

Simulating Hair Dynamics

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- Styling

 - Geometry of hair*

 - Density, distribution, orientation of hair strands*

- Simulation

 - Dynamic motion of hair*

 - Collision between hair and other objects*

 - Mutual hair interactions*

- Rendering

 - Color, shadows, light scattering effects, transparency, and anti-aliasing*

Hair Simulation



- Difficult to provide a realistic model

Each hair strand has a complex mechanical behaviors

Little knowledge available of mutual hair interactions

- Problems in terms of computation costs

Existing methods propose compromises between realism and efficiency depending on application



The Mechanics of Hair

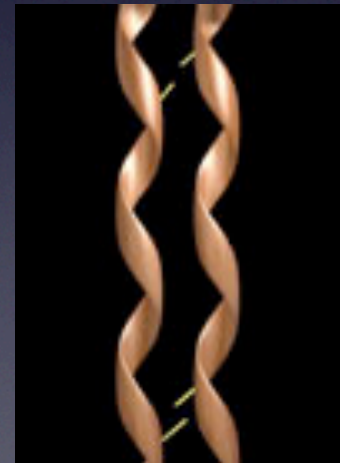
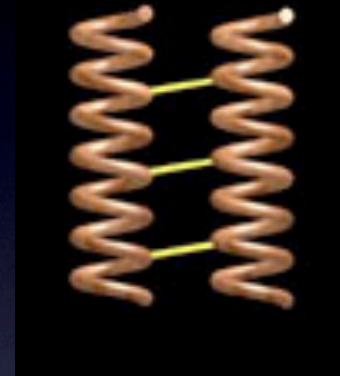
- Hair strands are anisotropic deformable objects

Can easily bend and sometimes twist

Strongly resist shearing and stretching

- Have some elastic properties

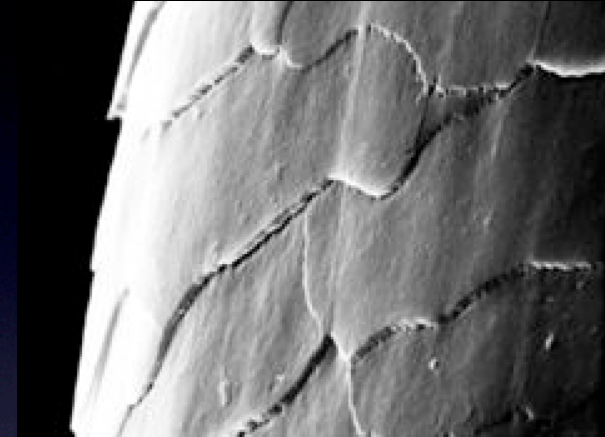
Tend to recover original shape after stress has been removed



- **Complex interactions between hair strands**

Surface of individual hair strands consists of irregular tiled scales

Causes anisotropic friction inside hair with direction depending on orientation of scales and direction of motion



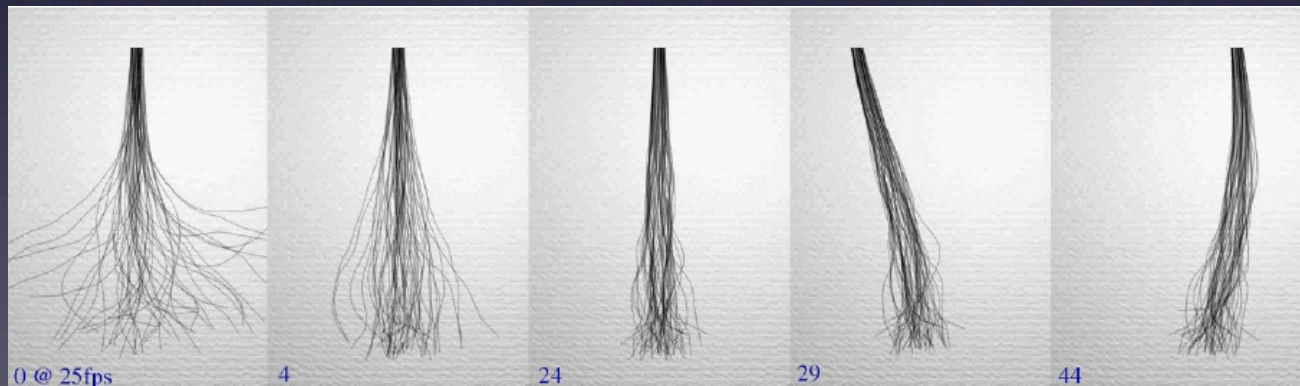
- **Geometric shape affects motion of hair**

Hair curls can longitudinally stretch during motion

Clumps more likely to appear in curly hair

More intricate geometries have less degrees of freedom during motion

Dynamics of Individual Hair Strands

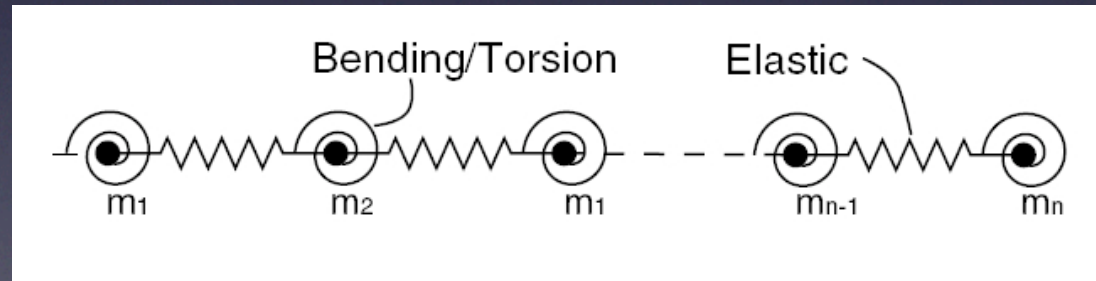


Mass-spring Systems

- Hair strand modeled as a set of particles connected by stiff springs and hinges

Each particle has one degree of translational and two degrees of rotational freedom

Bending rigidity ensured by angular springs at each joint



- Simple and easy to implement

But does not account for torsional rigidity or non-stretching of each strand



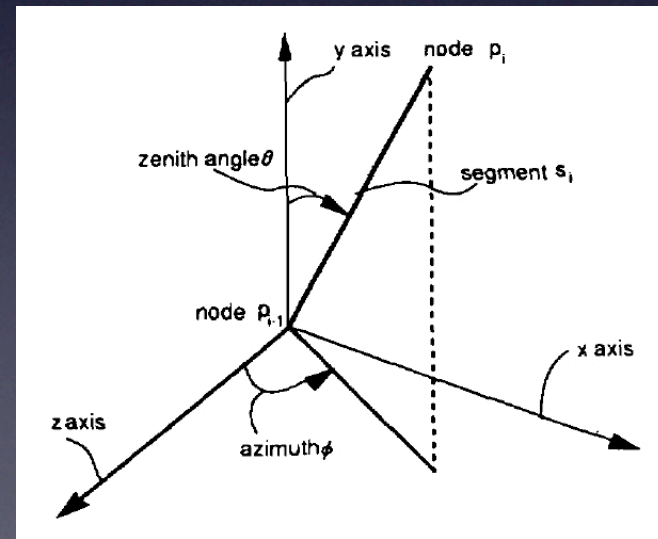
One-dimensional Projective Equations

- Hair strand considered as a chain of rigid sticks

Sticks parameterized by polar angles ϕ and θ

External force applied to each stick projected onto two planes defined by ϕ and θ

Fundamental principles of dynamics applied to each parameter leading to two differential equations at each step



- Hair is prevented from stretching and hair bending is properly recovered

But as torsional hair stiffness cannot be accounted for, three dimensional motion cannot be completely simulated

Motion processed from top to bottom, so difficult to handle external punctual forces



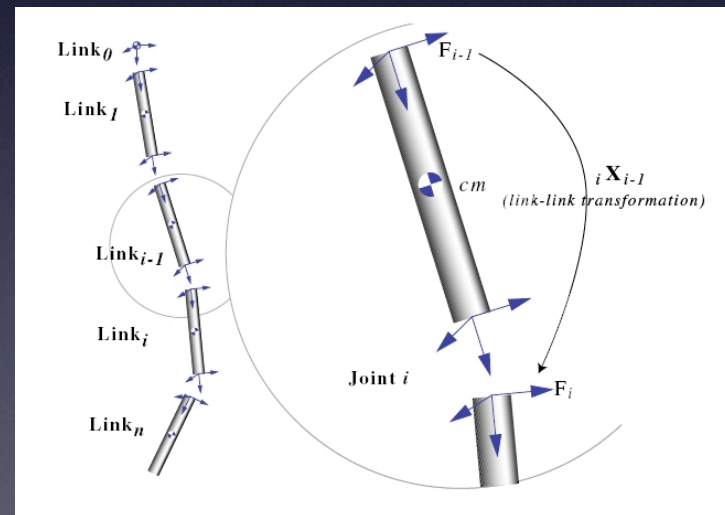
Rigid Multi-body Serial Chain

- Hair strand represented as a rigid multi-body open chain

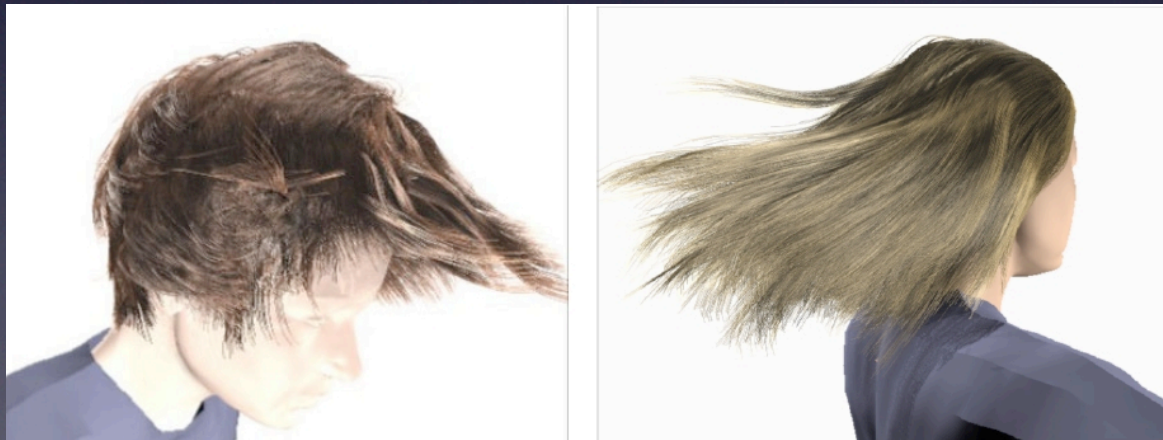
Stretching degrees of freedom removed to ensure only bending or twisting

Apart from gravity, forces responsible for bending or torsional rigidity are applied to each link

Motion computed using forward dynamics



Simulating the Dynamics of a Full Hairstyle



Hair as a Continuous Medium

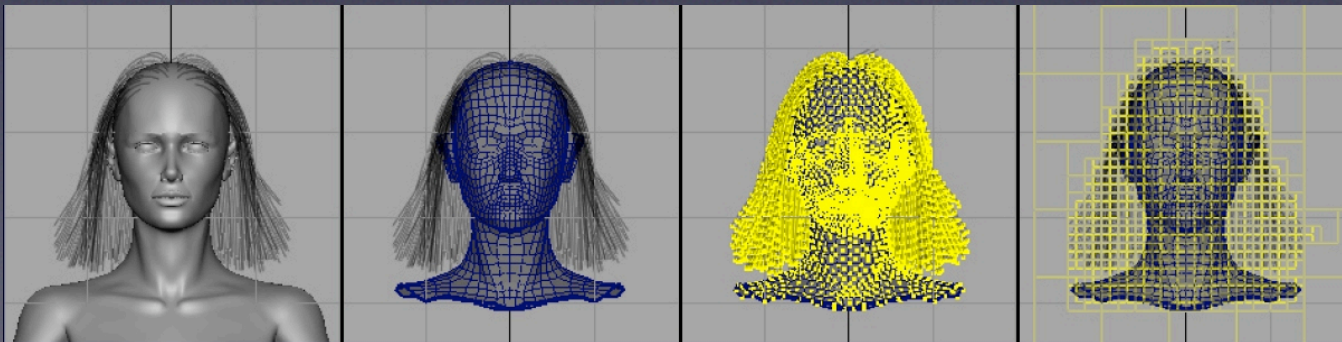
- A human head of hair normally consists of over 100,000 strands of hair
 - Simulating each individually is computationally overwhelming*
- But strands of hair in close proximity tend to move with similar motions

Suggests viewing hair as an anisotropic continuous medium



Smooth Particle Hydrodynamics

- Model interactions of hair using fluid dynamics
 - Kinematically link each hair strand to fluid particles in their vicinity*
 - Density of hair medium defined as mass of hair per unit volume*
 - Pressure and viscosity represent all the forces due to interactions between hair strands*
 - Hair-body interactions modeled by creating boundary fluid particles around solid objects*



- Captures the complex interactions of hair strands

But assumes a continuum of hair, so cannot capture the dynamic clustering effects seen in long and thick hair

Computationally expensive, slow even using parallelization



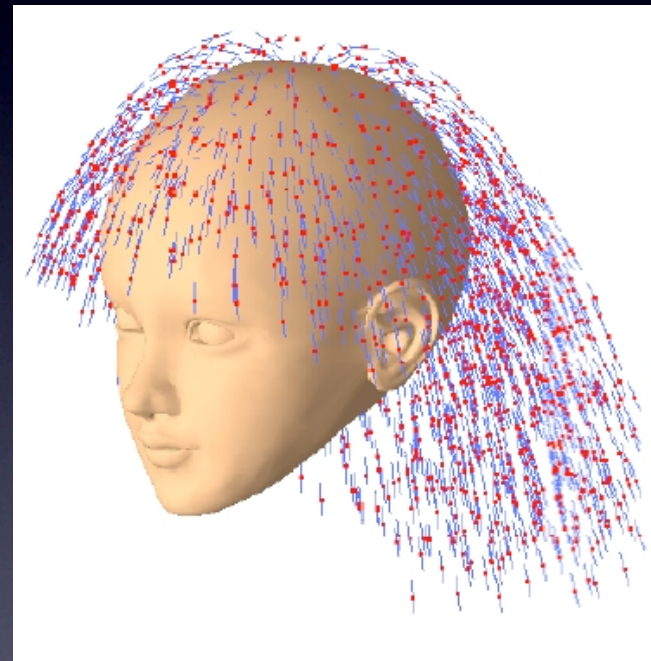
Loosely Connected Particles

- Use a set of SPH particles that interact in an adaptive way

Each particle represents a certain amount of hair material with a local orientation

- Neighboring particles with similar orientations are linked

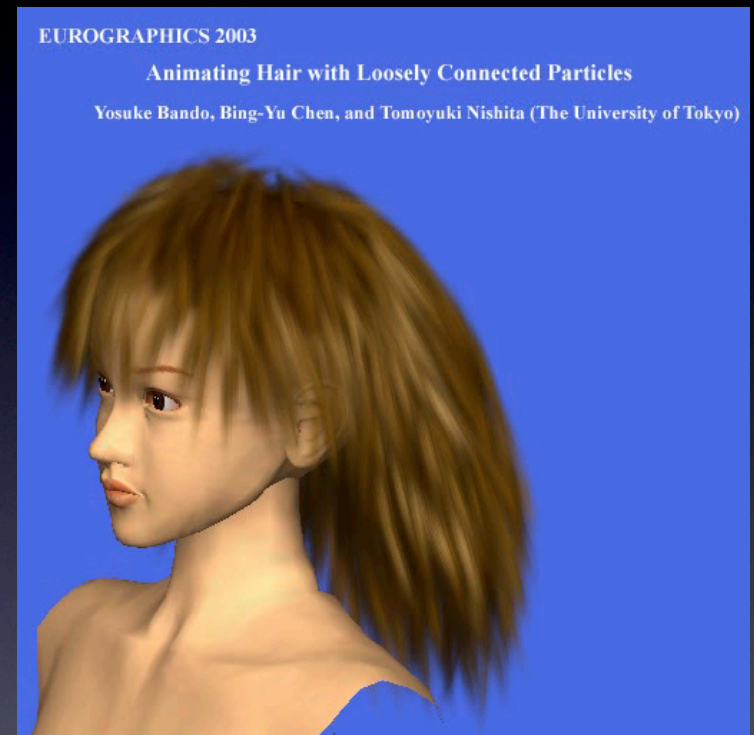
Represents spatial consistency of interactions between particles



- During motion each particle can interact with other particles in its local neighborhood

Links are breakable and disappear as soon as the particles move a certain distance apart

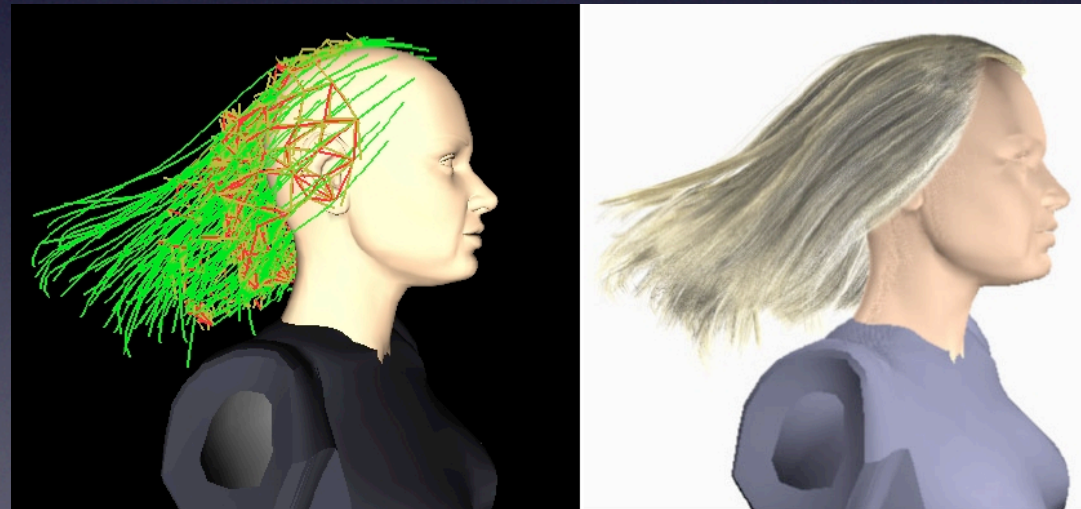
Allows separation and grouping while maintaining constant hair length



Interpolation between Guide Hair Strands

- Simulate a sparse set of hair strands

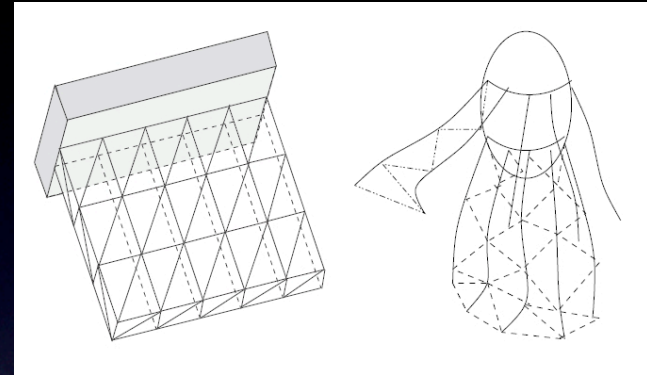
Create a dense model by interpolating the position of the remaining strands from the guide strands



- Use the guide strands to detect and handle hair interactions

Only using strands inefficient so build an auxiliary triangle strip between corresponding vertices

Check for interactions between hair segments and a hair segment and triangular face



Free Form Deformation

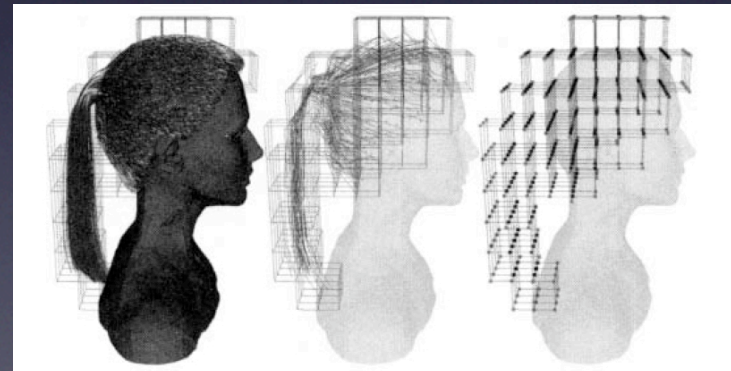
- Define a mechanical model for a lattice surrounding the head

Lattice is deformed as a particle system and hair strands follow by interpolation

Collisions between hair and body handled by approximating the body as a set of metaballs

- Good for simulating complex hairstyles when head motion has low magnitude

Cannot reproduce discontinuities in hair



Hair as Disjoint Groups

- Group nearby hair strands and simulate groups as independent, interacting entities

Saves computation time compared to simulating individual strands

Able to account for local discontinuities seen inside long hair during fast motion



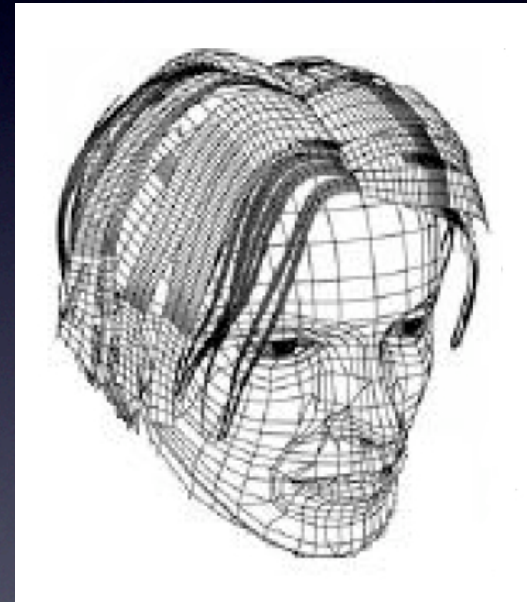
Real-time Simulation of Hair Strips

- Model groups of strands using a thin flat patch

Place springs between neighboring strips to prevent collisions

Also prevents strips from moving too close or far apart

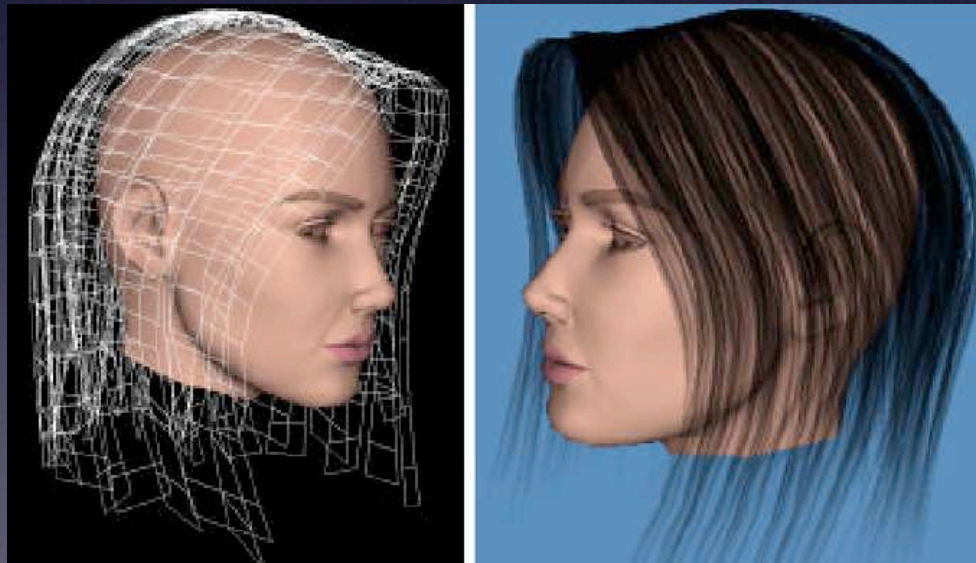
Use ellipsoids to represent the head and body and a reaction constraint method to move a strip back to the boundary if it intersects



- Using a strip to represent tens or hundreds of hairs allows real time simulation

But process limited in the types of hairstyle and motion it can represent

Flat shape of strips most suited to long straight hair



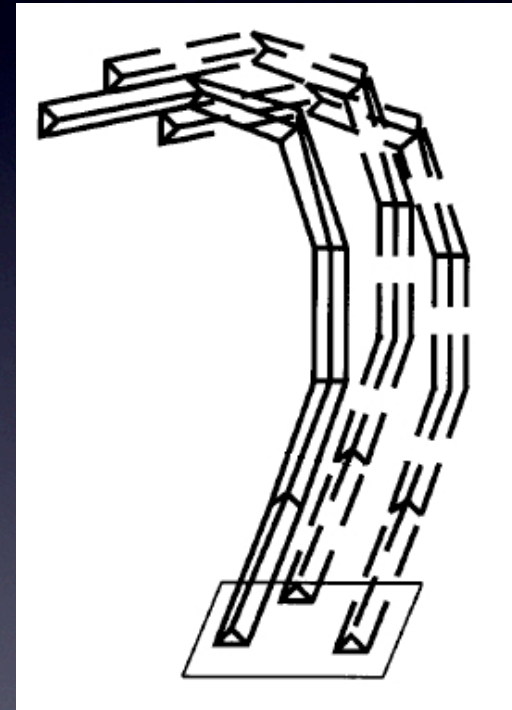
Simulation of Wisps

- Group neighboring strands together into wisps

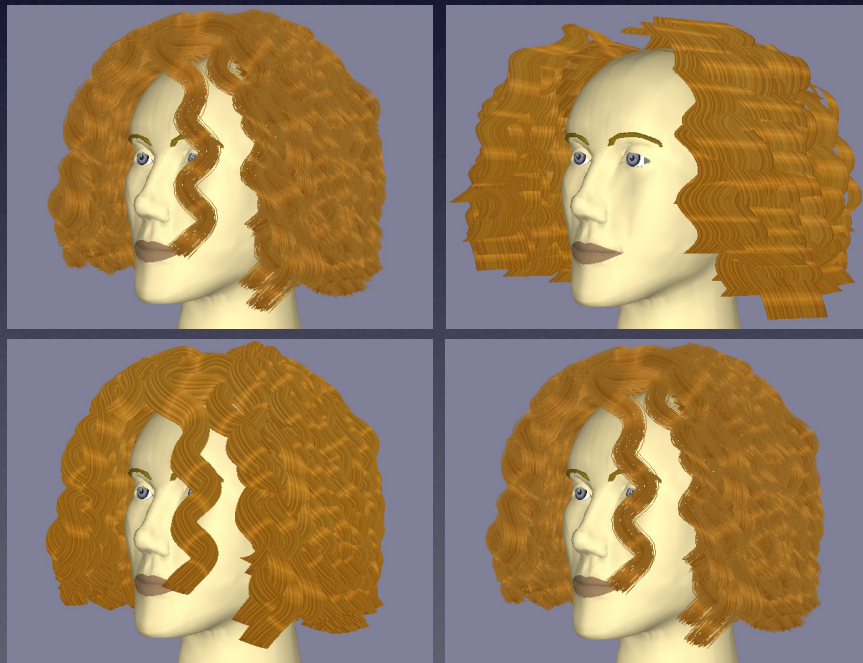
Approximate the shape of a wisp during motion using parabolic trajectories of particles initially located at the base of each wisp

Alternatively simulate the motion of a typical strand and generate additional strands by adding random displacements

Interactions between individual strands or wisps not considered



Multi-resolution Methods



Level-of-detail Representations

- Three levels of detail to accelerate simulation while maintaining high visual quality

Individual strands represented by subdivision curves

Clusters represented by subdivision swept volumes

Strips represented by subdivision patches

- Create a hair hierarchy using these LODs and collision detection using swept sphere volumes



- Hair hierarchy traversed during simulation to choose appropriate representation and resolution of a given section of hair

Transition automatically to a higher LOD for sections that are most significant based on visibility, viewing distance, or motion

If a section is occluded or out of field-of-view, simulate with the coarsest LOD

As distance decreases or hair moves more drastically, there is more observable detail and need for more detailed simulation



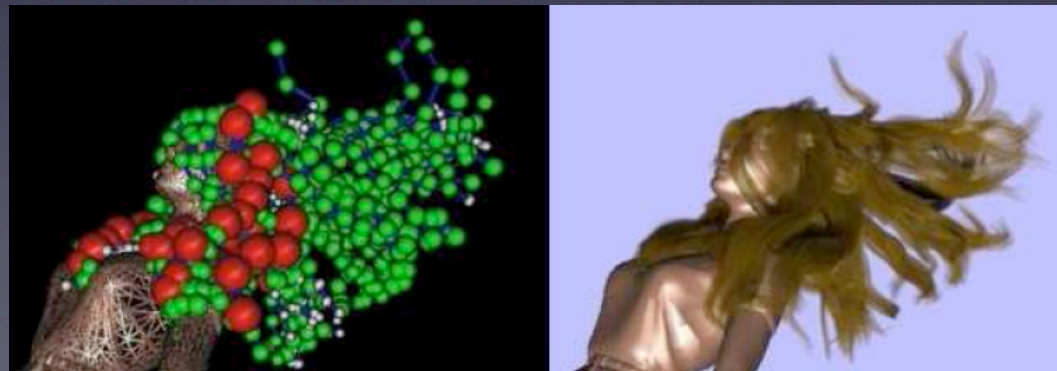
Adaptive Clustering

- Continuously adjust the amount of computation according to local complexity

An adaptive wisp tree represents at each time step the wisp segments of the hierarchy that are simulated

Hair should be more refined near the tips than roots, so AWT dynamically splits or groups wisps while preserving tree-like structure

Implicitly models hair interactions so that neighboring wisps with similar motions merge



Summary

- Hair modeling
- The mechanics of hair
- Dynamics of individual hair strands

Mass-spring systems

One-dimensional projective equations

Rigid multi-body serial chain

- **Simulating the dynamics of a full hairstyle**

- Smooth particle hydrodynamics*

- Loosely connected particles*

- Interpolation between guide hair strands*

- Free form deformation*

- Real-time simulation of hair strips*

- Simulation of wisps*

- **Multi-resolution methods**

- Level-of-detail-representations*

- Adaptive clustering*

References

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