## Pushdown Automata

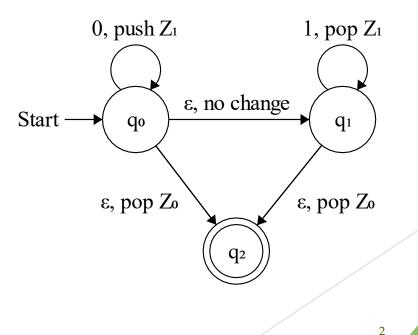
COMP 455 – 002, Spring 2019

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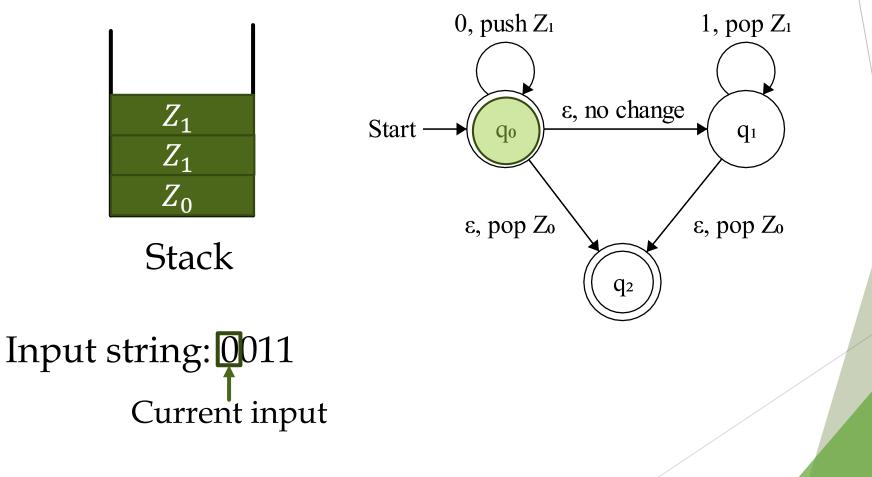
### Pushdown Automata (PDAs)

- A pushdown automaton (PDA) is essentially a finite automaton with a stack.
- Example PDA accepting  $L = \{0^n 1^n | n \ge 0\}$ :

- Initially, the symbol  $Z_0$  is on the stack.
- Acceptance can be by final state or empty stack.



## Example PDA Execution



### Formal Definition of a PDA

A PDA can be defined by a 7-tuple (Q, Σ, Γ,  $\delta$ ,  $q_0$ ,  $Z_0$ , F).

 $\bullet$ *δ*: The transition function:  $Q \times (\Sigma \cup {\varepsilon}) \times \Gamma \rightarrow$ 

- Q: A finite set of states
- **\***Σ: The input alphabet

Takes a state, an input symbol or  $\varepsilon$ , and a stack symbol.

- $\diamond q_0$ : The start state
- ↔*Z*<sup>0</sup> ∈ Γ: The initial stack symbol
- ✤ *F*: The set of accepting states

Returns a set of (state, stack symbol string) pairs.

### Moves in a PDA

 $\delta(q, a, Z) = \{(p_1, \gamma_1, \dots, (p_m, \gamma_m))\} \equiv$ 

If:

. . .

- ► The current state is *q*, and
- ► The current input symbol is *a*, **and**
- ► The symbol *Z* is on the top of the stack

### Moves in a PDA

 $\delta(q, a, Z) = \{(\underline{p_1}, \underline{\gamma_1}), \dots, (\underline{p_m}, \underline{\gamma_m})\} \equiv$ 

If the current state is *q*, the current input symbol is *a*, and the symbol *Z* is on the top of the stack,

**Then** choose a value *i*, (nondeterministic!)

• Enter state  $p_i$ ,

► Replace the symbol on top of the stack with  $\gamma_i$ , and

Advance to the next input symbol.

### *ε*-Transitions in a PDA

$$\delta(q,\varepsilon,Z) = \{(p_1,\gamma_1,\ldots,(p_m,\gamma_m)\} \equiv$$

- The rules here are identical for the states and the stack, but no input is consumed.
  - This adds further nondeterminism.

## Example: PDA Move Notation

$$M = (\{q_0, q_1, q_2\}, \{0, 1\}, \{Z_0, Z_1\}, \delta, q_0, Z_0, \{q_2\})$$

$$\delta(q_0, 0, Z_0) = \{(q_0, Z_1 Z_0)\}$$

$$\delta(q_0, 0, Z_1) = \{(q_0, Z_1 Z_1)\}$$

$$\delta(q_0, \varepsilon, Z_0) = \{(q_2, \varepsilon), (q_1, Z_0)\}$$

$$\delta(q_0, \varepsilon, Z_1) = \{(q_1, Z_1)\}$$

$$\delta(q_1, 1, Z_1) = \{(q_1, \varepsilon)\}$$

$$\delta(q_1, \varepsilon, Z_0) = \{(q_2, \varepsilon)\}$$

$$\delta(q_1, \varepsilon, Z_0) = \{(q_2, \varepsilon)\}$$

Zo

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**q**<sub>2</sub>

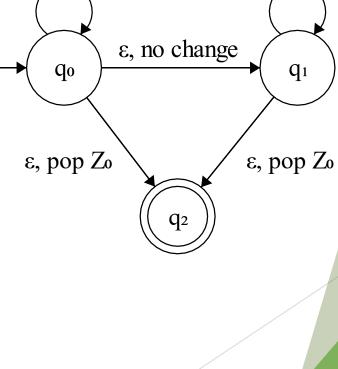
## Instantaneous Description

- An instantaneous description (ID) describes the "global state" of a PDA.
- An instantaneous description is given by  $(q, w, \gamma)$ :
  - � q: The current state
  - *★w*: The remaining input
  - $\diamond \gamma$ : The current contents of the stack
- We write  $(q, aw, Z\alpha) \vdash (p, w, \beta\alpha)$  if  $\delta(q, a, Z)$ contains  $(p, \beta)$ .
- We can also write  $\downarrow_{M}^{i} \downarrow_{M}^{*} \downarrow_{N}^{*} \downarrow_{N}^{*}$ ,  $\downarrow_{N}^{*} \downarrow_{N}^{*}$ ,  $\downarrow_{N}^{*} \downarrow_{N}^{*}$ .

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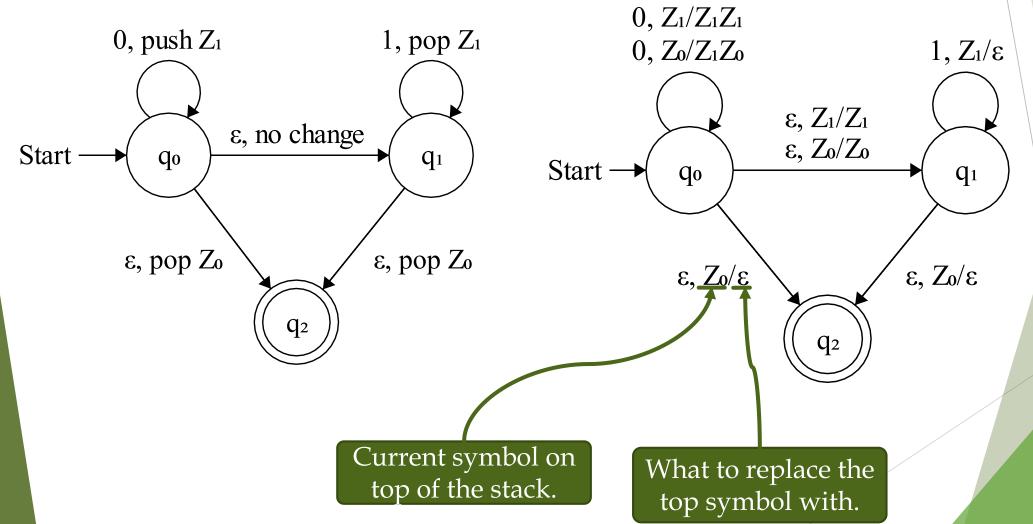
### Instantaneous Description Example

 $(q_{0}, 0011, Z_{0}) \vdash (q_{0}, 011, Z_{1}Z_{0})$   $\vdash (q_{0}, 11, Z_{1}Z_{1}Z_{0})$   $\vdash (q_{1}, 11, Z_{1}Z_{1}Z_{0})$   $\vdash (q_{1}, \varepsilon, Z_{0})$   $\vdash (q_{2}, \varepsilon, \varepsilon)$   $(q_{0}, 0, push Z_{1})$   $(q_{0}, \varepsilon, no c)$   $(q_{0}, \varepsilon, no c)$   $(q_{1}, \varepsilon, Z_{0})$   $(q_{1}, \varepsilon, Z_{0})$   $(q_{1}, \varepsilon, Z_{0})$   $(q_{2}, \varepsilon, \varepsilon)$ 



1, pop  $Z_1$ 

### Formalizing Graphical Notation

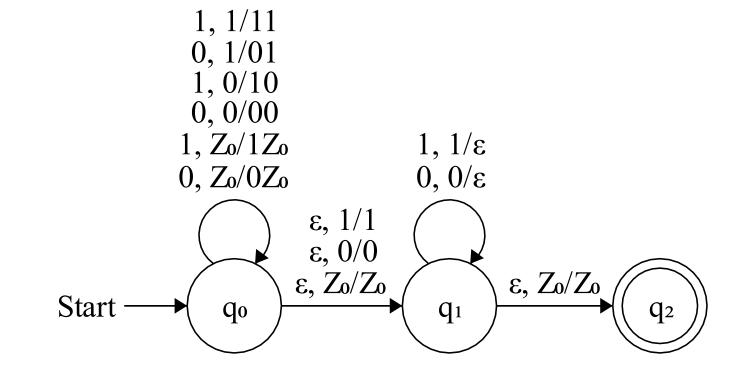


## The Language of a PDA

Let *M* be a PDA:  $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$ *M* defines *two* (possibly different) languages: ▶ The language accepted by *final state*:  $\bigstar L(M) \equiv \left\{ w \mid (q_0, w, Z_0) \stackrel{*}{\vdash} (p, \varepsilon, \gamma), \ p \in F, \ \gamma \in \Gamma^* \right\}$ ► The language accepted by *empty stack*:  $\bigstar N(M) \equiv \left\{ w \mid (q_0, w, Z_0) \stackrel{*}{\vdash} (p, \varepsilon, \varepsilon), \ p \in Q \right\}$ 

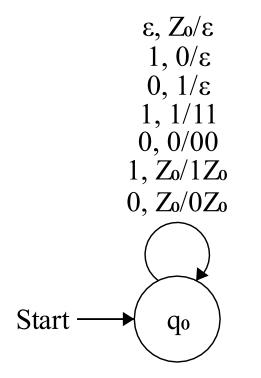
### More PDA Examples

 $L = \{xx^R \mid x \in (\mathbf{0} + \mathbf{1})^*\}$ 



## More PDA Examples

L is the language consisting of strings with an equal number of 0s and 1s.



This accepts by empty stack. (You could also convert it to accept by final state, instead.)

### Converting Empty Stack → Final State

**Theorem 6.9**: If  $L = N(P_N)$  for some PDA  $P_N$ , then  $L = L(P_F)$  for some PDA  $P_F$ .

**Proof**:

• Let  $P_N = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \phi)$ 

*P<sub>N</sub>*: Accepts by empty stack *P<sub>F</sub>*: Accepts by final state

Accepting states are unnecessary when accepting by empty stack.

► Then,  $P_F = (Q \cup \{p_0, p_f\}, \Sigma, \Gamma \cup \{X_0\}, \delta_F, p_0, X_0, \{p_f\}),$ where...

### Converting Empty Stack → Final State

- $\blacktriangleright \delta_F(p_0, \varepsilon, X_0) = \{(q_0, Z_0 X_0)\}$ 
  - ♦ *P<sub>F</sub>* starts by pushing *P<sub>N</sub>*'s start symbol onto the stack. *P<sub>F</sub>* will find its own start symbol (*X*<sub>0</sub>) on top of the stack only when *P<sub>N</sub>*'s stack is empty.
- For all  $q \in Q$ ,  $a \in \Sigma \cup \{\varepsilon\}$ , and  $\Upsilon \in \Gamma$ ,  $\delta_F(q, a, \Upsilon)$  contains all pairs in  $\delta_N(q, a, \Upsilon)$ .
  - $P_F$  just simulates  $P_N$  after initializing the stack.
- For all  $q \in Q$ ,  $\delta_F(q, \varepsilon, X_0)$  contains  $(p_f, \varepsilon)$ .

\*  $P_F$  can accept by final state whenever  $P_N$  would by empty stack.

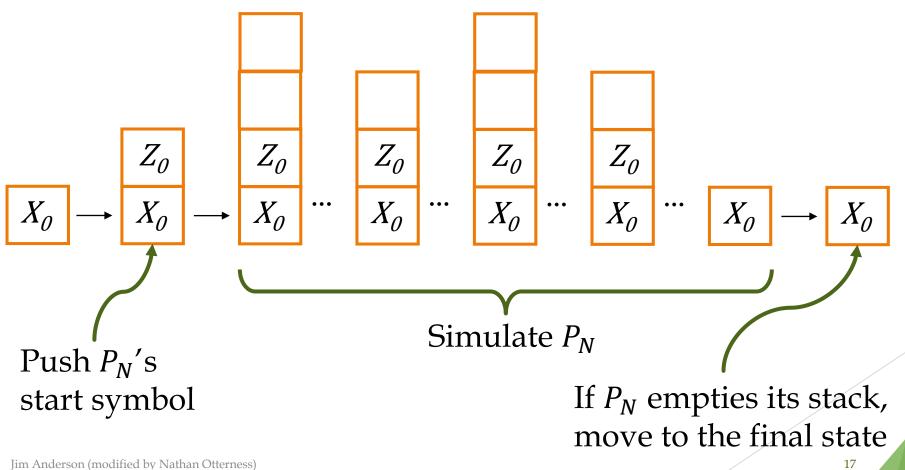
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 $P_{N} = \overline{(Q, \Sigma, \Gamma, \delta, q_{0}, Z_{0}, \emptyset)}$ 

 $P_F = \overline{\left(Q \cup \{p_0, p_f\}, \Sigma, \Gamma \cup \{X_0\}, \delta_F, p_0, X_0, \{p_f\}\right)}$ 

### Converting Empty Stack → Final State

▶ The behavior of  $P_F$  (just showing the stack):



### Converting Final State → Empty Stack

**Theorem 6.11**: If  $L = L(P_F)$  for some PDA  $P_F$ , then  $L = N(P_N)$  for some PDA  $P_N$ .

**Proof**:

• Let 
$$P_F = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

Then,  $P_N = (Q \cup \{p_0, p\}, \Sigma, \Gamma \cup \{X_0\}, \delta_N, p_0, X_0, \emptyset\},$ where...

## *P<sub>F</sub>*: Accepts by final state *P<sub>N</sub>*: Accepts by empty stack

#### Converting Final State → Empty Stack

•  $\delta_N(p_0, \varepsilon, X_0) = \{(q_0, Z_0 X_0)\}.$ 

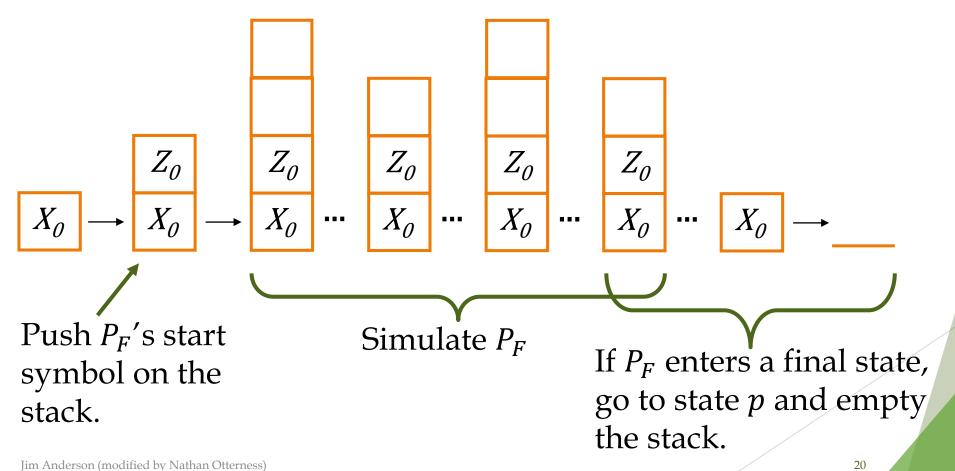
# $P_F = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$ $P_N = (Q \cup \{p_0, p\}, \Sigma, \Gamma \cup \{X_0\}, \delta_N, p_0, X_0, \emptyset\}$

- ♦  $P_N$  starts by pushing  $P_F$ 's start symbol onto the stack.  $X_0$  ensures that  $P_N$  doesn't prematurely clear the stack.
- ► For all  $q \in Q$ ,  $a \in \Sigma \cup \{\varepsilon\}$ , and  $\Upsilon \in \Gamma$ ,  $\delta_F(q, a, \Upsilon)$  contains all pairs in  $\delta_N(q, a, \Upsilon)$ .
  - $P_N$  simulates  $P_F$  after initializing the stack.
- ► For all  $q \in F$ ,  $\Upsilon \in \Gamma \cup X_0$ ,  $\delta_N(q, \varepsilon, \Upsilon)$  contains  $(p, \varepsilon)$ .
  - ✤ If  $P_F$  can accept by final state,  $P_N$  can begin emptying the stack.
- ► For all  $\Upsilon \in \Gamma \cup X_0$ ,  $\delta_N(p, \varepsilon, \Upsilon) = \{(p, \varepsilon)\}$ .

## \* $P_N$ continues to empty its stack until it is completely empty.

### Converting Final State → Empty Stack

• The behavior of  $P_N$  (just showing the stack):



## Converting CFGs to PDAs

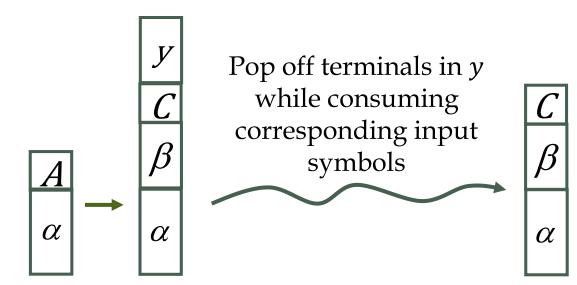
Given a CFG *G*, we will construct a PDA that simulates *leftmost derivations* in *G*.

Main ideas:

- Each left-sentential form of *G* is of the form  $xA\alpha$ , where:
  - ✤ *x* is all terminals,
  - ✤ A is the variable that will be replaced in the next derivation step, and
  - \*  $\alpha$  is some string that can include both variables and terminals.
- ▶ If you look at the "state" of the PDA at this point,
  - \*  $A\alpha$  will be on its stack, and
  - Input *x* will have already been consumed.

## Converting CFGs to PDAs

Apply the production  $A \rightarrow yC\beta$  like this:



Replace *A* (on top of the stack) with all of the terminals and variables it produces.

## Example PDA Execution for a CFG

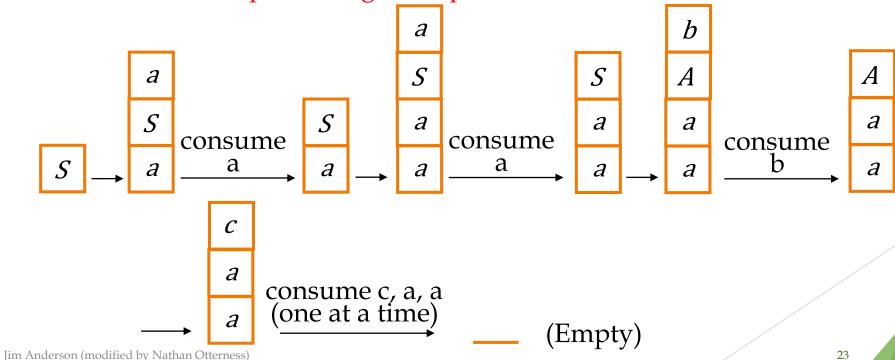
**Productions**:

- $S \rightarrow SS \mid \varepsilon \mid aSa \mid bA$
- $A \rightarrow c$

**PDA transition function**:

- $\delta(q,\varepsilon,S) = \{(q,SS), (q,\varepsilon), (q,aSa), (q,bA)\}$
- $\delta(q,\varepsilon,A) = \{(q,c)\}$
- $\delta(q, d, d) = \{(q, \varepsilon)\}$ , where  $d \in \{a, b, c\}$

**A LM derivation**:  $S \Rightarrow aSa \Rightarrow aaSaa \Rightarrow aabAaa \Rightarrow aabcaa$ . The PDA's stack when processing the input *aabcaa*:



### Formal Definition of a PDA for a CFG

Define a PDA *P* accepting the language defined by CFG *G*:

$$\blacktriangleright P = (\{q\}, T, V \cup T, \delta, q, S, \emptyset)$$

•  $\delta$  is defined by:

**\* Rule 1**: For each variable *A*:  $\delta(q, \varepsilon, A) = \{(q, \beta) | A → \beta \text{ is a production}\}$ 

**\* Rule 2**: For each terminal *a*:  $\delta(q, a, a) = \{(q, \varepsilon)\}$ 

Note: this means that any CFG can be accepted by a PDA (by empty stack) with only one state.

Reminder:
PDA definition: (Q, Σ, Γ, δ, q<sub>0</sub>, Z<sub>0</sub>, F)
CFG definition: (V, T, S, P)

**Theorem 6.13**: N(P) = L(G), where *P* and *G* are defined as before.

**Proof**: We will show that *w* is in N(P) if and only if it is in L(G).

"If": If *w* is in *L*(*G*) then it has a LM derivation  $S = \gamma_1 \underset{lm}{\Rightarrow} \gamma_2 \underset{lm}{\Rightarrow} \dots \underset{lm}{\Rightarrow} \gamma_n = w.$ We will show by induction on *i* that  $(q, w, S) \vdash (q, y_i, \alpha_i)$ , where  $\gamma_i = x_i \alpha_i$ , and  $x_i y_i = w.$ 

Shorthand for the language

of *P* accepted by empty stack.

**Base case**: i = 1, so  $\gamma_1 = S$ . This means  $x_1 = \varepsilon$ ,  $y_1 = w$ , and  $\alpha_1 = S$ . So,  $(q, w, S) \vdash (q_1, y_1, \alpha_1)$ .

**Inductive step**: Assume  $(q, w, S) \vdash (q, y_i, \alpha_i)$  by the inductive hypothesis. We need to show that  $(q, w, S) \vdash (q, y_{i+1}, \alpha_{i+1}).$ 

Reminder: After simulating the derivation up to  $\gamma_i$ ,  $y_i$  is the unconsumed input and  $\alpha_i$  is the stack contents.

We need to show that *P* can make moves that simulate the next step.

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This follows from the definition of  $\delta$ :

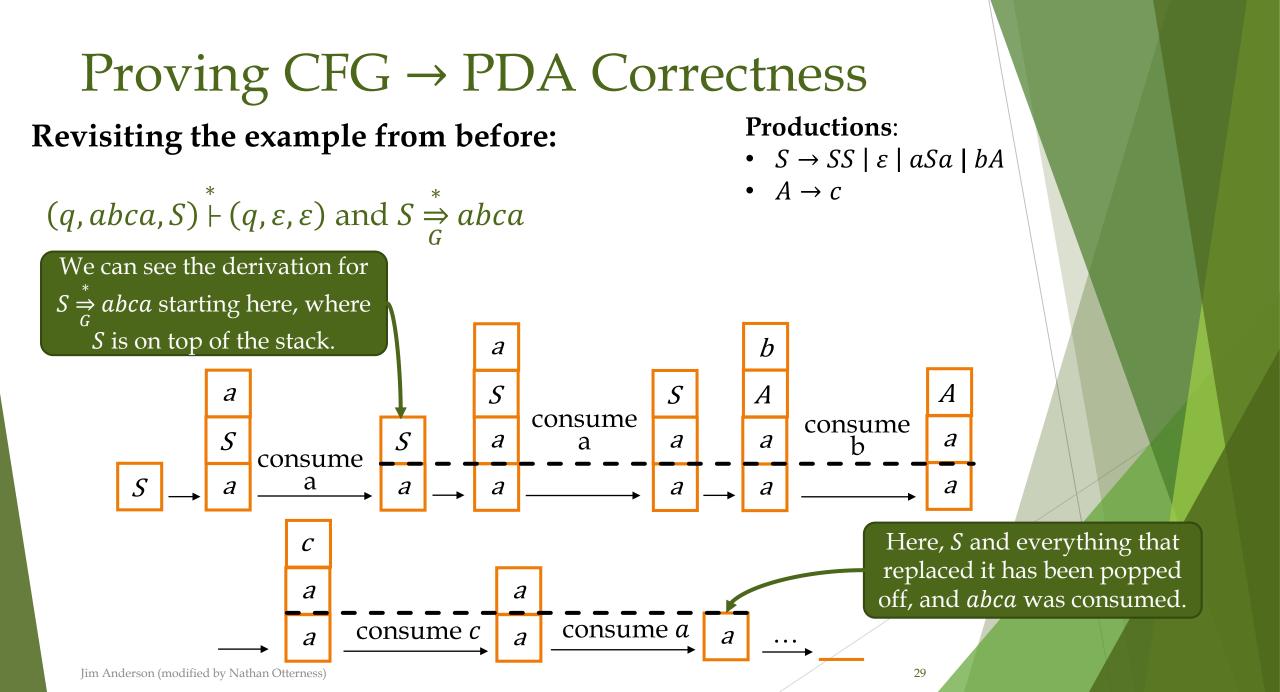
- $\alpha_i$  is of the form *A* ..., where *A* is a variable.
- The derivation step  $\gamma_i \Rightarrow \gamma_{i+1}$  involves replacing *A* by some string  $\beta$ .
- By Rule 1 in the definition of δ, we can replace A by β on top of the stack.
- By Rule 2 in the definition of δ, any leading terminals in β can be popped off the stack and the corresponding input consumed.

"Only if": We want to prove that if w is in N(M), then w is in L(G). To do so, we prove something more general:

### **Claim**: If $(q, x, A) \stackrel{*}{\vdash} (q, \varepsilon, \varepsilon)$ , then $A \stackrel{*}{\underset{G}{\Rightarrow}} x$ .

In words: Consider running *P* when *A* is on top of the stack, and continue running until *A* (and anything that replaced it) has been popped off the stack. If *x* is the string of input symbols consumed while doing this, then *x* is derivable from *A*.

**Example**: From the example PDA,  $(q, abca, S) \vdash (q, \varepsilon, \varepsilon)$  and  $\stackrel{*}{S} \stackrel{*}{\Rightarrow} abca$ .



**Claim**: If  $(q, x, A) \stackrel{*}{\vdash} (q, \varepsilon, \varepsilon)$ , then  $A \stackrel{*}{\underset{G}{\Rightarrow}} x$ .

We will prove this by induction on the number of moves made by *P*.

**Base case**: *P* makes one move. *A* can be popped off the stack directly only if  $A \rightarrow \varepsilon$  is a production (in which case  $x = \varepsilon$ ). In this case, the claim that  $A \Rightarrow_{G}^{*} \varepsilon$  follows.

**Claim:** If  $(q, x, A) \stackrel{*}{\vdash} (q, \varepsilon, \varepsilon)$ , then  $A \stackrel{*}{\Rightarrow}_{G} x$ .

**Inductive step**: Consider *n* moves, and assume that the claim is true for fewer than *n* moves.

The first move must be defined because of a production of the form  $A \rightarrow Y_1 Y_2 \dots Y_k$ , where each  $Y_i$  is either a variable or terminal.

If *Y*<sub>1</sub> is a terminal symbol, then the only thing that *P* can do is pop it off the stack and consume the corresponding symbol in the input.

Claim:

 $(q, x, A) \vdash (q, \varepsilon, \varepsilon)$ , then  $A \stackrel{*}{\Rightarrow} x$ 

#### Inductive step, continued:

The first move must be defined because of a production of the form  $A \rightarrow Y_1 Y_2 \dots Y_k$ , where each  $Y_i$  is either a variable or terminal.

If  $Y_1$  is a variable, then consider the behavior of *P* until  $Y_1$ , or whatever ends up replacing it, is erased from the stack. If  $y_1$  is the string of input symbols consumed while doing this, then by the inductive hypothesis  $Y_1 \Rightarrow y_1$ .

In turn, this argument can be applied to  $Y_2 \dots Y_k$ .

Claim:

 $(q, x, A) \vdash (q, \varepsilon, \varepsilon)$ , then  $A \stackrel{*}{\Rightarrow} x$ 

From the previous slide, it follows that  $x = x_1 x_2 \dots x_k$ , where  $x_i = Y_i$  if  $Y_i$  is a terminal and  $x_i = y_i$  if  $Y_i$  is a variable. By concatenating these various derivations, we have  $A \Rightarrow x$ . Claim:

 $(q, x, A) \vdash (q, \varepsilon, \varepsilon)$ , then  $A \stackrel{*}{\Rightarrow} x$ 

## Converting PDAs to CFGs

**Theorem 6.14**: If L = N(P) for some PDA *P*, then L = L(G) for some CFG *G*.

**Proof**:

Let  $P = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, \emptyset)$ .

Define  $G = (V, \Sigma, R, S)$  such that V contains [qXp] for all  $q, p \in Q$ , and all  $X \in \Gamma$ .

*R* is defined on the next slide...

These symbols will end up generating all strings that cause *X* to be popped from the stack while moving from state *q* to *p*.

## Converting PDAs to CFGs

*R* is defined as follows:

- ►  $S \rightarrow [q_0 Z_0 p]$ , for all  $p \in Q$ .
- If  $\delta(q, a, X)$  contains  $(r, Y_1Y_2 \dots Y_k)$ , then *R* contains the rule  $[qXr_k] \rightarrow a[rY_1r_1][r_1Y_2r_2] \dots [r_{k-1}Y_kr_k]$ .

a is an input symbol or  $\varepsilon$ 

X and each  $Y_i$  are stack symbols

- *r*<sub>1</sub>, *r*<sub>2</sub>, ... *r<sub>k</sub>* can be any list of states, so we need to add a production rule for *all possible lists* of *k* states.
- If  $\delta(q, a, X)$  contains  $(r, \varepsilon)$ , then *R* contains the rule  $[qXr] \rightarrow a$ .

### Intuition Behind PDA→CFG Method

A leftmost derivation in *G* of a string *w* simulates *P* with *w* as an input.

$$S \stackrel{*}{\underset{lm}{\Rightarrow}} 00[q_0 X q_1][q_1 X q_1][q_1 Z_0 q_1] \stackrel{*}{\underset{lm}{\Rightarrow}} 00011$$

(This comes from the example in the following slides).

#### Intuition Behind PDA→CFG Method

A leftmost derivation in *G* of a string *w* simulates *P* with *w* as an input.

 $S \xrightarrow{r}_{lm} 00 [q_0 X q_1] [q_1 X q_1] [q_1 Z_0 q_1] \xrightarrow{*}_{lm} 00011$ 

*P*'s current state

The state *P* will be in after *X* or the symbols that replace *X* have been erased from the stack.

The input

consumed by *P* 

#### Intuition Behind PDA→CFG Method

A leftmost derivation in *G* of a string *w* simulates *P* with *w* as an input.

$$S \stackrel{*}{\underset{lm}{\Rightarrow}} 00[q_0 X q_1][q_1 X q_1][q_1 Z_0 q_1] \stackrel{*}{\underset{lm}{\Rightarrow}} 00011$$

*P*'s current stack: *XXZ*<sub>0</sub>

► We will convert the following PDA *P* to a CFG.

$$N(P) = \{ 0^{i} 1^{j} \mid i \ge j \ge 1 \}.$$

$$P = (\{q_{0}, q_{1}\}, \{0, 1\}, \{X, Z_{0}\}, \delta, q_{0}, Z_{0}, \emptyset)$$

$$\delta(q_{0}, 0, Z_{0}) = \{(q_{0}, XZ_{0})\}$$

$$\delta(q_{0}, 0, X) = \{(q_{0}, XX)\}$$

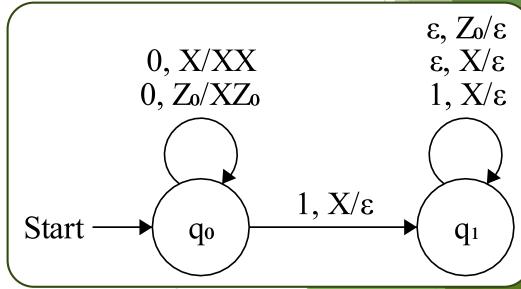
$$\delta(q_{0}, 1, X) = \{(q_{1}, \varepsilon)\}$$

$$\delta(q_{1}, 1, X) = \{(q_{1}, \varepsilon)\}$$

$$\delta(q_{1}, \varepsilon, X) = \{(q_{1}, \varepsilon)\}$$

$$\delta(q_{1}, \varepsilon, Z_{0}) = \{(q_{1}, \varepsilon)\}$$

$$State$$



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The variables in the CFG created from this example PDA will be:

 $V = \{ [q_0 X q_0], [q_0 X q_1], [q_1 X q_0], [q_1 X q_1], [q_0 Z_0 q_0], [q_0 Z_0 q_1], [q_1 Z_0 q_0], [q_1 Z_0 q_1] \}$ 

► Production rules from the start state *S*:  $*S \rightarrow [q_0 Z_0 q_0]$  $*S \rightarrow [q_0 Z_0 q_1]$   $\delta(q_0, 0, Z_0) = \{(q_0, XZ_0)\}$   $\delta(q_0, 0, X) = \{(q_0, XX)\}$   $\delta(q_0, 1, X) = \{(q_1, \varepsilon)\}$   $\delta(q_1, 1, X) = \{(q_1, \varepsilon)\}$   $\delta(q_1, \varepsilon, X) = \{(q_1, \varepsilon)\}$  $\delta(q_1, \varepsilon, Z_0) = \{(q_1, \varepsilon)\}$ 

▶ Production rules from  $\delta(q_0, 0, Z_0) = \{(q_0, XZ_0)\}$ :  $\diamond [q_0 Z_0 q_0] \rightarrow 0 [q_0 X q_0] [q_0 Z_0 q_0]$  $\Box r_1 = q_0$  and  $r_2 = q_0$  $\Rightarrow [q_0 Z_0 q_1] \rightarrow 0[q_0 X q_0][q_0 Z_0 q_1]$  $\Box r_1 = q_0$  and  $r_2 = q_1$  $\Rightarrow [q_0 Z_0 q_0] \rightarrow 0[q_0 X q_1][q_1 Z_0 q_0]$  $\Box r_1 = q_1 \text{ and } r_2 = q_0$  $\Rightarrow [q_0 Z_0 q_1] \rightarrow 0[q_0 X q_1][q_1 Z_0 q_1]$  $\Box r_1 = q_1 \text{ and } r_2 = q_1$ 

 $\delta(q_0, 0, Z_0) = \{(q_0, XZ_0)\}$   $\delta(q_0, 0, X) = \{(q_0, XX)\}$   $\delta(q_0, 1, X) = \{(q_1, \varepsilon)\}$   $\delta(q_1, 1, X) = \{(q_1, \varepsilon)\}$   $\delta(q_1, \varepsilon, X) = \{(q_1, \varepsilon)\}$  $\delta(q_1, \varepsilon, Z_0) = \{(q_1, \varepsilon)\}$ 

▶ Production rules from  $\delta(q_0, 0, Z_0) = \{(q_0, XZ_0)\}$ :  $\diamond [q_0 Z_0 q_0] \rightarrow 0 [q_0 X q_0] [q_0 Z_0 q_0]$  $\Box r_1 = q_0$  and  $r_2 = q_0$  $*[q_0Z_0q_1] \to 0[q_0Xq_0][q_0Z_0q_1]$  $\Box r_1 = q_0$  and  $r_2 = q_1$  $\Rightarrow [q_0 Z_0 q_0] \rightarrow 0[q_0 X q_1][q_1 Z_0 q_0]$  $\Box r_1 = q_1 \text{ and } r_2 = q_0$  $*[q_0Z_0q_1] \to 0[q_0Xq_1][q_1Z_0q_1]$  $\Box r_1 = q_1$  and  $r_2 = q_1$ 

$$\begin{split} \delta(q_0, 0, Z_0) &= \{(q_0, XZ_0)\} \\ \delta(q_0, 0, X) &= \{(q_0, XX)\} \\ \delta(q_0, 1, X) &= \{(q_1, \varepsilon)\} \\ \delta(q_1, 1, X) &= \{(q_1, \varepsilon)\} \\ \delta(q_1, \varepsilon, X) &= \{(q_1, \varepsilon)\} \\ \delta(q_1, \varepsilon, Z_0) &= \{(q_1, \varepsilon)\} \end{split}$$

These four rules are due to the number of possible lists of  $r_1, ..., r_k$ . In this case k = 2, and we have two states, so we end up with four possible lists containing two states.

▶ Production rules from  $\delta(q_0, 0, X) = \{(q_0, XX)\}$ :  $\diamond [q_0 X q_0] \rightarrow 0 [q_0 X q_0] [q_0 X q_0]$  $\Box r_1 = q_0$  and  $r_2 = q_0$  $\diamond [q_0 X q_1] \rightarrow 0 [q_0 X q_0] [q_0 X q_1]$  $\Box r_1 = q_0 \text{ and } r_2 = q_1$  $\diamond [q_0 X q_0] \rightarrow 0 [q_0 X q_1] [q_1 X q_0]$  $\Box r_1 = q_1 \text{ and } r_2 = q_0$  $\diamond [q_0 X q_1] \rightarrow 0 [q_0 X q_1] [q_1 X q_1]$  $\Box r_1 = q_1 \text{ and } r_2 = q_1$ 

Jim Anderson (modified by Nathan Otterness)

$$\begin{split} \delta(q_0, 0, Z_0) &= \{(q_0, XZ_0)\} \\ \delta(q_0, 0, X) &= \{(q_0, XX)\} \\ \delta(q_0, 1, X) &= \{(q_1, \varepsilon)\} \\ \delta(q_1, 1, X) &= \{(q_1, \varepsilon)\} \\ \delta(q_1, \varepsilon, X) &= \{(q_1, \varepsilon)\} \\ \delta(q_1, \varepsilon, Z_0) &= \{(q_1, \varepsilon)\} \end{split}$$

- ► Production rule from  $\delta(q_0, 1, X) = \{(q_1, \varepsilon)\}$ :  $\Rightarrow [q_0 X q_1] \rightarrow 1$
- ► Production rule from  $\delta(q_1, 1, X) = \{(q_1, \varepsilon)\}$ :
  - $\bigstar[q_1Xq_1]\to 1$
- ► Production rule from  $\delta(q_1, \varepsilon, X) = \{(q_1, \varepsilon)\}$ :

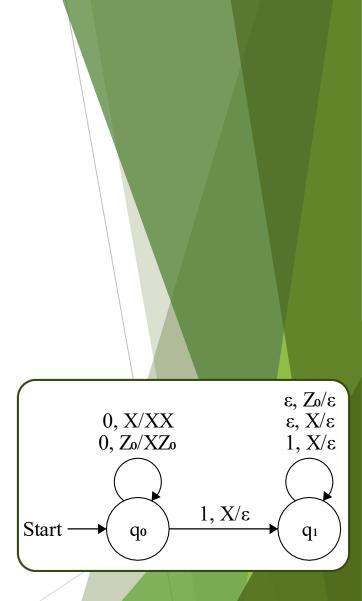
 $\bigstar[q_1Xq_1]\to\varepsilon$ 

► Production rule from  $\delta(q_1, \varepsilon, Z_0) = \{(q_1, \varepsilon)\}$ :

 $\bullet$   $[q_1 Z_0 q_1] \to \varepsilon$ 

 $\delta(q_0, 0, Z_0) = \{(q_0, XZ_0)\}$   $\delta(q_0, 0, X) = \{(q_0, XX)\}$   $\delta(q_0, 1, X) = \{(q_1, \varepsilon)\}$   $\delta(q_1, 1, X) = \{(q_1, \varepsilon)\}$   $\delta(q_1, \varepsilon, X) = \{(q_1, \varepsilon)\}$  $\delta(q_1, \varepsilon, Z_0) = \{(q_1, \varepsilon)\}$ 

- ▶ We now have production rules for every variable except for [q<sub>1</sub>Z<sub>0</sub>q<sub>0</sub>] and [q<sub>1</sub>Xq<sub>0</sub>].
  - ✤ These variables have *no production rules* if they are ever produced we could never replace them with terminals.
  - \* Intuitively, this makes sense because the original PDA can't possibly transition from  $q_1$  to  $q_0$ .
    - □Remember that  $[q_1Xq_0]$  corresponds to *P* transitioning from  $q_1$  to  $q_0$  while popping *X* off the stack.



- $\blacktriangleright S \rightarrow [q_0 Z_0 q_0]$
- ►  $S \rightarrow [q_0 Z_0 q_1]$
- $\blacktriangleright [q_0 Z_0 q_0] \rightarrow 0[q_0 X q_0][q_0 Z_0 q_0] \blacktriangleright [q_1 X q_1] \rightarrow 1$
- $\blacktriangleright \ [q_0 Z_0 q_1] \rightarrow 0[q_0 X q_0][q_0 Z_0 q_1] \ \blacktriangleright \ [q_1 X q_1] \rightarrow \varepsilon$
- $\blacktriangleright \ [q_0 Z_0 q_0] \rightarrow 0 [q_0 X q_1] [q_1 Z_0 q_0] \ \blacktriangleright \ [q_1 Z_0 q_1] \rightarrow \varepsilon$
- $\blacktriangleright \ [q_0 Z_0 q_1] \to 0 [q_0 X q_1] [q_1 Z_0 q_1]$
- $\blacktriangleright [q_0 X q_0] \rightarrow 0 [q_0 X q_0] [q_0 X q_0]$
- $\blacktriangleright [q_0 X q_1] \rightarrow 0[q_0 X q_0][q_0 X q_1]$
- $\blacktriangleright \ [q_0 X q_0] \rightarrow 0 [q_0 X q_1] [q_1 X q_0]$

This technique can result in many *useless* productions, which are either unreachable or will never lead to a terminal string.

 $\blacktriangleright$   $[q_0 X q_1] \rightarrow 0[q_0 X q_1][q_1 X q_1]$ 

 $\blacktriangleright$   $[q_0 X q_1] \rightarrow 1$ 

- $\blacktriangleright S \rightarrow [q_0 Z_0 q_0]$
- ►  $S \rightarrow [q_0 Z_0 q_1]$
- $\blacktriangleright [q_0 Z_0 q_0] \rightarrow 0[q_0 X q_0][q_0 Z_0 q_0] \blacktriangleright [q_1 X q_1] \rightarrow 1$
- $\blacktriangleright \ [q_0 Z_0 q_1] \rightarrow 0 [q_0 X q_0] [q_0 Z_0 q_1] \ \blacktriangleright \ [q_1 X q_1] \rightarrow \varepsilon$
- $\blacktriangleright \ [q_0 Z_0 q_0] \rightarrow 0[q_0 X q_1][q_1 Z_0 q_0] \ \blacktriangleright \ [q_1 Z_0 q_1] \rightarrow \varepsilon$
- $\blacktriangleright \ [q_0 Z_0 q_1] \to 0 [q_0 X q_1] [q_1 Z_0 q_1]$
- $\blacktriangleright [q_0 X q_0] \rightarrow 0 [q_0 X q_0] [q_0 X q_0]$
- $\blacktriangleright [q_0 X q_1] \rightarrow 0[q_0 X q_0][q_0 X q_1]$
- $\blacktriangleright \ [q_0 X q_0] \rightarrow 0[q_0 X q_1][q_1 X q_0]$

We know that  $[q_1Z_0q_0]$  and  $[q_1Xq_0]$  can never lead to terminals due to having no productions, so any production of these variables is useless.

 $\blacktriangleright$   $[q_0 X q_1] \rightarrow 0[q_0 X q_1][q_1 X q_1]$ 

 $\blacktriangleright$   $[q_0 X q_1] \rightarrow 1$ 

- $\blacktriangleright S \rightarrow [q_0 Z_0 q_0]$
- ►  $S \rightarrow [q_0 Z_0 q_1]$
- $\blacktriangleright \ [q_0 Z_0 q_0] \rightarrow 0[q_0 X q_0][q_0 Z_0 q_0] \ \blacktriangleright \ [q_1 X q_1] \rightarrow 1$
- $\blacktriangleright \ [q_0 Z_0 q_1] \rightarrow 0[q_0 X q_0][q_0 Z_0 q_1] \ \blacktriangleright \ [q_1 X q_1] \rightarrow \varepsilon$
- $\blacktriangleright \ [q_0 Z_0 q_0] \rightarrow 0 [q_0 X q_1] [q_1 Z_0 q_0] \ \blacktriangleright \ [q_1 Z_0 q_1] \rightarrow \varepsilon$
- $\blacktriangleright \ [q_0 Z_0 q_1] \to 0 [q_0 X q_1] [q_1 Z_0 q_1]$
- $\blacktriangleright [q_0 X q_0] \rightarrow 0 [q_0 X q_0] [q_0 X q_0]$
- $\blacktriangleright [q_0 X q_1] \rightarrow 0[q_0 X q_0][q_0 X q_1]$
- $\blacktriangleright \ [q_0 X q_0] \rightarrow 0 [q_0 X q_1] [q_1 X q_0]$

 $[q_0Z_0q_0]$  has only one other production, which also produces itself, meaning that  $[q_0Z_0q_0]$  can never be entirely replaced with terminals.

- $\blacktriangleright [q_0 X q_1] \rightarrow 0[q_0 X q_1][q_1 X q_1]$
- ►  $[q_0 X q_1] \rightarrow 1$

- $\blacktriangleright S \rightarrow [q_0 Z_0 q_0]$
- ►  $S \rightarrow [q_0 Z_0 q_1]$
- $\blacktriangleright \ [q_0 Z_0 q_0] \rightarrow 0[q_0 X q_0][q_0 Z_0 q_0] \ \blacktriangleright \ [q_1 X q_1] \rightarrow 1$
- $\blacktriangleright \ [q_0 Z_0 q_1] \rightarrow 0[q_0 X q_0][q_0 Z_0 q_1] \ \blacktriangleright \ [q_1 X q_1] \rightarrow \varepsilon$
- $\blacktriangleright \ [q_0 Z_0 q_0] \rightarrow 0 [q_0 X q_1] [q_1 Z_0 q_0] \ \blacktriangleright \ [q_1 Z_0 q_1] \rightarrow \varepsilon$
- $\blacktriangleright \ [q_0 Z_0 q_1] \to 0 [q_0 X q_1] [q_1 Z_0 q_1]$
- $\blacktriangleright [q_0 X q_0] \rightarrow 0[q_0 X q_0][q_0 X q_0]$
- $\blacktriangleright [q_0 X q_1] \rightarrow 0[q_0 X q_0][q_0 X q_1]$
- $\blacktriangleright \ [q_0 X q_0] \rightarrow 0 [q_0 X q_1] [q_1 X q_0]$

 $[q_0 X q_0]$  has only one remaining production, which only produces itself. So,  $[q_0 X q_0]$  can never be replaced with terminals and is also useless.

 $\blacktriangleright$   $[q_0 X q_1] \rightarrow 0[q_0 X q_1][q_1 X q_1]$ 

 $\blacktriangleright$   $[q_0 X q_1] \rightarrow 1$ 

After removing all of the useless productions, we end up with the following production rules in the grammar:

- $\blacktriangleright S \rightarrow [q_0 Z_0 q_1]$
- $\blacktriangleright [q_0 Z_0 q_1] \to 0 [q_0 X q_1] [q_1 Z_0 q_1]$
- $\blacktriangleright [q_0 X q_1] \rightarrow 0 [q_0 X q_1] [q_1 X q_1]$
- $\blacktriangleright [q_0 X q_1] \rightarrow 1$
- $\blacktriangleright [q_1 X q_1] \to 1$
- $\blacktriangleright [q_1 X q_1] \to \varepsilon$
- $\blacktriangleright [q_1 Z_0 q_1] \to \varepsilon$

Remember that the language of the PDA and CFG is  $\{0^i 1^j \mid i \ge j \ge 1\}$ . Example string in the language: 001.

Leftmost derivation in the constructed grammar:  $S \Rightarrow [q_0 Z_0 q_1]$  $\Rightarrow 0[q_0 X q_1][q_1 Z_0 q_1]$  $\Rightarrow 00[q_0 X q_1][q_0 X q_1][q_1 Z_0 q_1]$  $\Rightarrow 001[q_0 X q_1][q_1 Z_0 q_1]$  $\Rightarrow 001[q_1 Z_0 q_1]$  $\Rightarrow 001$  Sequence of moves in the original PDA:  $(q_0, 001, Z_0)$  $\vdash (q_0, 01, XZ_0)$  $\vdash (q_0, 1, XXZ_0)$  $\vdash (q_1, \varepsilon, XZ_0)$  $\vdash (q_1, \varepsilon, Z_0)$  $\vdash (q_1, \varepsilon, \varepsilon)$   $S \rightarrow [q_0 Z_0 q_1]$   $[q_0 Z_0 q_1] \rightarrow 0[q_0 X q_1][q_1 Z_0 q_1]$   $[q_0 X q_1] \rightarrow 0[q_0 X q_1][q_1 X q_1]$   $[q_0 X q_1] \rightarrow 1$   $[q_1 X q_1] \rightarrow 1$   $[q_1 X q_1] \rightarrow \varepsilon$   $[q_1 Z_0 q_1] \rightarrow \varepsilon$ 

$$\begin{split} &\delta(q_0, 0, Z_0) = \{(q_0, XZ_0)\} \\ &\delta(q_0, 0, X) = \{(q_0, XX)\} \\ &\delta(q_0, 1, X) = \{(q_1, \varepsilon)\} \\ &\delta(q_1, 1, X) = \{(q_1, \varepsilon)\} \\ &\delta(q_1, \varepsilon, X) = \{(q_1, \varepsilon)\} \\ &\delta(q_1, \varepsilon, Z_0) = \{(q_1, \varepsilon)\} \end{split}$$

We will prove that our construction is correct by first proving that the variables mean what we say they do.

**Claim**:  $[qXp] \stackrel{*}{\underset{G}{\Rightarrow}} w$  if and only if  $(q, w, X) \stackrel{*}{\underset{P}{\vdash}} (p, \varepsilon, \varepsilon)$ .

Remember that this is the condition for determining *w*'s membership in the language of a PDA by empty stack.

"We can derive w from [qXp] if and only if we can move from state q to p while consuming w and popping X from the stack."

► Special case:  $[q_0 Z_0 p] \stackrel{*}{\Rightarrow} w$  if and only if  $(q_0, w, Z_0) \stackrel{*}{\vdash} (p, \varepsilon, \varepsilon)$ 

▶ Because  $S \Rightarrow [q_0 Z_0 p]$  (by our construction), this implies  $w \in L(G)$  if and only if  $w \in N(P)$ .

**Claim** (again):  $[qXp] \stackrel{*}{\Rightarrow} w$  if and only if  $(q, w, X) \stackrel{*}{\vdash} (p, \varepsilon, \varepsilon)$ . **"If"**: We show by induction on the number of PDA moves that  $(q, w, X) \stackrel{i}{\vdash} (p, \varepsilon, \varepsilon)$  implies  $[qXp] \stackrel{*}{\Rightarrow} w$ .

**Base case**: i = 1. This means that  $w \in \Sigma \cup \{\varepsilon\}$ .

The only way the PDA can accept a string in one step is if the string is a single symbol or  $\varepsilon$ .

 $\delta(q, w, X)$  must contain  $(p, \varepsilon)$ . Therefore,  $[qXp] \rightarrow w$  is a production due to our construction of the CFG.

$$[qXp] \stackrel{*}{\underset{G}{\Rightarrow}} w \text{ if and only if } (q, w, X) \stackrel{*}{\underset{P}{\mapsto}} (p, \varepsilon, \varepsilon)$$

"If", Inductive step: *i* steps, where i > 1.

$$(q, ax, X) \vdash (r_0, x, Y_1 \dots Y_k) \stackrel{*}{\vdash} (p, \varepsilon, \varepsilon)$$

★ This means that (r<sub>0</sub>, Y<sub>1</sub> ... Y<sub>k</sub>) ∈ δ(q, a, X), so the CFG will have a production [qXr<sub>k</sub>] → a[r<sub>0</sub>Y<sub>1</sub>r<sub>1</sub>] ... [r<sub>k-1</sub>Y<sub>k</sub>r<sub>k</sub>], where
□ r<sub>k</sub> = p, and

 $\Box$   $r_1, r_2 \dots r_{k-1}$  are any states in Q.

"If", Inductive step, continued

- $(q, ax, X) \vdash (r_0, x, Y_1 \dots Y_k) \stackrel{*}{\vdash} (p, \varepsilon, \varepsilon)$ 
  - ♦ We have a production  $[qXr_k] \rightarrow a[r_0Y_1r_1] \dots [r_{k-1}Y_kr_k]$ , where

 $\Box$   $r_k = p$ , and

- $\Box$   $r_1, r_2 \dots r_{k-1}$  are any states in Q.
- For each  $Y_i$  in  $Y_1 \dots Y_k$ :
  - ★ Let  $r_i$  be the state of the PDA when  $Y_i$  is popped off the stack.
  - ◆ Let  $w_i$  be the input consumed when popping  $Y_i$  off the stack.
    - $\Box$  In this example,  $x = w_1 \dots w_k$
  - ◆ Putting the above points another way,  $(r_{i-1}, w_i, Y_i) \vdash (r_i, \varepsilon, \varepsilon)$ .
- Any set of moves going from  $r_{i-1}$  to  $r_i$  will take fewer than n moves, so the inductive hypothesis tells us that  $[r_{i-1}Y_ir_i] \Rightarrow w_i$ .
- Therefore,  $a[r_0Y_1r_1] \dots [r_{k-1}Y_kr_k] \stackrel{*}{\Rightarrow} aw_1 \dots w_k = ax = w.$

**Claim** (again):  $[qXp] \stackrel{*}{\Rightarrow} w$  if and only if  $(q, w, X) \stackrel{*}{\vdash} (p, \varepsilon, \varepsilon)$ . **"Only if"**: We show by induction on the number of derivation steps that  $[qXp] \stackrel{i}{\Rightarrow} w$  implies  $(q, w, X) \stackrel{*}{\vdash} (p, \varepsilon, \varepsilon)$ .

**Base case**: i = 1.  $[qXp] \rightarrow w$ , where  $w \in \Sigma \cup \{\varepsilon\}$ . From the construction of the CFG, we know that  $\delta(q, w, X)$  must contain  $(p, \varepsilon)$ .

Proving PDA→CFG Correctness "Only if" claim:  $[qXp] \stackrel{i}{\Rightarrow} w$  implies  $(q, w, X) \stackrel{*}{\vdash} (p, \varepsilon, \varepsilon)$  $r_k = p$ **Inductive step**: i > 1.  $[qXr_k] \Rightarrow a[r_0Y_1r_1] \dots [r_{k-1}Y_kr_k] \stackrel{i-1}{\Longrightarrow} w.$ Let  $w = aw_1w_2 \dots w_k$ , where  $[r_{i-1}Y_ir_i] \xrightarrow{w} w_j$  and  $1 \le i \le k$ . By the inductive hypothesis,  $(r_{i-1}, w_i, Y_i) \vdash (r_i, \varepsilon, \varepsilon)$ , and  $1 \leq i \leq k$ . Therefore,  $(r_{i-1}, w_i, Y_i Y_{i+1} \dots Y_k) \vdash (r_i, \varepsilon, Y_{i+1} \dots Y_k)$ From the first step of the derivation,  $(q, w, X) \vdash (r_0, w_1 \dots w_k, Y_1 \dots Y_k)$ . So,  $(q, w, X) \vdash (p, \varepsilon, \varepsilon)$ .

#### Deterministic PDAs

A PDA  $P = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$  is **deterministic** if and only if:

- 1.  $\delta(q, a, X)$  has at most one member for any  $q \in Q$ ,  $a \in \Sigma \cup \{\varepsilon\}$ , and  $X \in \Gamma$ .
- 2. If  $\delta(q, a, X)$  is nonempty for some  $a \in \Sigma$ , then  $\delta(q, \varepsilon, X)$  must be empty.
- ► Deterministic PDAs (DPDAs) are useful in parsing.
- Unlike DFAs, which are just as powerful as NFAs, DPDAs are *less powerful than nondeterministic PDAs*.

There is at most one possible transition for every combination of state, input symbol, and stack symbol.

#### Regular Languages and DPDAs

**Theorem 6.17**: If *L* is a regular language, then L = L(P) for some DPDA *P*.

**Proof sketch**: A DFA is a special case of a DPDA in which the stack is not used, i.e., all moves "replace"  $Z_0$  by  $Z_0$ , where  $Z_0$  is the start symbol.

# DPDAs Accepting by Empty Stack

It is impossible for a DPDA that accepts by empty stack to accept both a string *x* and a string *xy*, where  $y \neq \varepsilon$ .

A language *L* has the **prefix property** if there are no two different strings *x* and *y* in *L* such that *x* is a prefix of *y*.

**Theorem 6.19**: A language *L* is N(P) for some DPDA *P* if and only if *L* has the prefix property and *L* is L(P') for some DPDA *P*'.

The DPDA would need to empty its stack while reading *x*, so it would fail when trying to process more input on an empty stack.

#### Relationships Between DPDAs and CFLs

**Theorem**: The languages accepted by DPDAs by final state properly include the regular languages, but are properly included in the context-free languages.

**Proof sketch**: Regular language inclusion (not necessarily *proper* inclusion) is implied by Theorem 6.17 (a regular language must be accepted by some DPDA).

"Proper" inclusion: The superset must have some elements not present in the subset.

#### DPDA Inclusion Proof Sketch, Continued

The fact that regular languages are properly included in the languages of DPDAs is because the language  $\{w2w^R \mid w \in (\mathbf{0} + \mathbf{1})^*\}$  is accepted by a DPDA by final state, but is not a regular language.

The "2" tells the DPDA when to start looking for w<sup>R</sup>, enabling it to be deterministic.

#### DPDA Inclusion Proof Sketch, Continued

The fact that the language of DPDAs is properly included by context-free languages is because the language  $\{ww^R \mid w \in (\mathbf{0} + \mathbf{1})^*\}$  is accepted by a PDA but not by any DPDA.

▶ We will not prove in class that it's impossible for a DPDA to accept this, but the intuition is that the DPDA can't "know" when w ends and w<sup>R</sup> begins.

#### DPDAs and Ambiguous Grammars

**Theorem 6.20**: If L = N(P) for some DPDA *P*, then *L* has an unambiguous CFG.

#### **Proof sketch**:

A CFG is ambiguous if and only if multiple leftmost derivations are possible.

If we apply the previous PDA $\rightarrow$ CFG construction to a DPDA, we will end up with production rules where multiple derivations of the same string aren't possible.

#### DPDAs and Ambiguous Grammars

**Theorem 6.21**: If L = L(P) for some DPDA *P*, then *L* has an unambiguous CFG.

#### **Proof sketch:**

Define L\$ = {x\$ |  $x \in L$ }, and \$ is a new symbol not in L's alphabet. This means that L\$ has the *prefix property*. We can modify P to accept L\$ by final state. Therefore, by Theorem 6.19, L\$ = N(P') for some DPDA P'.

If a string *w* contained a prefix in *L*\$, *w* and the prefix would both need to end with \$, which is not possible under our definition of *L*\$.

#### DPDAs and Ambiguous Grammars

**Theorem 6.21**: If L = L(P) for some DPDA *P*, then *L* has an unambiguous CFG. **Proof sketch, continued**:

We know by Theorem 6.20 that, L\$ has an unambiguous CFG *G*, because L\$ = N(P') for some DPDA *P'*.

However, in *G*, \$ is a terminal symbol. To fix this, define a grammar *G*' that is the same as *G* except \$ is a variable and the production  $\$ \rightarrow \varepsilon$  is included.

Now, G' is unambiguous, and L = L(G').