



# COMP768 Final Project

## Cloth Simulation & Video-based Cloth Parameter Estimation

Zhen Wei



THE UNIVERSITY  
of NORTH CAROLINA  
at CHAPEL HILL

# Motivation

- Cloth Simulation

- ▶ Movie
- ▶ Games
- ▶ VR scene
- ▶ Virtual Try-on



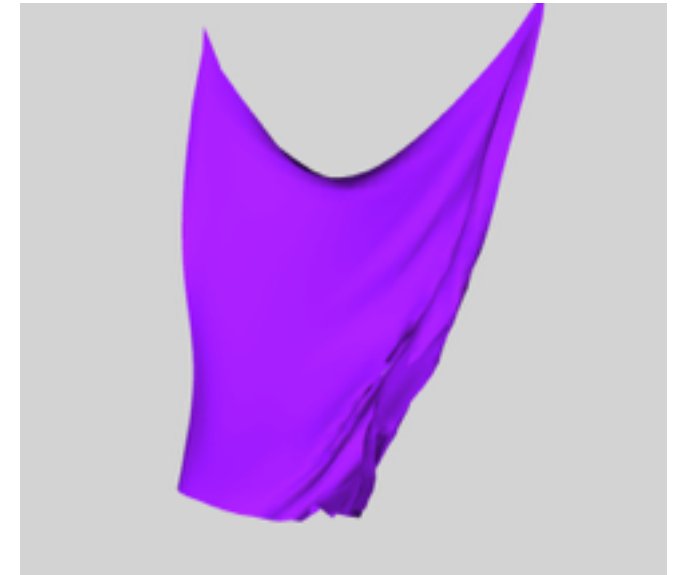
- Cloth Parameter Estimation

- ▶ Good parameters can produce very realist appearance
- ▶ Choosing parameters are time-consuming



# Outline

- Cloth Simulation
  - Position Based Method Implementation
  - Stretching, Bending, Self-collision, Damping
- Video-based Cloth Parameter Estimation
  - Machine-Learning-Based Cloth Material Retrieval in Real-Life Videos
    - Design a small network to learn motion feature and use a simple classifier using synthetic data
    - Collect real-life video data
      - Preprocessing and use optical flow algorithm to get flow feature
  - Extension: Garment Movement with Human Motion
    - Get synthetic dataset



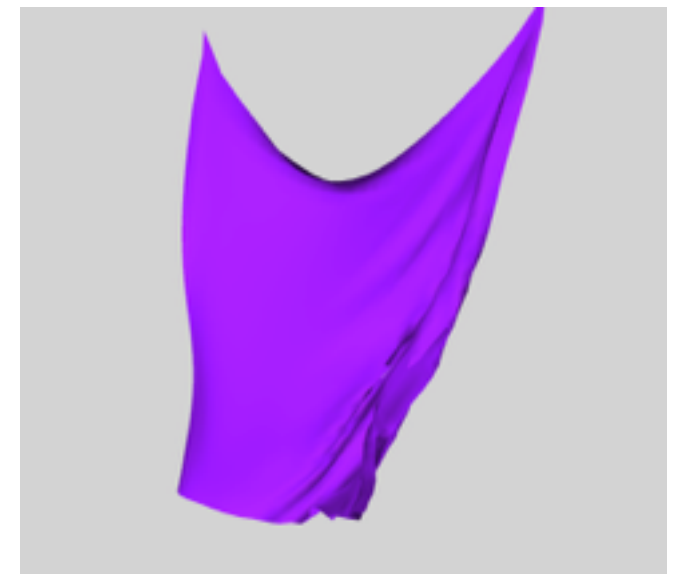
# Outline

- **Cloth Simulation**

- Position Based Method Implementation
- Stretching, Bending, Self-collision, Damping

- Video-based Cloth Parameter Estimation

- Machine-Learning-Based Cloth Material Retrieval in Real-Life Videos
  - Design a small network to learn motion feature and use a simple classifier using synthetic data
  - Collect real-life video data
    - Preprocessing and use optical flow algorithm to get flow feature
- Extension: Garment Movement with Human Motion
  - Get synthetic dataset





# Cloth Simulation

- Force Based Methods
  - Internal and external forces are accumulated, Newton's second law
  - Employ a time integration method, update velocities and finally positions
- Impulse Based Methods
  - Directly manipulate velocities, one layer of integration can be skipped
- Position Based Methods
  - Omit the velocity layer as well and immediately works on the positions
  - Define general constraints via a constraint function
  - Directly solve for the equilibrium configuration and project positions



# Cloth Simulation

## ● Recall Position Based Method

- ▶ A vertex  $i \in [1, \dots, N]$
- ▶ mass  $m_i$ ,
- ▶ a position  $\mathbf{x}_i$
- ▶ a velocity  $\mathbf{v}_i$ .
- ▶ Constraint  $C_j$

Based on this data and a time step  $\Delta t$ , the dynamic object is simulated as follows:

```
(1) forall vertices  $i$ 
(2)   initialize  $\mathbf{x}_i = \mathbf{x}_i^0, \mathbf{v}_i = \mathbf{v}_i^0, w_i = 1/m_i$ 
(3) endfor
(4) loop
(5)   forall vertices  $i$  do  $\mathbf{v}_i \leftarrow \mathbf{v}_i + \Delta t w_i \mathbf{f}_{ext}(\mathbf{x}_i)$ 
(6)   dampVelocities( $\mathbf{v}_1, \dots, \mathbf{v}_N$ )
(7)   forall vertices  $i$  do  $\mathbf{p}_i \leftarrow \mathbf{x}_i + \Delta t \mathbf{v}_i$ 
(8)   forall vertices  $i$  do generateCollisionConstraints( $\mathbf{x}_i \rightarrow \mathbf{p}_i$ )
(9)   loop solverIterations times
(10)    projectConstraints( $C_1, \dots, C_{M+M_{coll}}, \mathbf{p}_1, \dots, \mathbf{p}_N$ )
(11)  endloop
(12)  forall vertices  $i$ 
(13)     $\mathbf{v}_i \leftarrow (\mathbf{p}_i - \mathbf{x}_i) / \Delta t$ 
(14)     $\mathbf{x}_i \leftarrow \mathbf{p}_i$ 
(15)  endfor
(16)  velocityUpdate( $\mathbf{v}_1, \dots, \mathbf{v}_N$ )
(17) endloop
```



# Cloth Simulation

- Recall Position Based Method
  - ▶ Stretching Constraints
  - ▶ Bending Constraints
  - ▶ Self Collision Handling

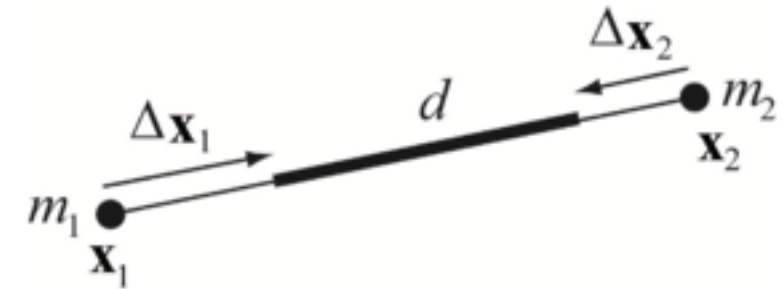


Figure: Stretching [Bender 15]

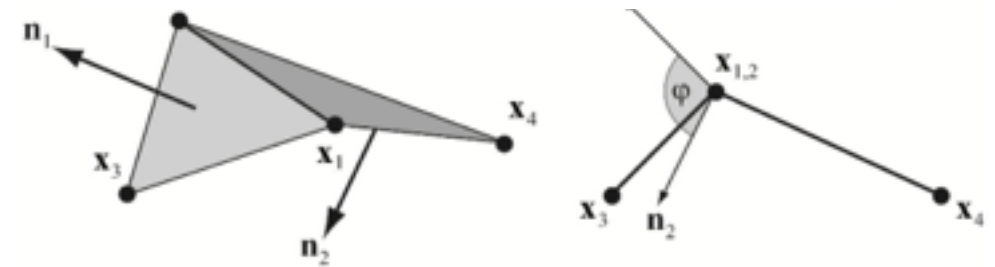


Figure: Bending [Bender 15]

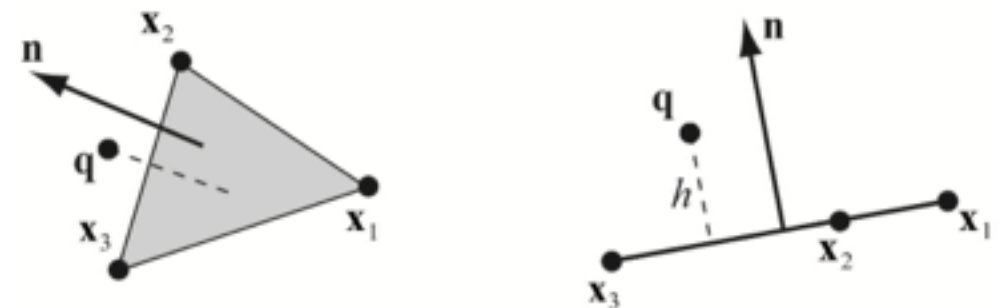


Figure: Collision [Bender 15]



# Cloth Simulation

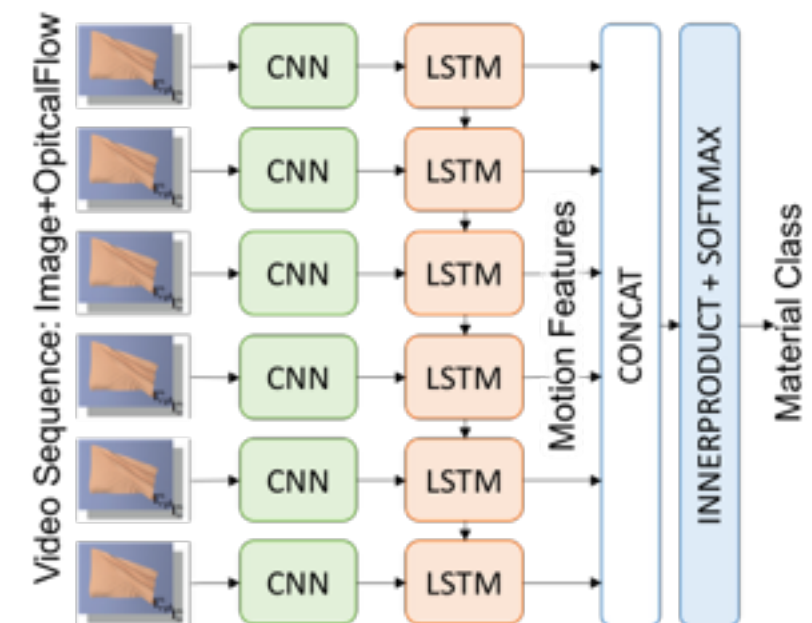
- Position Based Method
  - ▶ Stretching Constraints
  - ▶ Bending Constraints
  - ▶ Self Collision Detection
  - ▶ Damping
- Other: GUI
  - ▶ Drag a point of the cloth





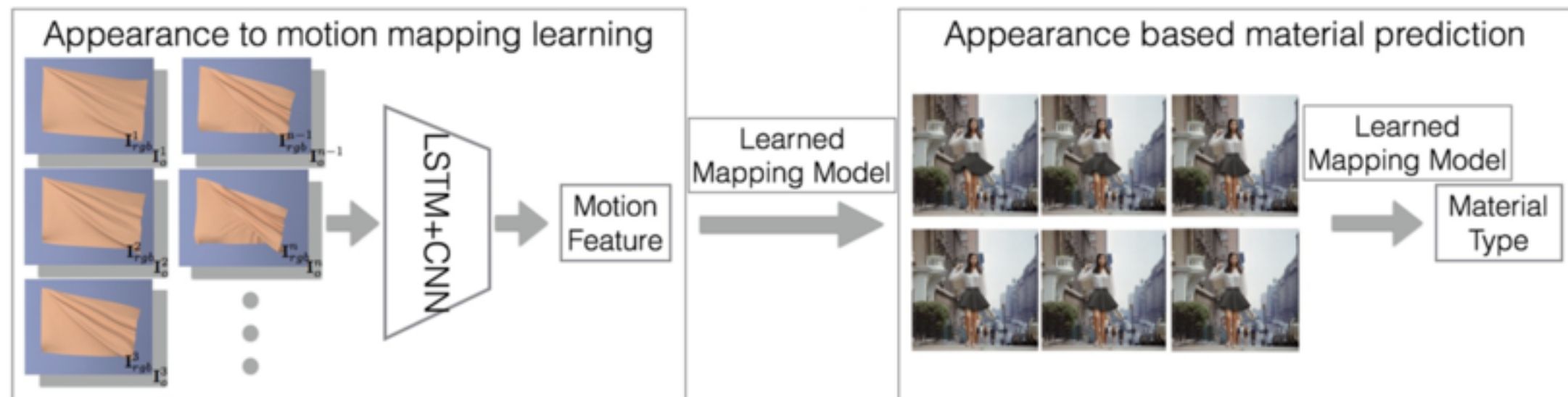
# Outline

- Cloth Simulation
  - Position Based Method Implementation
  - Stretching, Bending, Self-collision, Damping
- **Video-based Cloth Parameter Estimation**
  - Machine-Learning-Based Cloth Material Retrieval in Real-Life Videos
    - Design a small network to learn motion feature and use a simple classifier using synthetic data
    - Collect real-life video data
      - Preprocessing and use optical flow algorithm to get flow feature
    - Extension: Garment Movement with Human Motion
      - Get synthetic dataset



# Video-based Cloth Parameter Estimation

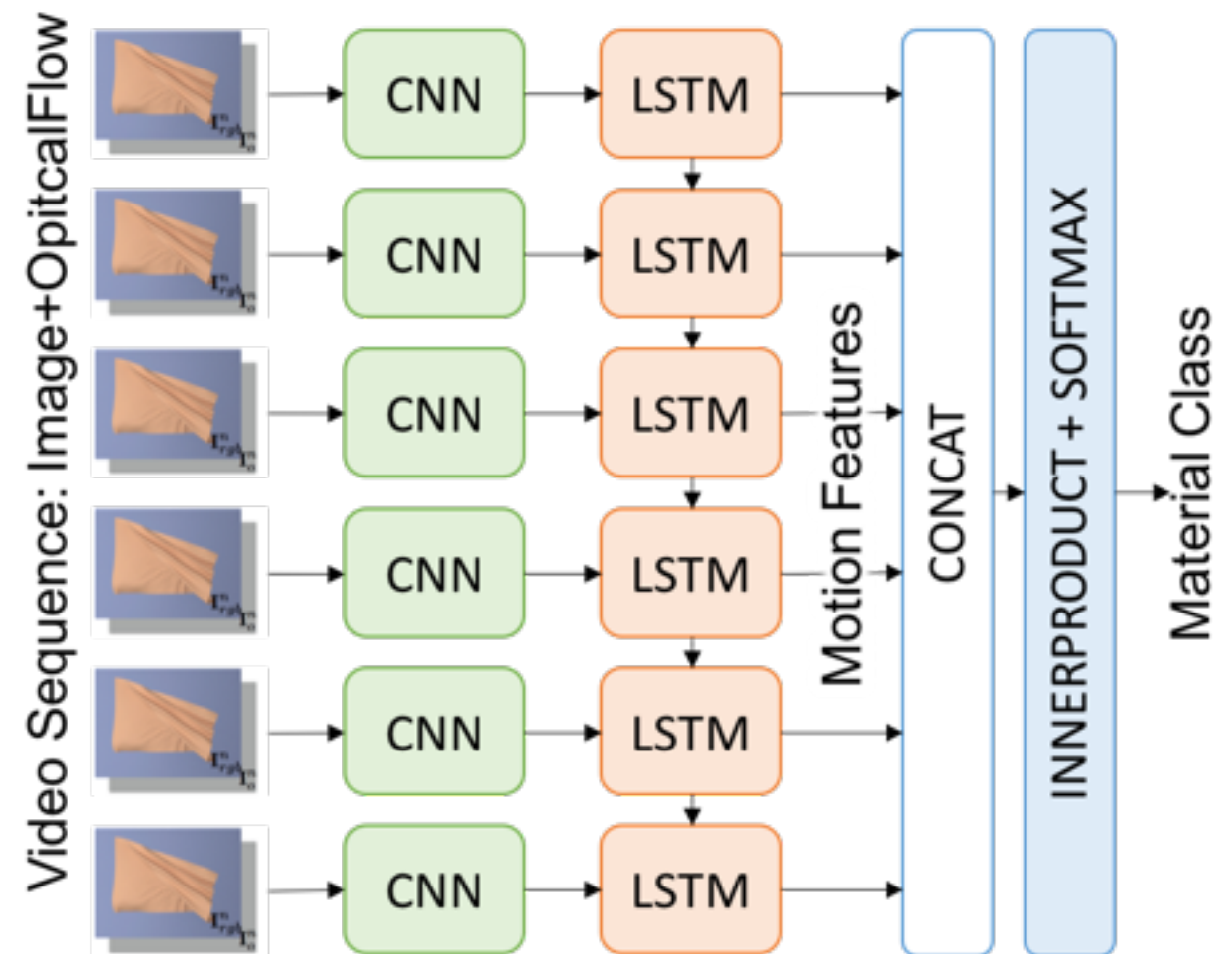
- Machine-Learning-Based Cloth Material Retrieval in Real-Life Videos:



# Video-based Cloth Parameter Estimation

- Machine-Learning-Based Cloth Material Retrieval in Real-Life Videos:

- Design a small network to get motion feature and use simple the classifier to get material class
- Toy dataset: synthetic data
  - Train: ~10k sequences
  - Test: ~1k sequences
- Result:
  - Accuracy:
    - ~2% higher than random
- Analysis and modification:
  - use trained model to finetune
  - more data & longer sequence
  - More meaningful classifier



# Outline

- Cloth Simulation
  - Position Based Method Implementation
  - Stretching, Bending, Self-collision, Damping
- **Video-based Cloth Parameter Estimation**
  - Machine-Learning-Based Cloth Material Retrieval in Real-Life Videos
    - Design a small network to learn motion feature and use a simple classifier using synthetic data
    - [Collect real-life video data](#)
      - Preprocessing and use optical flow algorithm to get flow feature
  - Extension: Garment Movement with Human Motion
    - Get synthetic dataset





# Video-based Cloth Parameter Estimation

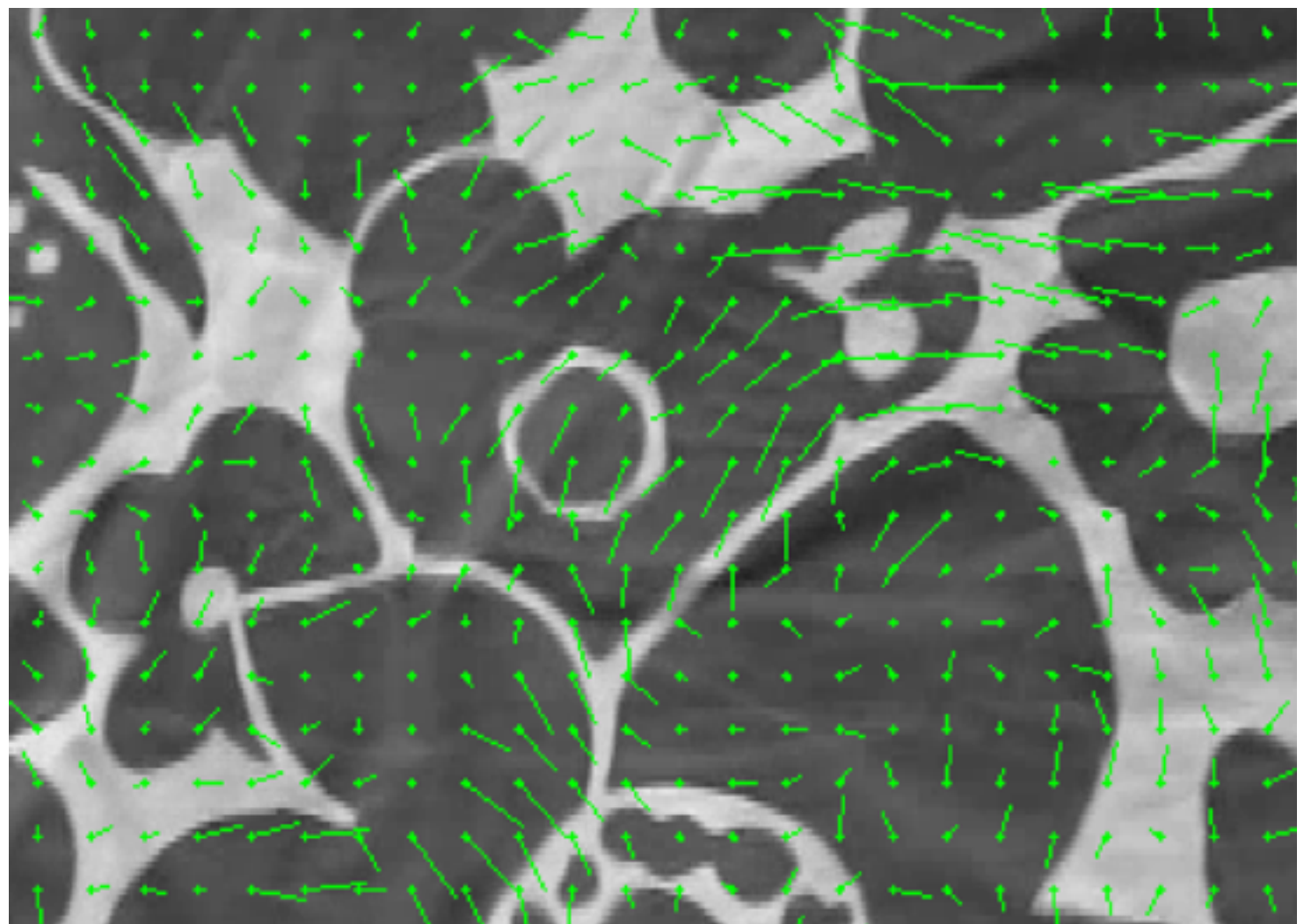
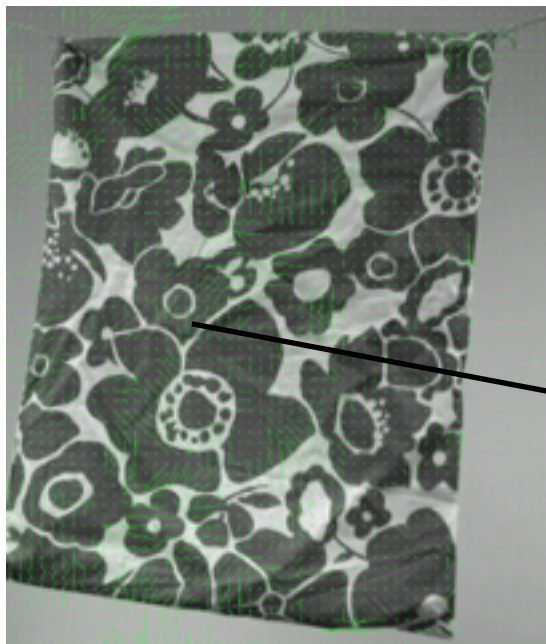
- Machine-Learning-Based Cloth Material Retrieval in Real-Life Videos:
  - ▶ Collect real-life cloth moving videos.





# Video-based Cloth Parameter Estimation

- Machine-Learning-Based Cloth Material Retrieval in Real-Life Videos:
  - optical flow algorithm for generating features of real-life videos



# Outline

- Cloth Simulation
  - Position Based Method Implementation
  - Stretching, Bending, Self-collision, Damping
- **Video-based Cloth Parameter Estimation**
  - Machine-Learning-Based Cloth Material Retrieval in Real-Life Videos
    - Design a small network to learn motion feature and use a simple classifier using synthetic data
    - Collect real-life video data
      - Preprocessing and use optical flow algorithm to get flow feature
  - Extension: Garment Movement with Human Motion
    - Get synthetic dataset



# Video-based Cloth Parameter Estimation

- ◉ Extension:  
Garment movement
  - ▶ not only considering material
  - ▶ Cloth movement vs. Garment movement
  - ▶ Human motion





# Video-based Cloth Parameter Estimation

- Extension: Garment movement:
  - Data Collection
  - Generate synthetic dataset for garment movement
    - ArcSim
    - Blender
    - Make human



# Milestone Comparison & Future Work

- Machine-Learning-Based Cloth Material Retrieval in Real-Life Videos:
  - Oct.: Collect real-life cloth moving videos.
  - Oct.: Write an optical flow algorithm for generating features of real-life videos
  - ~~Oct.: Run testing on the real-life videos~~
- Extension: Garment movement:
  - Nov.: Generate synthetic dataset for garment movement
  - Nov.-Dec.: Do clustering ~~on the motion subspace for the garment movement~~
  - ~~Dec.: Testing and Comparison~~



- Design and train a small network
- Cloth Simulation
  - Position Based Method Implementation





# Thank you.



THE UNIVERSITY  
*of* NORTH CAROLINA  
*at* CHAPEL HILL