

Memory Management Basics

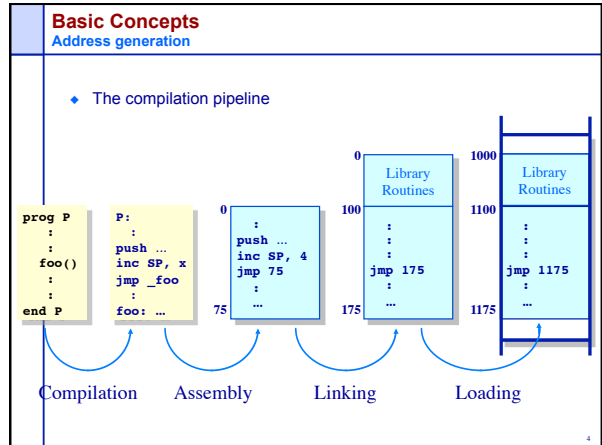
Basic Memory Management Concepts

Address spaces

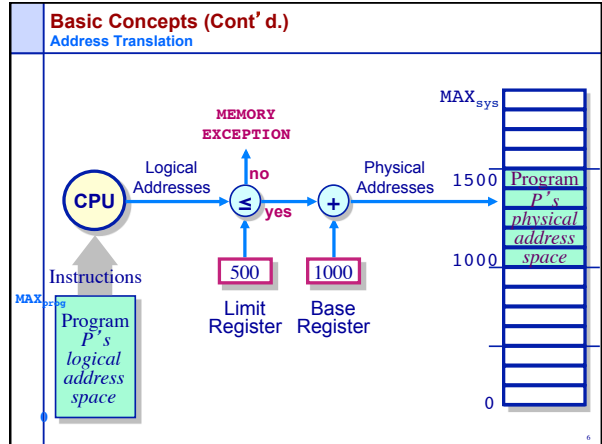
- ◆ **Physical address space** — The address space supported by the hardware
 - Starting at address 0, going to address MAX_{sys}
- ◆ **Logical/virtual address space** — A process' s view of its own memory
 - Starting at address 0, going to address MAX_{prog}

But where do addresses come from?
MOV r0, @0xfffa620e

- ◆ Which is bigger, physical or virtual address space?
 - A. Physical address space
 - B. Virtual address space
 - C. It depends on the system.



- ### Program Relocation
- ◆ Program issues virtual addresses
 - ◆ Machine has physical addresses.
 - ◆ If virtual == physical, then how can we have multiple programs resident concurrently?
 - ◆ Instead, relocate virtual addresses to physical at run time.
 - While we are relocating, also bounds check addresses for safety.
 - ◆ I can relocate that program (safely) in two registers...



- ◆ With base and bounds registers, the OS needs a hole in physical memory at least as big as the process.
 - A. True
 - B. False

Evaluating Dynamic Allocation Techniques

The fragmentation problem

- ◆ External fragmentation
 - Unused memory between units of allocation
 - E.g. two fixed tables for 2, but a party of 4
- ◆ Internal fragmentation
 - Unused memory within a unit of allocation
 - E.g., a party of 3 at a table for 4

Simple Memory Management Schemes

Dynamic allocation of partitions

- ◆ Simple approach:
 - Allocate a partition when a process is admitted into the system
 - Allocate a contiguous memory partition to the process

OS keeps track of...
 Full-blocks
 Empty-blocks ("holes")

Allocation strategies
 First-fit
 Best-fit
 Worst-fit

First Fit Allocation

To allocate n bytes, use the first available free block such that the block size is larger than n .

To allocate 400 bytes, we use the 1st free block available

Rationale & Implementation

- ◆ Simplicity of implementation
- ◆ Requires:
 - Free block list sorted by address
 - Allocation requires a search for a suitable partition
 - De-allocation requires a check to see if the freed partition could be merged with adjacent free partitions (if any)

<p>Advantages</p> <ul style="list-style-type: none"> ◆ Simple ◆ Tends to produce larger free blocks toward the end of the address space 	<p>Disadvantages</p> <ul style="list-style-type: none"> ◆ Slow allocation ◆ External fragmentation
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Best Fit Allocation

To allocate n bytes, use the smallest available free block such that the block size is larger than n .

To allocate 400 bytes, we use the 3rd free block available (smallest)

Rationale & Implementation

- ◆ To avoid fragmenting big free blocks
- ◆ To minimize the size of external fragments produced
- ◆ Requires:
 - Free block list sorted by size
 - Allocation requires search for a suitable partition
 - De-allocation requires search + merge with adjacent free partitions, if any

<p>Advantages</p> <ul style="list-style-type: none"> ◆ Works well when most allocations are of small size ◆ Relatively simple ◆ Doug Lea's malloc "In most ways this malloc is a best-fit allocator" 	<p>Disadvantages</p> <ul style="list-style-type: none"> ◆ External fragmentation ◆ Slow de-allocation ◆ Tends to produce many useless tiny fragments (not really great)
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Worst Fit Allocation

To allocate n bytes, use the *largest* available free block such that the block size is larger than n .

To allocate 400 bytes, we use the 2nd free block available (largest)

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Rationale & Implementation

- ◆ To avoid having too many tiny fragments
- ◆ Requires:
 - Free block list sorted by size
 - Allocation is fast (get the largest partition)
 - De-allocation requires merge with adjacent free partitions, if any, and then adjusting the free block list

<p>Advantages</p> <ul style="list-style-type: none"> ◆ Works best if allocations are of medium sizes 	<p>Disadvantages</p> <ul style="list-style-type: none"> ◆ Slow de-allocation ◆ External fragmentation ◆ Tends to break large free blocks such that large partitions cannot be allocated
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Allocation strategies

- ◆ First fit, best fit and worst fit all suffer from external fragmentation.
 - A. True
 - B. False

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Dynamic Allocation of Partitions

Eliminating Fragmentation

- ◆ Compaction
 - Relocate programs to coalesce holes
- ◆ Swapping
 - Preempt processes & reclaim their memory

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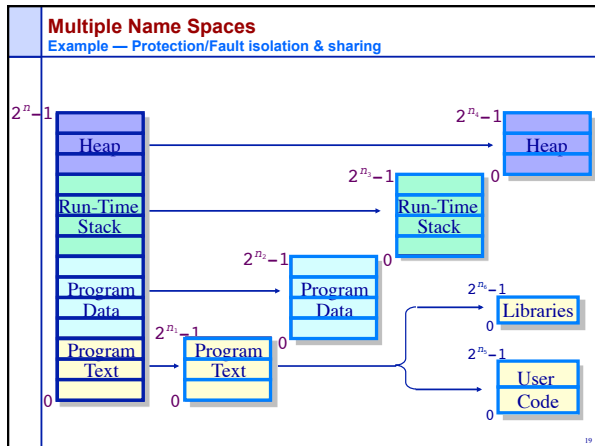
Memory Management

Sharing Between Processes

- ◆ Schemes so far have considered only a single address space per process
 - A single *name space* per process
 - No sharing

How can one share code and data between programs without paging?

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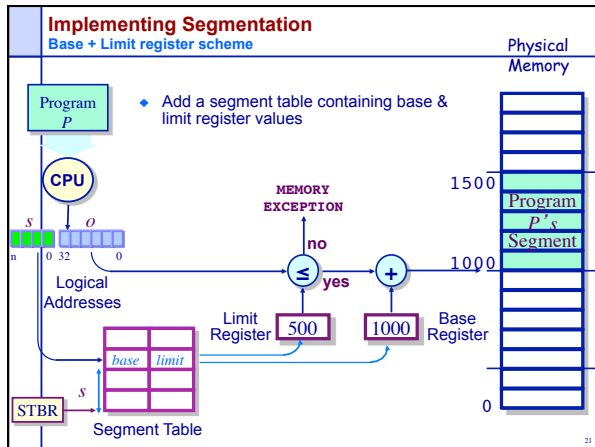


Supporting Multiple Name Spaces

Segmentation

- ◆ New concept: A *segment* — a memory “object”
 - A virtual address space
- ◆ A process now addresses objects — a pair $(s, addr)$
 - s — segment number
 - $addr$ — an offset within an object
 - ◆ Don't know size of object, so 32 bits for offset?

Segment + Address register scheme
Single address scheme



Memory Management Basics

Are We Done?

- ◆ Segmentation allows sharing
- ◆ ... but leads to poor memory utilization
 - We might not use much of a large segment, but we must keep the whole thing in memory (bad memory utilization).
 - Suffers from external fragmentation
 - Allocation/deallocation of arbitrary size segments is complex
- ◆ How can we improve memory management?
 - Paging