



Memory Management Basics

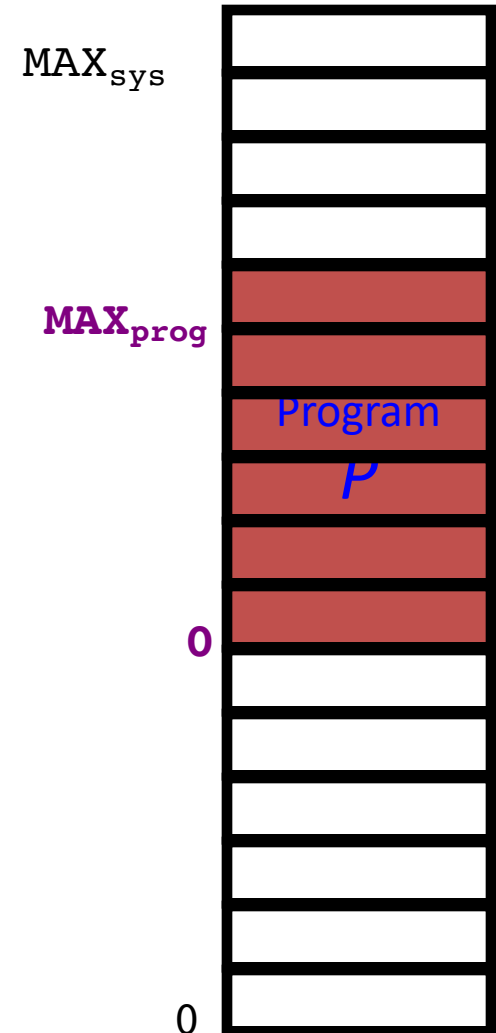
Don Porter

Portions courtesy Emmett Witchel and Kevin Jeffay



Review: Address Spaces

- *Physical address space* — The address space supported by the hardware
 - Starting at address 0, going to address $\mathbf{MAX}_{\text{sys}}$
- *Virtual address space* — A process's view of its own memory
 - Starting at address 0, going to address $\mathbf{MAX}_{\text{prog}}$



But where do addresses come from?

```
MOV r0, @0xfffa620e
```



- Which is bigger, physical or virtual address space?
 - A. Physical address space
 - B. Virtual address space
 - C. It depends on the system.

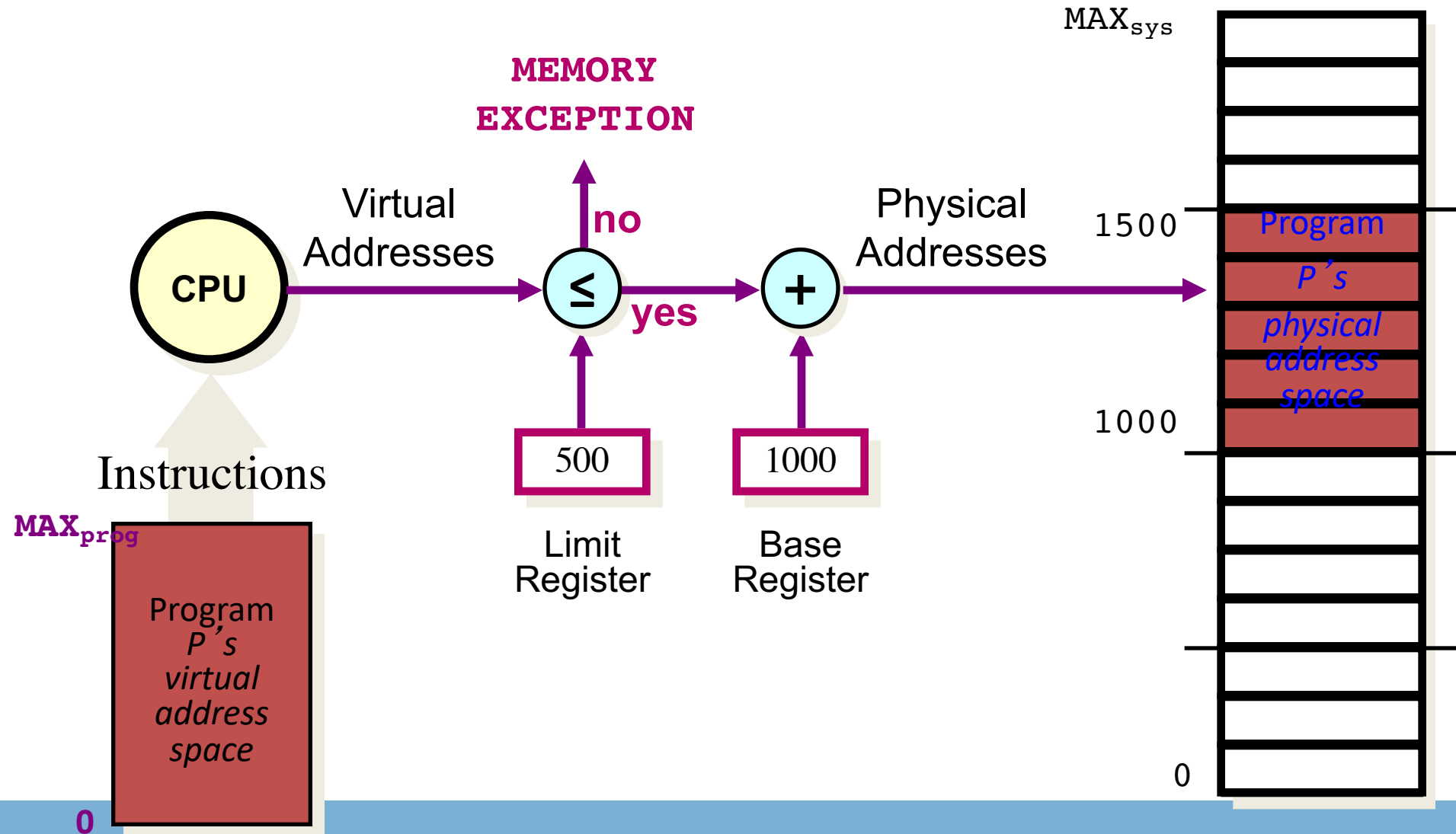


Program Relocation

- Program issues virtual addresses
- Machine has physical addresses.
- If virtual == physical, then how can we have multiple programs resident concurrently?
- Instead, relocate virtual addresses to physical at run time.
 - While we are relocating, also bounds check addresses for safety.
- I can relocate that program (safely) in two registers...



2 register translation



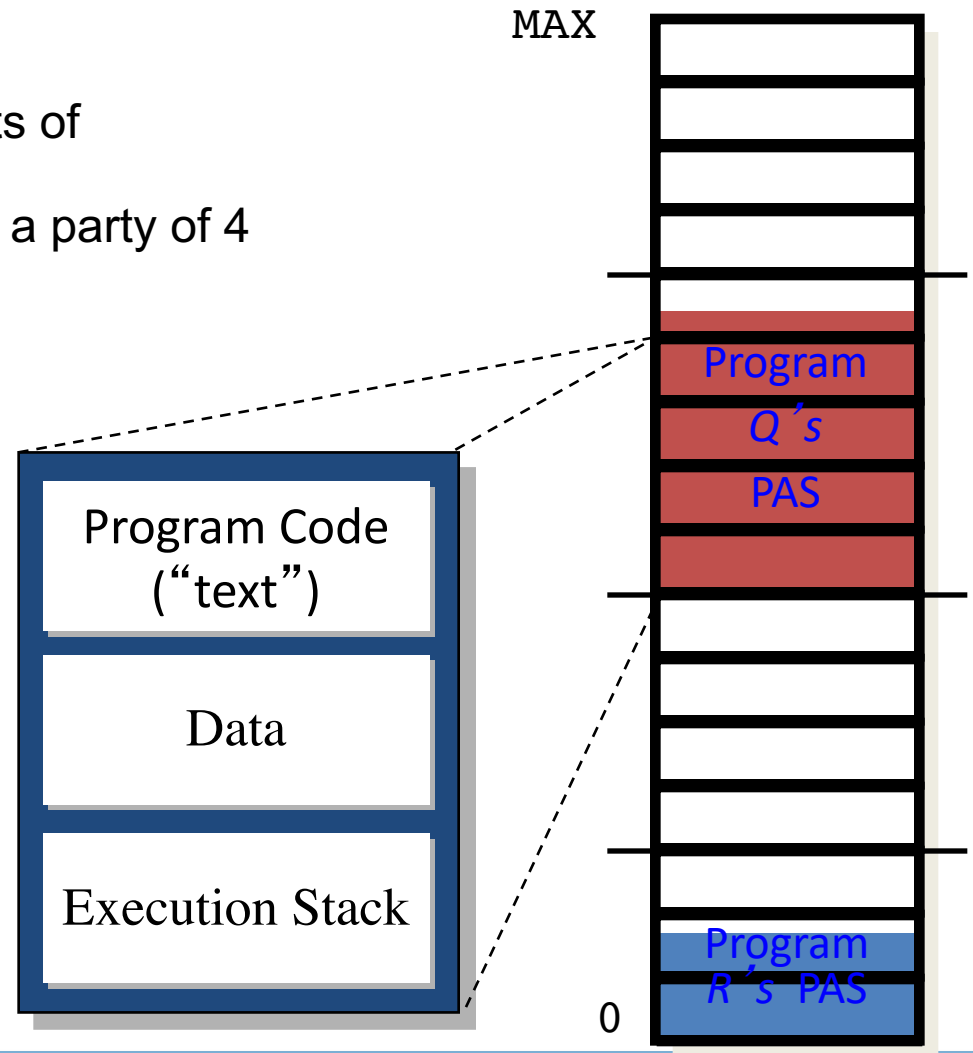


- With base and bounds registers, the OS needs a hole in physical memory at least as big as the process.
 - A. True
 - B. False



The Fragmentation Problem

- External fragmentation
 - Unused memory between units of allocation
 - E.g, two fixed tables for 2, but a party of 4
- Internal fragmentation
 - Unused memory within a unit of allocation
 - E.g., a party of 3 at a table for 4





Dynamic Allocation of Partitions

- Simple approach:
 - Allocate a partition when a process is admitted into the system
 - Allocate a contiguous memory partition to the process

OS keeps track of...

Full-blocks

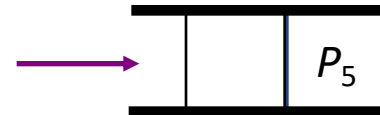
Empty-blocks (“holes”)

Allocation strategies

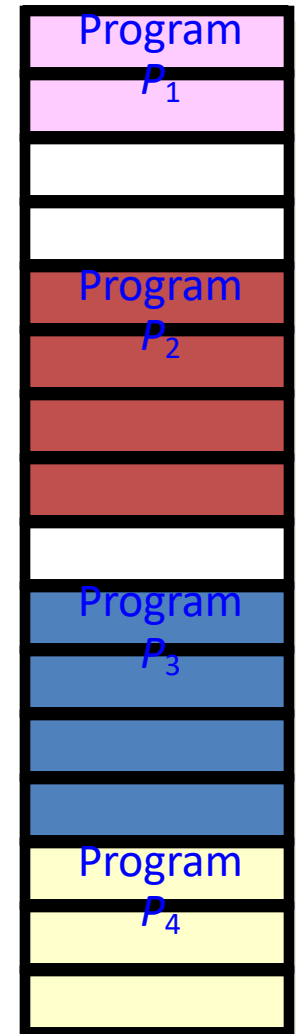
First-fit

Best-fit

Worst-fit



MAX



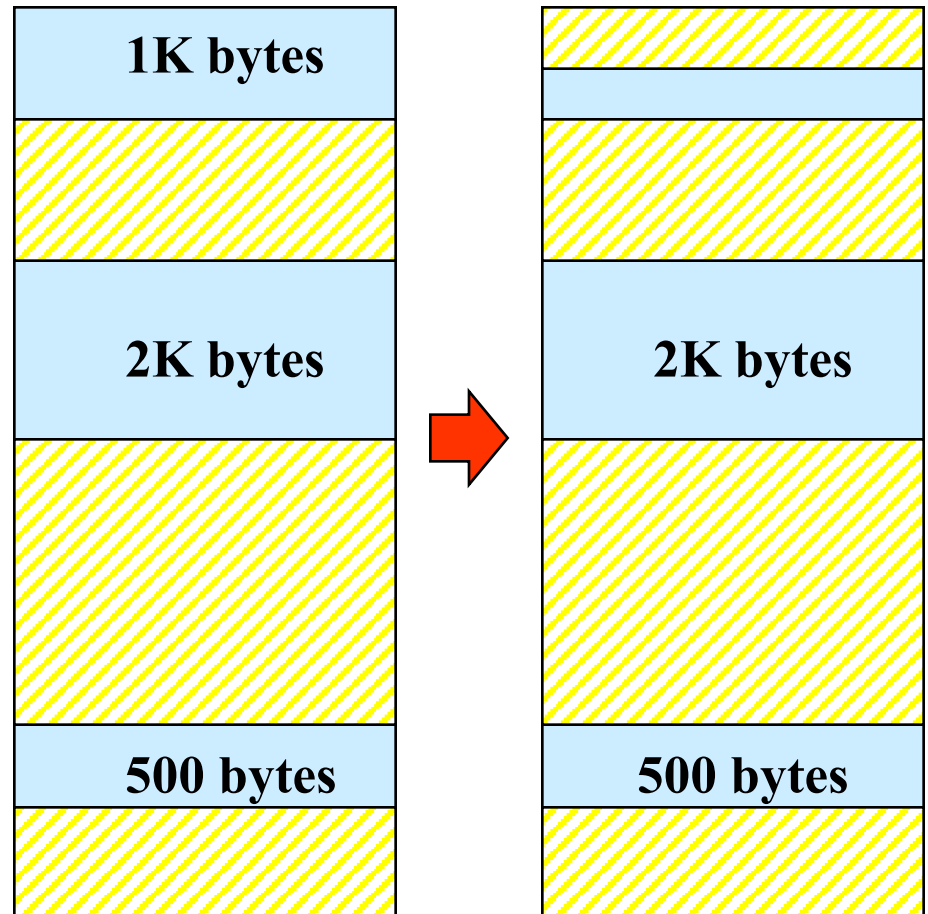
0



First Fit Allocation

To allocate n bytes, use the *first* available free block such that the block size is larger than n .

To allocate 400 bytes,
we use the 1st free block available





First Fit: Rationale and Implementation

- Simplicity!
- Requires:
 - Free block list sorted by address
 - Allocation requires a search for a suitable partition
 - De-allocation requires a check to see if the freed partition could be merged with adjacent free partitions (if any)

Advantages

- ◆ Simple
- ◆ Tends to produce larger free blocks toward the end of the address space

Disadvantages

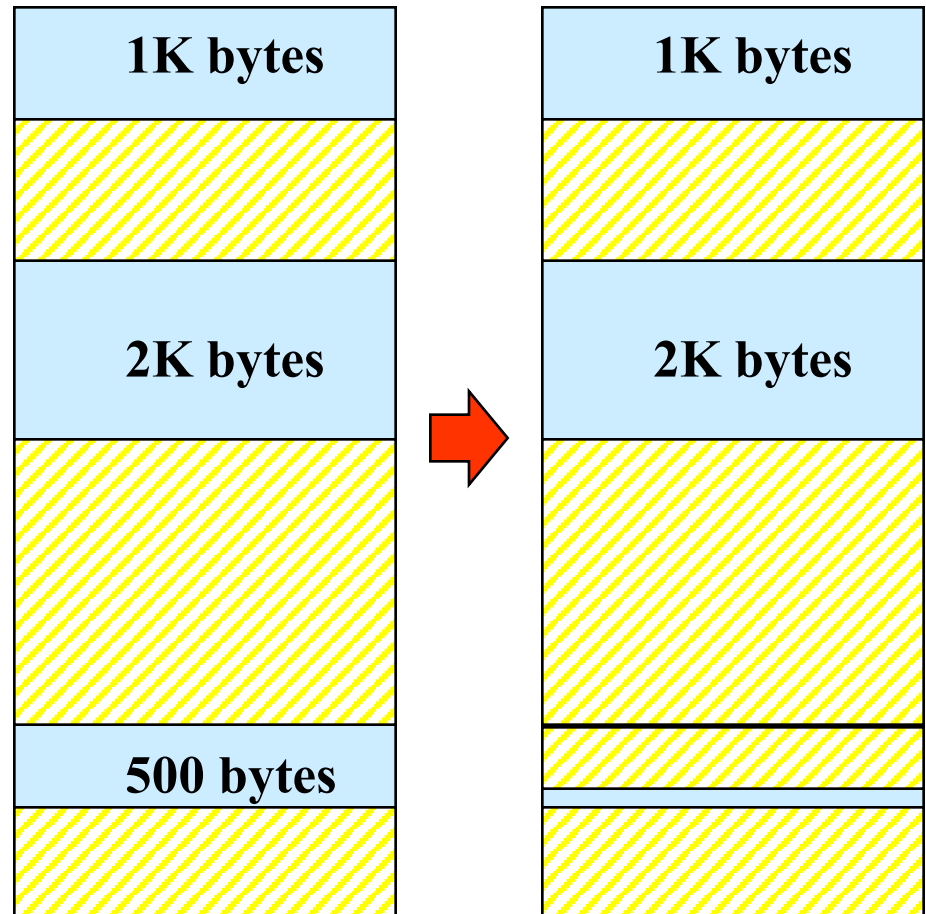
- ◆ Slow allocation
- ◆ External fragmentation



Best Fit Allocation

To allocate n bytes, use the *smallest* available free block such that the block size is larger than (or equal to) n .

To allocate 400 bytes,
we use the 3rd free block
available (smallest)





Best Fit: Rationale and Implementation

- Avoid fragmenting big free blocks
- To minimize the size of external fragments produced
- Requires:
 - Free block list sorted by size
 - Allocation requires search for a suitable partition
 - De-allocation requires search + merge with adjacent free partitions, if any

Advantages

- ◆ Works well when most allocations are of small size
- ◆ Relatively simple

Disadvantages

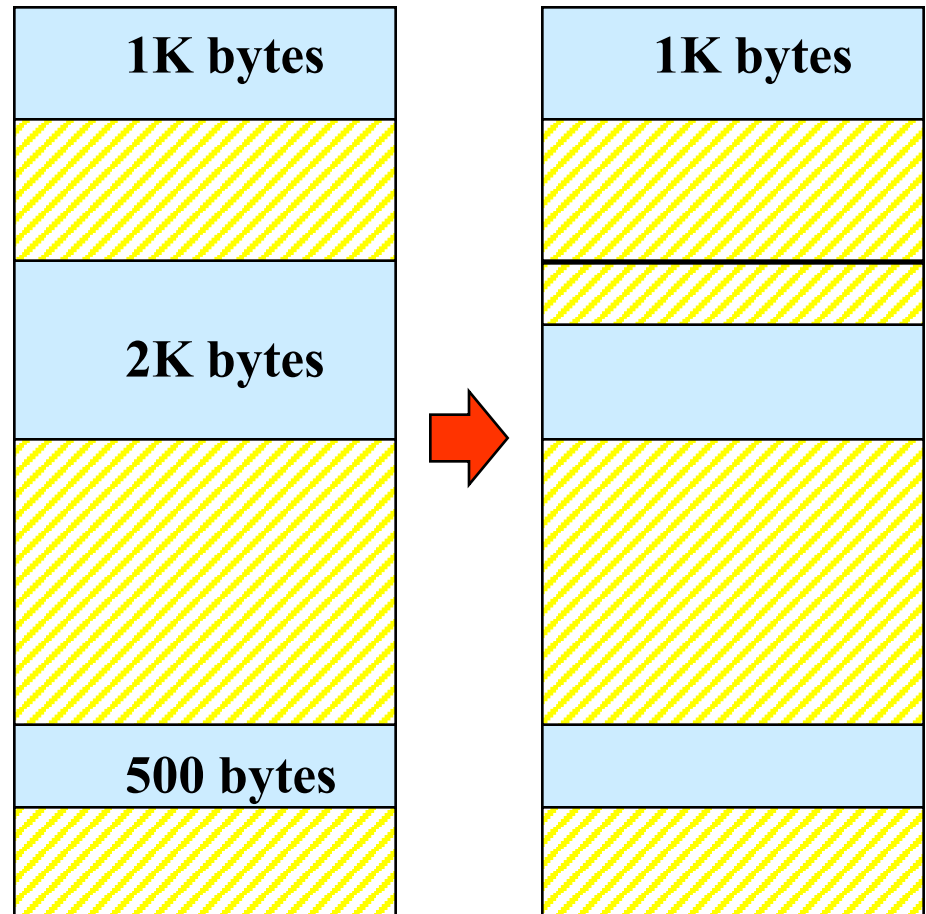
- ◆ External fragmentation
- ◆ Slow de-allocation
- ◆ Tends to produce many useless tiny fragments (not really great)



Worst Fit Allocation

To allocate n bytes, use the *largest* available free block such that the block size is larger than n .

To allocate 400 bytes,
we use the 2nd free block
available (largest)





Worst Fit: Rationale and Implementation

- Avoid having too many tiny fragments
- Requires:
 - Free block list sorted by size
 - Allocation is fast (get the largest partition)
 - De-allocation requires merge with adjacent free partitions, if any, and then adjusting the free block list

Advantages

- ◆ Works best if allocations are of medium sizes

Disadvantages

- ◆ Slow de-allocation
- ◆ External fragmentation
- ◆ Tends to break large free blocks such that large partitions cannot be allocated



Allocation strategies

- First fit, best fit and worst fit all suffer from external fragmentation.
 - A. True
 - B. False

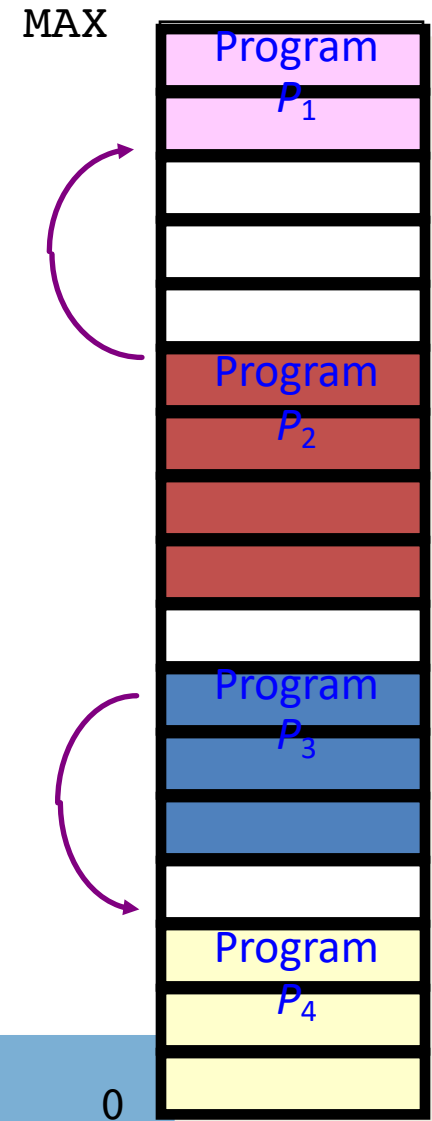
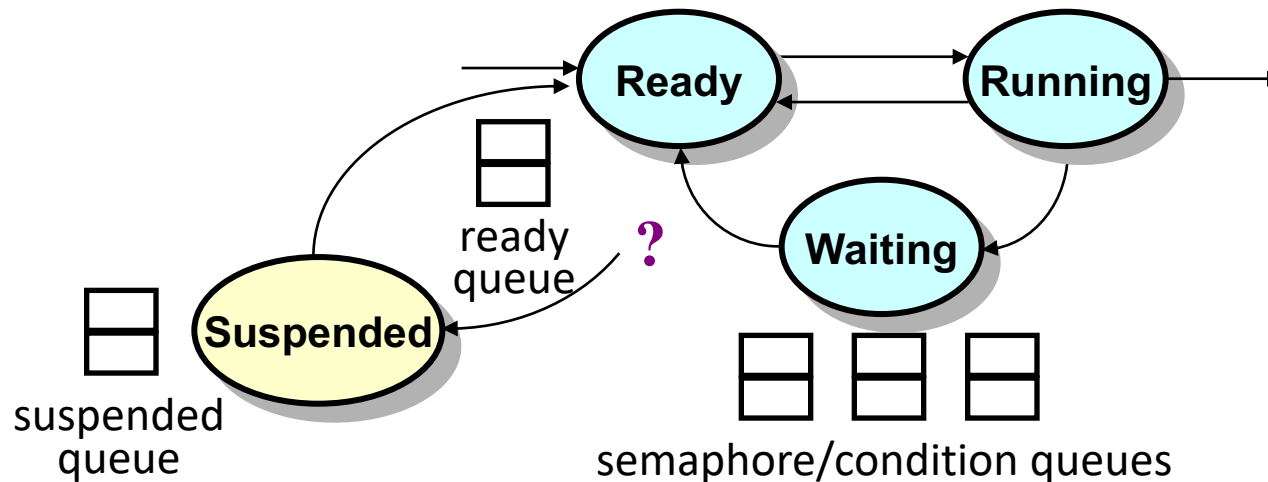


Eliminating Fragmentation

- Compaction
 - Relocate programs to coalesce holes

◆ Swapping

- Preempt processes & reclaim their memory



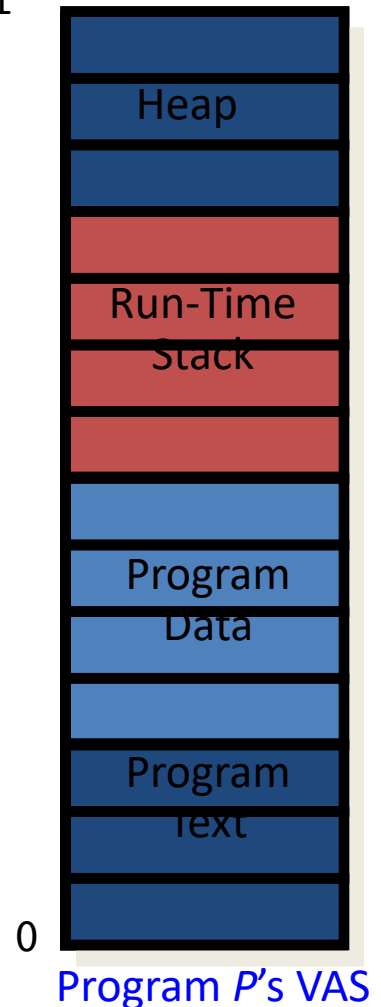


Sharing Between Processes

- Schemes so far have considered only a single address space per process
 - A single *name space* per process
 - No sharing

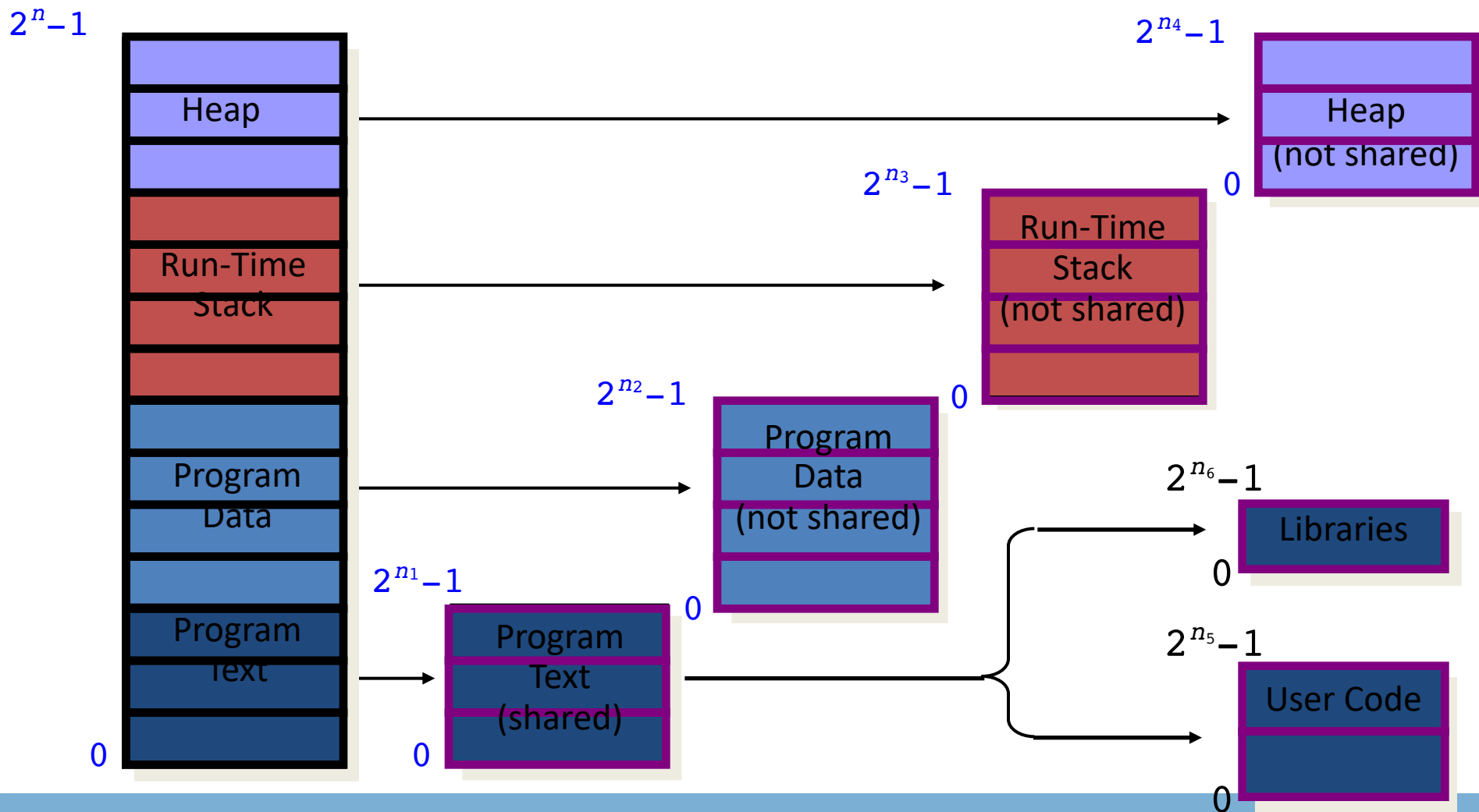
How can one share code and data between programs without paging?

$2^n - 1$





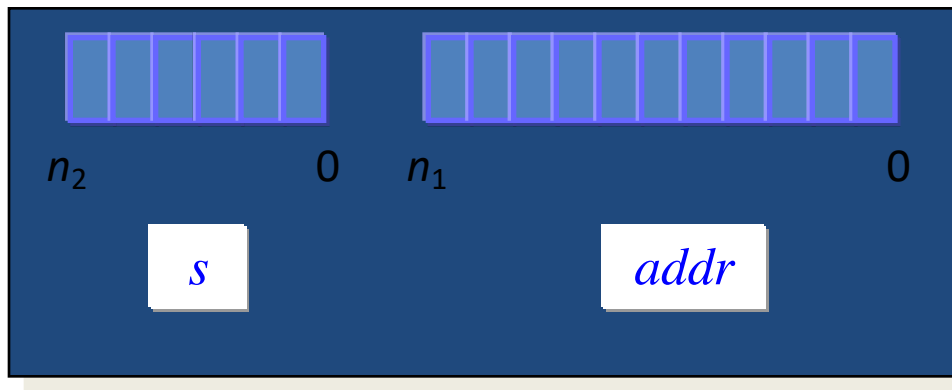
Multiple (sub) Name Spaces



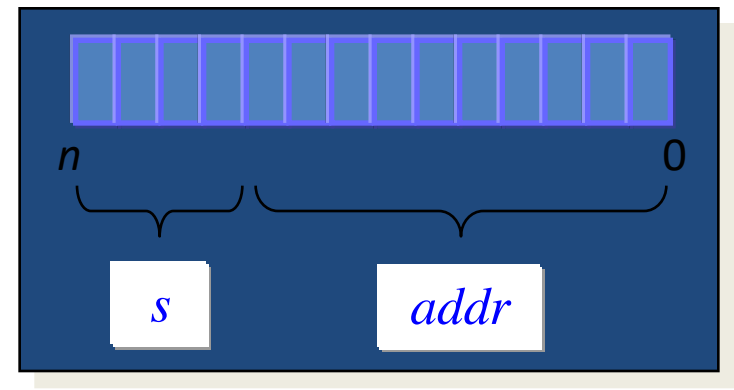


Segmentation

- New concept: A *segment* — a memory “object”
 - A virtual address space
- A process now addresses objects —a pair (s , $addr$)
 - s — segment number
 - $addr$ — an offset within an object
 - Don't know size of object, so 32 bits for offset?



Segment + Address register scheme



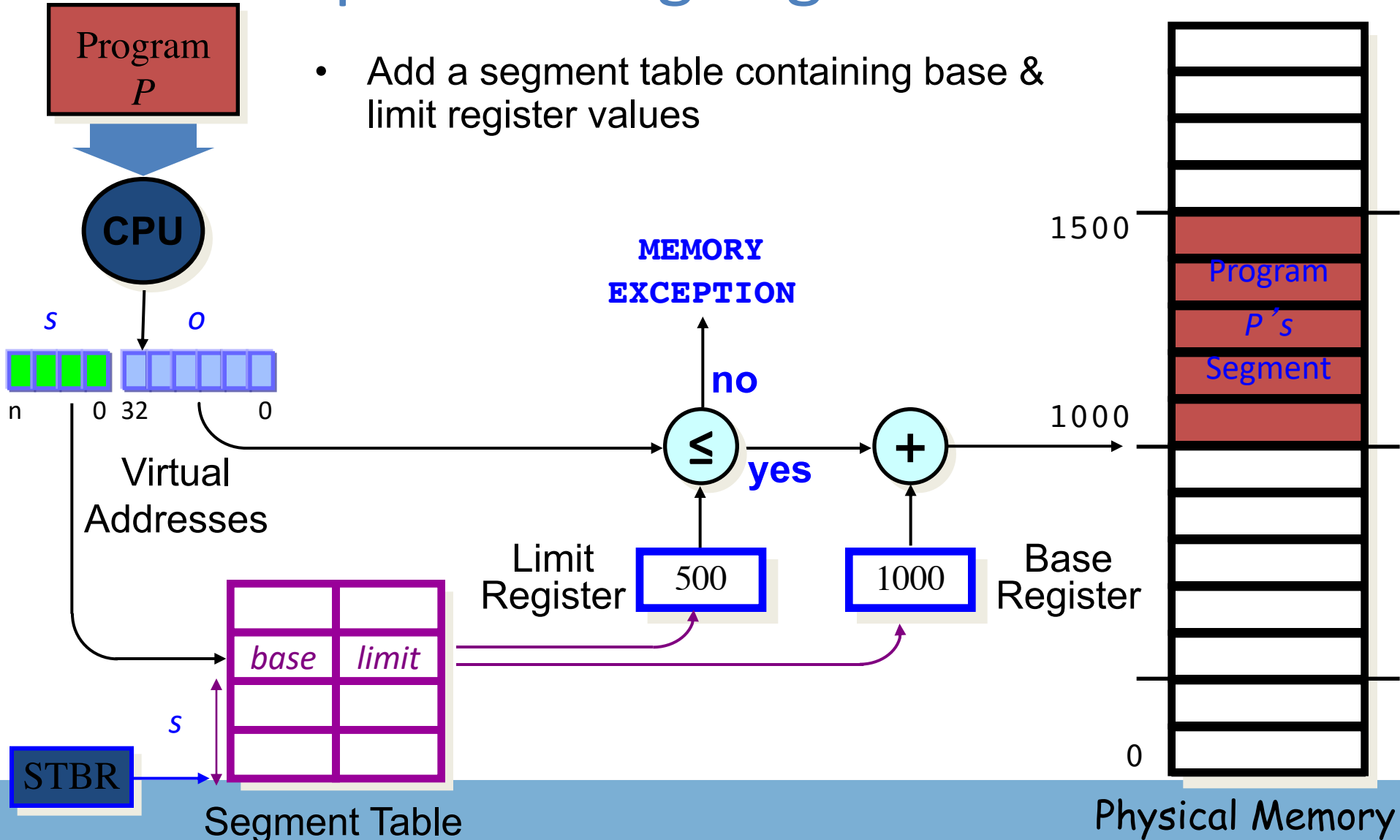
Single address scheme

Two ways to encode a virtual address



Implementing Segmentation

- Add a segment table containing base & limit register values





Are we done?

- Segmentation allows sharing
 - And dead simple hardware
 - Can easily cache all translation metadata on-chip
 - Low latency to translate virtual addresses to physical addresses
 - Two arithmetic operations (add and limit check)
- ... but leads to poor memory utilization
 - We might not use much of a large segment, but we must keep the whole thing in memory (bad memory utilization).
 - Suffers from external fragmentation
 - Allocation/deallocation of arbitrary size segments is complex
- How can we improve memory management?
 - stay tuned...