq \begin{cases} W' + (W' - \lceil k^{min} \rceil) + \dots + (W' - \lceil N'k^{min} \rceil), \\ & \text{if } T^{min} \geq \frac{l_f}{r_f} \\ \left\lfloor \frac{1}{k^{min}} \right\rfloor + \left\lfloor \frac{2}{k^{min}} \right\rfloor + \dots + \left\lfloor \frac{W'}{k^{min}} \right\rfloor, \text{ if } T^{min} < \frac{l_f}{r_f} \end{cases}$$

where  $k^{min} = \frac{T^{min}}{l_f/r_f}$ , and  $N' = \left\lfloor \frac{W'-1}{k^{min}} \right\rfloor$ . The right-handside of the above is an increasing function of W'. Since  $W' \leq W - 1$ ,

$$B(t_{i+1}^{-}) \leq \begin{cases} (N+1)(W-1) - (N)(N+1)\frac{k^{min}}{2}, \\ \text{if } T^{min} \geq \frac{l_f}{r_f} \\ \frac{W(W-1)}{2k^{min}}, \\ \text{if } T^{min} < \frac{l_f}{r_f} \end{cases}$$

where  $N = \lfloor \frac{W-2}{k^{m+n}} \rfloor$ . Since this upper bound on  $B(t_{i+1}^-)$  is independent of *i*, it is an upper bound on the maximum buffer occupancy in all time intervals  $[t_i, t_{i+1}), i \ge 0$ . Therefore, if the provisioned buffer space, *B*, is at least as large as given by this upper bound, no packets are lost at the sequencer reordering buffers.

## C Condition on *w* to Allow Large Throughput to be Achieved

Suppose  $r' > r_f$  is the bottleneck bandwidth available to the flow f at time  $t_0$  (and thereafter). Without loss of generality, assume that the first server is the bottleneck server<sup>7</sup>. We derive a condition on W such that if there is only a single packet at the bottlenecked first server (and in the network) at a time  $t_0$ , then there continues to be at least one packet at the bottlenecked server at all future times (given that the source has packets to transmit). If this is the case, then the bottleneck bandwidth available to flow f is not wasted.

Suppose packet  $p_f^1$  arrives at the server queue at time  $t_0$ . Then it can be shown that packet  $p_f^k$ , (where packets  $p_f^1, \ldots, p_f^k$  are transmitted back-to-back) would incur a maximum delay of  $(\sum_{j=1}^{H-1} \pi_j + \sum_{j=1}^{H} \beta_{f,j} + (H+k-1)*l_f/r')$  before it departs from the network. The acknowledgment for packet  $p_f^k$  would reach the ingress node after an additional delay of at most  $D^{max}$ . The corresponding  $S_1$  of this packet at the ingress node would be  $S_1(p_f^k) = t_0 + (k-1)l_f/r_f$ . Therefore, the tag-vector of packet  $p_f^k$  would definitely be available for re-use at the first server, if k satisfies:  $\sum_{j=1}^{H-1} \pi_j + \sum_{j=1}^{H} \beta_{f,j} + (H+k-1)*l_f/r' + D^{max} \leq (k-1)*l_f/r_f$ . This implies:

$$k \ge \frac{\sum_{j=1}^{H-1} \pi_j + \sum_{j=1}^{H} \beta_{f,j} + D^{max} + H * \frac{l_f}{r'}}{\frac{l_f}{r_f} - \frac{l_f}{r'}} + 1 \quad (9)$$

Now observe that, if the bottlenecked first server remains backlogged till the time the acknowledgment for  $p_f^k$  arrives, then the subsequent acknowledgments (spaced  $l_f/r'$  apart) clock the transmission of new packets, and the bottleneck server, that transmits a packet every  $l_f/r'$  units, would remain backlogged subsequently.

Further, due to source flow control, the tags for packet  $p_f^k$  would become available for re-use at most by the time  $W + m_k$  packets arrive for transmission at the first server after  $t_0$ , where  $m_k$  is given by the term:

$$\frac{\sum_{j=1}^{H-1} \pi_j + \sum_{j=1}^{H} \beta_{f,j} + (H+k-1)\frac{l_f}{r'} + D^{max}}{l_f/r_f}$$
(10)

Therefore, if the time it takes for the first server to transmit  $W + m_k$  packets at the rate r', is at least as large as the maximum time it takes for the acknowledgment of packet  $p_j^k$  to arrive after  $t_0$ , the first server always remains backlogged with packets to transmit. That is, the following condition would ensure that the server remains continuously backlogged:  $(W + m_k) * \frac{l_f}{r'} \ge \sum_{j=1}^{H-1} \pi_j + \sum_{j=1}^{H} \beta_{f,j} + D^{max} + (H + k - 1) * \frac{l_f}{r'}$ . From (9) and (10), this yields:

$$(W-1)l_f \ge r'(\sum_{j=1}^{H-1} \pi_j + \sum_{j=1}^{H} \beta_{f,j} + D^{max}) + H l_f \quad (11)$$

If, on the other hand, W does not satisfy condition (11) for the available bottleneck bandwidth r', then it can be seen, using a similar argument as above, that the throughput rate that the source can sustain,  $R^{max}(W, r')$ , is given by:

$$\simeq r_f + \frac{\left(1 - \frac{r_f}{r'}\right)(W - 1) * l}{\sum_{j=1}^{H-1} \pi_j + \sum_{j=1}^{H} \beta_{f,j} + D^{max} + H * \frac{l_f}{r'}}$$

<sup>&</sup>lt;sup>7</sup>Suppose this is not the case. Then even if the first server transmits packets once only every  $l_f/r'$  time units, the bottleneck server will remain backlogged.

## D Proof of Lemma 2

In the following, a *non-preemptive* scheduling algorithm is one that does not preempt the transmission of a lower priority packet even after a higher priority packet arrives. On the other hand, a *preemptive* scheduling algorithm always ensures that the packet in service is the packet with the highest priority by possibly preempting the transmission of a lower priority packet. A non-preemptive algorithm is considered *equivalent* to a preemptive algorithm if the priority assigned to all the packets is the same in both. The following lemma is stated and proved in [8].

**Lemma 3** If PS is a work conserving preemptive scheduling algorithm, NPS its equivalent non-preemptive scheduling algorithm and the priority assignment of a packet is not changed dynamically, then

$$L_{NPS}(p^k) - L_{PS}(p^k) \le \frac{l^{max}}{C}$$

where  $L_{PS}(p^k)$  and  $L_{NPS}(p^k)$  denote the time a packet leaves the server when PS and NPS scheduling algorithms are employed, respectively. Also,  $l^{max}$  is the maximum length of a packet and C is the capacity of the server.

We first state and prove Lemma 4, which is used to prove Lemma 2.

**Lemma 4** If the  $j^{th}$  server's capacity is not exceeded, then the time at which packet  $p_f^k$  departs a Preemptive CSGT server, denoted by  $L_{PCSGT}^j(p_f^k)$ , is

$$L_{PCSGT}^{j}(p_{f}^{k}) \le F_{j}(p_{f}^{k}) \qquad j \ge 1$$
(12)

**Proof:** Let  $S_j(p_f^k) = F_j(p_f^k) - l_f^k/r_f$ . At server *j*, define the quantity  $R_{f,j}(t)$  for flow *f* as follows:

$$= \begin{cases} r_f \text{ if } \exists k \ni (a_{f,j}^k \le t) \land (S_j(p_f^k) < t \le F_j(p_f^k)) \\ 0 \text{ otherwise} \end{cases}$$
(13)

Let S be the set of flows served by server j. Then server j with capacity  $C_j$  is defined to have *exceeded its capacity* at time t if  $\sum_{n \in S} R_{n,j}(t) > C_j$ . Let  $K_{f,j}(t_1, t_2)$  be the set of all flow f packets that arrive at server j in interval  $[t_1, t_2]$  and have deadlines no greater than  $t_2$ . For packet  $p_f^k$ , let  $T_{f,j}^k =$  $F_j(p_f^k) - \max(a_{f,j}^k, S_j(p_f^k))$ . The proof of Lemma 4 is by induction on j.

**<u>Base Case</u>** : j = 1. From (2) and (5), we have:  $F_1(p_f^k) \ge a_{f,1}^k + l_f^k/r_f^k$ . Then it can be observed from (4) and (13) that:

$$\int_{t_1}^{t_2} R_{f,1}(t) dt = \sum_{i \in K_f(t_1, t_2)} (r_{f,1}^i * T_{f,1}^i)$$
$$\geq \sum_{i \in K_f(t_1, t_2)} (r_{f,1}^i * \frac{l_f^i}{r_f^i}) \geq \sum_{i \in K_f(t_1, t_2)} l_f^i$$

Therefore, the cumulative length of all flow f packets that arrive in interval  $[t_1, t_2]$  and have deadline value no greater than  $t_2$ , denoted by  $AP_f(t_1, t_2)$ , is given as  $AP_f(t_1, t_2) \leq \int_{t_1}^{t_2} R_{f,1}(t) dt$ .

 $\int_{t_1}^{t_2} R_{f,1}(t) dt.$  We now prove the lemma by contradiction. Assume that for packet  $p_f^k$ ,  $L_{PCSGT}^1(p_f^k) > F_1(p_f^k)$ . Also, let  $t_0$  be the beginning of the busy period in which  $p_f^k$  is served and  $t_2 = F_1(p_f^k)$ . Let  $t_1$  be the least time less than  $t_2$  during the busy period such that no packet with deadline value greater than  $t_2$  is served in the interval  $[t_1, t_2]$  (it can be shown that such a  $t_1$  exists). Clearly, all the packets served in the interval  $[t_1, t_2]$  arrive in this interval (else they would have been served earlier than  $t_1$ ) and have deadline value less than or equal to  $t_2$ . Since the server is busy in the interval  $[t_1, t_2]$  and packet  $p_f^k$  is not serviced by  $t_2$ , we have:  $\sum_{f \in S} AP_f(t_1, t_2) > C_1(t_2 - t_1)$ . Since  $AP_f(t_1, t_2) \leq \int_{t_1}^{t_2} R_{f,1}(t) dt$ , we have:

$$\int_{t_1}^{t_2} \sum_{f \in S} R_{f,1}(t) dt > C_1(t_2 - t_1)$$
(14)

Since the server capacity is not exceeded,  $\sum_{f \in S} R_{f,1}(t) \leq C_1$ . Hence,  $\int_{t_1}^{t_2} \sum_{f \in S} R_{f,1}(t) dt \leq C_1(t_2 - t_1)$ . This contradicts (14) and hence the base case is proved.

**Induction Hypothesis** : Assume (12) holds for  $1 \le j \le m$ . **Induction Step** : We will show that (12) holds for  $1 \le j \le m + 1$ .

From (3) and the Induction Hypothesis, we get:  $F_{m+1}(p_f^k) \ge a_{f,m+1}^k + l_f^k/r_f^k$ . The induction step can now be proved in exactly the same manner as the base case. Therefore, from induction, the lemma follows.

Since Preemptive CSGT is work conserving and does not dynamically change the priority of a packet, lemma 2 follows immediately from Lemma 4 and Lemma 3.

### E Proof of Theorem 2

Since  $D^{max}$  is the maximum latency after which a packet from the egress node reaches the ingress node, the following condition is *sufficient* to ensure that the tags of packet  $p_f^k$  will be reused by the ingress node:

$$d_{f,H}^{k} + D^{max} \le F_1(p_f^k) - \frac{l_f^k}{r_f}$$
(15)

Consider any tag value F at the *last* server H. Let  $k_F$  denote the sequence number of the <u>last</u> packet that is ever assigned the deadline tag F at server H. Then the departure time of packet  $p_f^{k_F}$  from the last server,  $d_H^{k_F}$ , must not satisfy condition (15)—otherwise, tag F would be re-used for another packet, and  $p_f^{k_F}$  does not qualify to be the last packet to be assigned the tag F. We therefore have:

$$F - d_H^{k_F} < D^{max} + \frac{l_f^{k_F}}{r_f^{k_F}} + \sum_{j=1}^{H-1} (\beta_{f,j} + \pi_j + \max_{1 \le i \le k_F} \frac{l_f^i}{r_f})$$

Let  $\hat{T}$  be the upper bound on the right hand side of the above for all F. That is, for a source with equal-sized packets, let  $\hat{T} = D^{max} + H \frac{l_f}{r_f} + \sum_{j=1}^{H-1} \pi_j + \sum_{j=1}^{H-1} \beta_{f,j}$ . Now consider any time interval  $(t_1, t_2)$ . From the def-

Now consider any time interval  $(t_1, t_2)$ . From the definition of  $\hat{T}$ , we know that given any  $F \ge (t_1 + \hat{T})$  that has been assigned as a deadline tag at the last server H, at least one packet with this tag F will be delivered after time  $t_1$  (this is true even for  $t_1 = a_{f,1}^1$ , since  $F_1(p_f^1) \le a_{f,1}^1 + \hat{T}$ ). Further, from Lemma 2, we know that any packet with an assigned deadline tag F will be delivered no later than  $F + \beta_{f,H}$ . Therefore, for every  $F \in [t_1 + \hat{T}, t_2 - \beta_{f,H}]$  that has been assigned as a tag to any packet, at least one packet with that deadline tag will depart the last server in the time interval  $(t_1, t_2)$ . Let  $B(t_0, t)$  represent the total number of bits in packets that are last assigned deadlines that lie in any time interval  $(t_0, t]$ . Then,  $W_{f,H}(t_1, t_2) \ge B(t_1 + \hat{T}, t_2 - \beta_{f,H})$ .

Let  $t_3 = t_1 + \hat{T}$  and  $t_4 = t_2 - \beta_{f,H}$ . Let  $t'_3 \ge t_3$  be the smallest time instant that coincides with a deadline—let the corresponding packet be  $p_f^{k_3}$ . Let  $t'_4 \le t_4$  be the largest time instant that coincides with a deadline—let the corresponding packet be  $p_f^{k_4}$ . Then, since the source transmits at least at its reserved rate, the total number of bits in packets with deadline in the range  $(t'_3, t'_4)$  is given by:  $B(t'_3, t'_4) = r_f(t'_4 - t'_3)$ .

Now note that  $t'_3 < t_3 + l_f/r_f$ . This is so because otherwise,  $F(p_f^{k_3-1}) \in [t_3, t'_3)$ , which violates the definition of  $t'_3$ . Similarly,  $t'_4 > t_4 - l_f/r_f$ . This is so because otherwise,  $F(p_f^{k_4+1}) \in (t'_4, t_4]$ , which violates the definition of  $t'_4$ . Therefore, we have:  $t'_4 - t'_3 > (t_4 - t_3) - 2l_f/r_f$ . Therefore, we get:  $W_{f,H}(t_1, t_2) \ge B(t_3, t_4) \ge B(t'_3, t'_4) = r_f(t'_4 - t'_3) > r_f(t_4 - t_3) - 2l_f$ . This implies,

$$W_{f,H}(t_1, t_2) > r_f(t_2 - t_1) - r_f * D^{max} - r_f\left((H+2)\frac{l_f}{r_f} + \sum_{j=1}^{H-1} \pi_j + \sum_{j=1}^{H} \beta_{f,j}\right)$$

Next, consider a time instant  $t_5 \in (t_3, t_4)$  that coincides with a deadline tag at the last server. Let  $p_f^{k_5}$  be the <u>last</u> packet that is assigned the deadline  $t_5$ . Then  $p_f^{k_5}$  is received at the sequencer in the interval  $(t_1, t_2)$ . If  $p_f^{k_5}$  is not a future packet, it departs the sequencer (for simplicity, we assume that packets depart the sequencer instantly). If not, it has to be buffered till all packets with smaller sequence numbers reach the sequencer as well. Among all these packets with smaller sequence numbers than  $p_f^{k_5}$ , let p' have the largest deadline (if there are more than one such packets, let p' be the last packet to be assigned that deadline).

Packet  $p_f^{k_5}$  arrives for transmission at the first server latest by  $F_1(p_f^{k_5}) - l_f^{k_5}/r_f$ . Let t' be the time at which p' arrives for transmission at the first server. Since p' has a smaller sequence number than  $p_f^{k_5}$ ,  $t' < F_1(p_f^{k_5}) - l_f^{k_5}/r_f$ . Further, due to source flow control,  $F_1(p') \leq t' + W * l_f/r_f$ . Therefore,  $F_1(p') < F_1(p_f^{k_5}) + (W-1) * l_f/r_f \Rightarrow F_H(p') < t_5 + (W-1) * l_f/r_f$ . Since p' is guaranteed to be delivered at the sequencer by  $F_H(p') + \beta_{f,H}, p_f^{k_5}$  will also be delivered by this time. This implies that, for any deadline in the interval  $(t_1 + \hat{T}, t_2 - \beta_{f,H} - (W - 1) * l_f/r_f)$ , the last packet to be assigned that deadline will depart *the sequencer* in the time interval  $(t_1, t_2)$ . Therefore, the number of bits that depart the sequencer in the time interval  $(t_1, t_2), W_f^{app}(t_1, t_2)$ , is given by:  $W_f^{app}(t_1, t_2) \ge B(t_3, t_4 - (W - 1) * \frac{l_f}{r_f}) \ge B(t'_3, t'_4 - (W - 1) * \frac{l_f}{r_f}) > r_f(t_4 - t_3) - 2r_f \frac{l_f}{r_f} - (W - 1)l_f$ . This implies,

$$\begin{split} W_{f}^{app}(t_{1},t_{2}) &> r_{f}(t_{2}-t_{1}) - r_{f} * D^{max} - W * l_{f} \\ &- r_{f} \left( (H+1) \frac{l_{f}}{r_{f}} + \sum_{j=1}^{H-1} \pi_{j} + \sum_{j=1}^{H} \beta_{f,j} \right) \end{split}$$